SystemTest™ 2 User's Guide

MATLAB[®] SIMULINK[®]



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SystemTest[™] User's Guide

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Getting Started

This section explains what the SystemTestTM software is and shows you how to use it. It contains the following topics:

- "Product Overview" on page 1-2
- "Quick Tour of the SystemTest Software" on page 1-3
- "Running Tests from the MATLAB Command Line" on page 1-10
- "Example: Building a Test" on page 1-11

Product Overview

The SystemTest software provides MATLAB[®] and Simulink[®] users with a framework that integrates software, hardware, simulation, and other types of testing in one environment. You use predefined elements to build test sections that simplify the development and maintenance of standard test routines. You can save and share tests throughout a development project to ensure standard and repeatable test verification. The SystemTest software offers integrated data management and analysis capabilities for creating and executing tests, and saving test results to facilitate continuous testing across the development process.

The SystemTest software automates testing in MATLAB and Simulink products. With the SystemTest software you get:

- Graphical test editing Quickly edit your test within a graphical test development environment.
- Repeatable test execution All tests developed with the SystemTest software share the same execution flow, which provides a consistent test framework among tests.
- Parameterized testing Create test vectors over which your test iterates.
- Reusability After you design a test, you can save it for later use by you or others.
- Maintainability Because you design and execute tests from the SystemTest desktop, you do not need to understand unfamiliar code or concepts.
- Integration The SystemTest software integrates with MATLAB, Simulink, and other products based on MATLAB and Simulink.

Quick Tour of the SystemTest Software

In this section ...

"Getting Familiar with the Desktop" on page 1-3

"General Desktop Features" on page 1-5

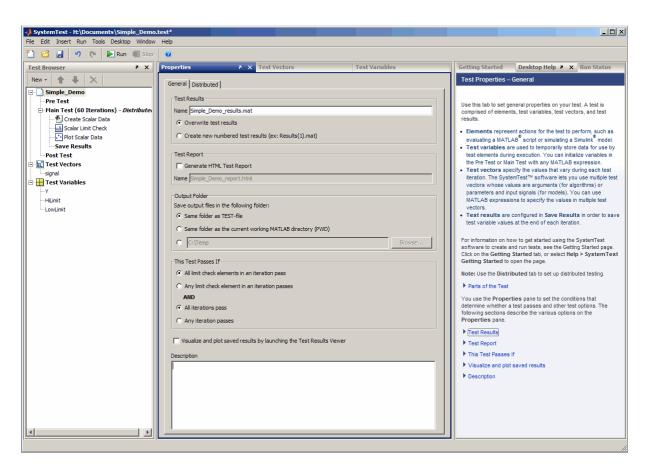
"Setting SystemTest Preferences" on page 1-7

"Viewing Test Results" on page 1-9

Getting Familiar with the Desktop

The SystemTest desktop is an integrated development environment that lets you perform all of your testing activities from one centralized location. This section provides an overview of the SystemTest environment. For more information about how to use the SystemTest software to build tests and run them, see "Example: Building a Test" on page 1-11.

To get familiar with the SystemTest environment, open the SystemTest desktop from MATLAB by selecting **Start > MATLAB > SystemTest > SystemTest Desktop** or typing **systemtest** at the MATLAB command line.



The desktop has a number of different panes that help you to build and run your test.

- **Test Browser** Shows the overall structure of a test. A test is made up of Pre Test, Main Test, Save Results, and Post Test. Use the Test Browser to add elements to your test. These elements determine what actions your test performs.
- **Test Vectors** Lets you define the parameters or test cases of your test. The test vectors you define determine the number of iterations performed by your test. Test vectors are automatically indexed during test execution.

- **Test Variables** Lets you define variables used in the scope of your test. Variables can serve both input and output functions in your test. You can define variables that are declared in the Pre Test section of your test or in the Main Test section of your test.
- **Properties** Shows the properties of the test or the element you are editing. The contents of this pane change when you select a section or element in your test.
- Elements If open, this undocked Elements pane allows you to add elements to your test. If not open, you can add elements using the New button in the Test Browser.
- **Resources** Lists the instrument or other external device resources associated with the current test. This is only used if you have a license for the Instrument Control Toolbox[™] software.
- Getting Started Shows information to help you start using the SystemTest software. If the Getting Started page is closed, select Help > SystemTest Getting Started to open it.
- **Desktop Help** Shows help about the element or aspect of the test that is currently selected. For the full product Help, select **Help > SystemTest User's Guide**.
- Run Status Shows a summary of the test's execution status.

General Desktop Features

The SystemTest desktop has a variety of features to make navigation easier.

Context Menus

Many areas of the user interface have context menus. For example, if you right-click in the **Test Vectors**, **Test Variables**, **Resources**, **Run Status**, **Getting Started**, or **Desktop Help** panes, you can access these context menus.

If you have the **Elements** pane open, you can add elements to your test using the context menus. If you right-click any element there, you can insert it directly into Pre Test, Main Test, or Post Test using the **Elements** pane context menus. If that section of the test already contains elements, the inserted element will be placed below the currently selected element in that section. You can change the order of elements in the test by using the arrow buttons in the **Test Browser**, or by dragging and dropping.

Hot Keys

The SystemTest software offers various keyboard shortcuts, or hot keys, to access certain commands via the keyboard. For example, pressing **F5** is an alternative way to run a test, and pressing **Ctrl+N** creates a new untitled test.

See the full list of SystemTest hot keys in Appendix A, "SystemTest Hot Keys".

Undo/Redo Support

Undo and redo support is available through the **Edit** menu or on the SystemTest toolbar. This feature allows you to undo actions you have done throughout the desktop. The undo queue is global to the entire desktop. For example, if you add a test vector and then perform an action in the Properties pane, those two actions will be the last two items in the queue. The undo order applies across all the panes in the desktop.

To use this feature, select the **Edit** > **Undo** *action* command, where *action* is the last action you performed. Use the **Undo** command repeatedly to undo multiple actions. The **Edit** > **Redo** *action* command will redo the last undo you performed.

Most actions in the desktop are undoable. Some actions pertaining to the elements that are part of the hardware toolboxes, Data Acquisition Toolbox[™], Instrument Control Toolbox, and Image Acquisition Toolbox[™], cannot be undone since they involve connections to hardware.

The following actions will clear the list of actions in the undo queue:

- Closing a test
- Opening a test
- Creating a new test
- Refreshing a Simulink model in the Simulink element

Setting SystemTest Preferences

You can set SystemTest preferences by selecting **File > Preferences** on the SystemTest desktop. This opens the MATLAB Preferences dialog box. Click **SystemTest** in the left tree if SystemTest Preferences are not showing in the right pane.

📣 Preferences		<u> </u>
 General MAT-Files Confirmation Dialogs Source Control Fonts Colors Command Window Command History Editor/Debugger Help Web Current Directory Array Editor GUIDE Time Series Tools Figure Copy Template Report Generator SystemTest Instrument Control Virtual Reality Simulink 	SystemTest Preferences Most Recently Used Test List Number of entries: 4 == Test Run Options Minimize SystemTest when starting a test Save test before running	
	OK Cancel Apply	Help

Most Recently Used Test List

This option determines how many tests will appear on the SystemTest **File** menu's most recent files list. The default is 4 tests. If you change it to 0, no recent tests will appear on the list. The maximum number is 9.

Test Run Options

Select **Minimize SystemTest when starting a test** if you want the SystemTest desktop to minimize when a test starts running. This check box is cleared by default.

Select **Save test before running** if you want the SystemTest software to save your test before it runs. If this option is selected and you run a test that is not yet saved, you will be prompted to name and save the test. This check box is selected by default.

Note You can save a test any time, before or after running it, by selecting **File > Save**.

Confirmation Dialog Boxes

You can also turn off confirmation dialog boxes used in the SystemTest software in a different area of the Preferences dialog box by selecting **General** > **Confirmation Dialogs**. Three SystemTest confirmation dialog boxes are listed there, as shown in the figure that follows.

- Warn about launching Test Results Viewer without any saved results — Occurs if you attempt to open the Test Results Viewer when the latest test that ran does not contain any mapped results under Saved Results. To save results, click Saved Results in the Test Browser.
- Warn about using a Simulink model with an infinite simulation stop time Occurs if you attempt to run a test containing a Simulink element that uses a model with an infinite simulation stop time.
- Warn about using a Simulink model with unnamed logged signals — Occurs if you have a model that has logging enabled but has logged signals with no name, and you use that model in a Simulink element in the SystemTest software.

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∃-General	General	Confirmation Dialogs Preferences			
·····MAT-Files ·····Confirmation Dialogs ·····Source Control		wing dialog boxes require user confirmation. Select a check box if you wa			
Multithreading	State	Dialog Box Description	Tool 🛆		
+ Keyboard		Warn before deleting Command History items	Command History		
+ Fonts		Warn before clearing the Command Window	Command Window		
Colors		Confirm when overwriting variables in MAT files	Current Directory		
		Prompt when editing files that do not exist	Editor		
Toolbars		Prompt to exit debug mode when saving file	Editor		
Command Window		Show linking and brushing message bar	Figure Window		
Command History		Prompt to save on activate	GUIDE		
E-Editor/Debugger		Prompt to save on export	GUIDE		
Help		Confirm changing default callback implementation	GUIDE		
Web		Confirm before exiting MATLAB	General		
		rn about missing search databases Help			
		Prompt when editing drivers that do not exist	Instrument Control		
Workspace		Prompt when editing driver tests that do not exist	Instrument Control		
GUIDE		Warn about lanching Test Results Viewer without any saved results	SystemTest		
		Warn about using a Simulink model with an infinite simulation stop time	SystemTest		
		Warn about using a Simulink model with unnamed logged signals	SystemTest		
⊡-Figure Copy Template		Confirm when deleting variables	Workspace		
Report Generator					
SystemTest					
Database Toolbox					
Instrument Control					
⊡-Virtual Reality					
Simulink					
Simscape	1				
Simulink Control Design		Select all Clear all			
		OK Cancel	Apply Help		

Viewing Test Results

The SystemTest software allows you to view the results you have chosen to save for your test using a workspace variable called stresults. It provides access to the test results object, which is useful for comparing the results of separate test runs and for postprocessing test results.

For more information, see Chapter 10, "Accessing Test Results from the MATLAB Command Line".

Running Tests from the MATLAB Command Line

You can run one or more SystemTest tests from the MATLAB command line, using the strun function. This is useful for running multiple test files as a batch or calling a test file as part of an M-file.

Note If you use this feature, it is a good idea to first run the test from the SystemTest desktop to verify that elements are not in an error state, and that the test will run successfully, before running it via the MATLAB command line using the strun function.

The function takes the name of your test file as a string. The test file must be on the MATLAB path, or you can specify the full path in the string.

For example, to run a test called mytest that is on the MATLAB path, use this syntax:

strun('mytest')

To run a test called mytest that is not on the MATLAB path, but is in a local directory called c:\work, use this syntax:

strun('c:\work\mytest.test')

To run multiple tests, use a cell array of strings, as follows:

```
strun({'mytest' 'mytest2'})
```

Note MATLAB will remain busy while tests are executing via the strun command. Control is returned to the MATLAB command line once all tests execute.

For more information about using strun, see the function page.

Example: Building a Test

In this section...

"Overview" on page 1-11

"Planning Your Test" on page 1-11

"Building Your Test" on page 1-12

"Running Your Test" on page 1-36

"Analyzing Your Test Results" on page 1-40

Overview

This simple example illustrates the four primary stages of testing: planning, building, running the test, and viewing test results.

The example uses a simple MATLAB expression to emulate a scalar measurement during each iteration of the test. The example uses an arbitrary formula dependent on the test vector named signal to generate the Y data. The example tests each measurement to determine if it falls within certain specified limits. If a measurement exceeds these limits, that particular iteration of the test fails. By default, the test fails if any iteration fails, but you can configure other pass/fail criteria.

The following sections provide more information about each stage, building the example test along the way. If you prefer, instead of working through the following sections to build the example, you can load it into the SystemTest software by running the Getting Started with SystemTest demo from the **Demos** page in the MATLAB Help browser (under **MATLAB > SystemTest > MATLAB**) or by entering systemtest Simple_Demo at the MATLAB command prompt.

Planning Your Test

In this first stage, you must identify what it is you want to test. The SystemTest software lets you specify input data, such as measurements from a model or device, and compare this input data to some predefined limits. Based on this comparison, the SystemTest software can declare whether a test passes or fails. Keep the following in mind as you plan tests:

- Identify your test data and test vectors.
- Specify test limits and determine if these limits can be expressed as scalar or matrix values. (The Limit Check element supports both scalar and matrix data.)
- Determine what operations your test must perform. Must certain operations happen before others?
- Determine pass/fail criteria for your test.
- Decide which test variables you want to save as test results.

After this planning, you can begin to construct your test, which is described in "Building Your Test" on page 1-12.

Building Your Test

The SystemTest interface provides a graphical integrated environment that you can use to create and edit tests. Tests consist of elements, test vectors, and test variables. You can use each of these entities to create a variety of test scenarios ranging from a simple test that runs a series of elements once to a full parameter sweep that iterates over the values of test vectors that you define.

The following sections show how to construct a test:

- "Starting the SystemTest Software" on page 1-13
- "Structuring Your Test" on page 1-13
- "How Test Vectors and Test Variables Relate to the MATLAB Workspace" on page 1-15
- "Creating a Test Vector" on page 1-15
- "Defining Test Variables" on page 1-18
- "Adding Elements" on page 1-20
- "Defining Pass/Fail Criteria" on page 1-30
- "Saving Test Results" on page 1-31

- "Test Report" on page 1-33
- "Saving Your Test" on page 1-35

Starting the SystemTest Software

Start by opening the SystemTest desktop using the MATLAB Start button. To open the SystemTest software, select Start > MATLAB > SystemTest > SystemTest Desktop.

Alternatively, you can execute the systemtest command from the MATLAB command line.

The SystemTest software displays the desktop on your screen. See "Quick Tour of the SystemTest Software" on page 1-3 for an overview.

Structuring Your Test

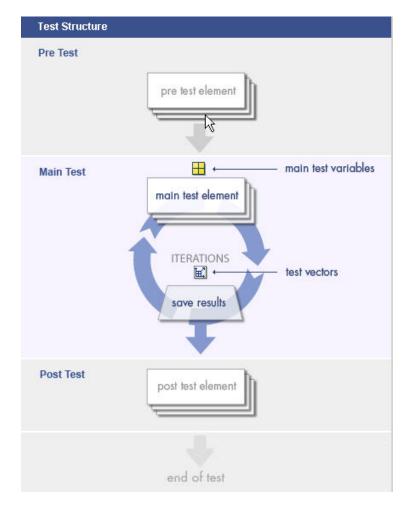
The SystemTest software divides tests into three sections.

- **Pre Test** This section is used to execute test elements in order to perform any test set-up operations, such as initializing variables, loading data from a file, and initializing system resources. Using Pre Test variables, you can assign an initial value to a test variable that persists between Main Test section iterations (unless another element in Main Test modifies the value). Pre Test is not mandatory, but it can be used if your test requires set-up operations to be performed.
- **Main Test** Main Test defines the test elements that need to be performed across the parameter space defined by your test vectors. In this section Main Test variables are initialized before each Main Test iteration, which lets you assign an initial value to a test variable each time the Main Test runs. This is useful if your test variable has a derived value such as being indexed by a test vector or is the result of a MATLAB expression.

The number of iterations performed in the Main Test is indicated in the **Test Browser** in parentheses after **Main Test**. Iterations specifies the number of times the Main Test section will be run. This is determined from the test vectors you define. The SystemTest desktop also offers a **Save Results** area for you to specify which test variables you want to save as test results at the end of each Main Test iteration.

• **Post Test** — In this section you can perform any cleanup work necessary at the completion of the Main Test section, such as clearing workspace variables, closing a file, or freeing system resources.

For details about the sections of the test, see "Working with the Sections of a Test" on page 3-2.



The following figure illustrates the structure of a test.

How Test Vectors and Test Variables Relate to the MATLAB Workspace

The SystemTest software has its own internal workspace that it uses to manage test variables and test vectors independently. However it does leverage the MATLAB workspace during test execution, and when using a MATLAB element.

During test execution, SystemTest test variables and test vectors are evaluated in the MATLAB base workspace. Then at the end of test execution, they are cleared out and the MATLAB base workspace is restored to what it was before the test execution.

When using a MATLAB element in the SystemTest software, you can reference a variable in the base workspace without having to create a test vector or test variable in the SystemTest software. However the SystemTest software will not be aware of this data, so you could not make use of it in any other element type or in saved results. You can only access it from a MATLAB element. If you need to use it in other elements, you can create test variables or test vectors in the SystemTest software.

Creating a Test Vector

Test vectors are composed of values derived from a MATLAB expression. You can use any MATLAB expression that evaluates to a 1-by-n matrix or cell array to define your test vector. Using test vectors, you can iterate through a range of values to see how a system performs. Test vectors constitute parameterized testing in the SystemTest software. They are the test cases for your test.

For tests with multiple test vectors, the product of the lengths of the test vectors defines the number of iterations the test performs. For example, if you define the test vector [10 20 30], the test runs three times, using a value of 10 for the first run, 20 for the second, and 30 for the final run. If you add a second test vector with three other values, the total number of test runs would be nine. The SystemTest software iterates through each vector in combination with the other vector as though the test were a group of nested FOR loops—the outermost loop being the first test vector in your table and the innermost loop being the last test vector. The **Main Test** section in the **Test Browser** shows the total number of test iterations defined by your test vectors.

T

For the example, use the vector [pi/15:pi/15:4*pi] which defines 60 values for our test vector ranging from pi/15 to 4*pi in pi/15 increments. To specify this test vector:

1 Click the New Vector button in the Test Vectors pane.

The Insert Test Vector dialog box opens.

_

- 2 Keep the default test vector type of **MATLAB Expression**. Assign a name to the test vector by clicking the **Name** field. For this example, name the test vector signal.
- **3** Assign a value to the test vector by clicking the **Expression** field. Enter the test vector specified above for the pi values. Click **OK**.

Properties		Test Vectors	× 5	Test Variables	
New >	C Evaluate		1		
Name		Length	Group Name		Гуре
signal	60			MATLAB Ex	pression
General Grou	uping				
Name:	signal				
Type:	MATLAB Expre	ccion			
Type.	MATCAD EXPLO	331011			
Expression:	[pi/15:pi/15:4*	ʻpi]			
Test Vector s	uccessfully eval	uated to a 1x60 do	uble		
Evaluate	lest Vector ead	h time the test is r	un		
					_
•					▼ ↓
p					

After you create the test vector, in the **Test Browser** pane, the **Main Test** section label updates to include the number of iterations defined by the test vector. It should say Main Test (60 Iterations).

Note Grouping test vectors determines how they will be iterated through when the test runs. For information on grouping vectors, see "Creating Grouped Test Vectors" on page 2-5.

Note You can also use probability distributions when you create a test vector. For information, see "Creating Randomized Test Vectors with Probability Distributions" on page 2-18.

Defining Test Variables

The SystemTest software uses *test variables* to define temporary storage variables that a test acts on or generates. You assign test variables in the Pre Test or Main Test sections of your test.

You can define Pre Test variables or Main Test variables. Using Pre Test variables, you can assign an initial value to a test variable that persists between Main Test section iterations (unless another element in Main Test modifies the value). Pre Test is not mandatory, but it can be used if your test requires set-up operations to be performed.

Main Test defines the test elements that need to be performed across the parameter space defined by your test vectors. Main Test variables are initialized before each Main Test iteration, which allows you to assign an initial value to a test variable each time the Main Test runs. This is useful if your test variable has a derived value such as being indexed by a test vector or is the result of a MATLAB expression. You add elements in this section.

The example test requires three test variables:

- Y Contains a value that will be calculated from the signal test vector at each iteration.
- HiLimit Contains the upper limit for Y that you do not want the signal to exceed.
- LowLimit Contains the lower limit for Y that you do not want the signal to go below.

To create these test variables:

- 1 Click the **Test Variables** tab in the middle pane of the SystemTest desktop.
- 2 Click the **New** button to create a Pre Test or Main Test variable. The Insert Test Variable dialog box opens. Leave the default value of Main Test in the Assigned in field, to create a new Main Test variable.

Insert Test Variable	×
Name:	
Var1	
Initial value (optional)	
Assigned in	
Main Test	T
	OK Cancel

- **3** Assign a name to the test variable by clicking the **Name** field and entering the test variable name. For this example, enter Y.
- **4** Set the test variable's initial value by clicking the **Initial Value** field and entering a value. For the example test variable Y, enter 0. Click **OK**.

Note If you do not provide an initial value, it will default to empty, that is, Var1 = []; in MATLAB code.

Note Test variables are re-initialized at the start of each test iteration. The **Initial value** field is blank by default when you create a test variable. If you leave it blank, it will initialize to []. If you enter an initial value (which can be any valid MATLAB expression), that value gets assigned in every iteration.

Properties	Test Vectors	Test Variables 🛛 🔻 🗙
New Edit 🛉 🐥	×	
Name	Initial Value	Assigned In
γ	0	Main Test

5 Repeat steps 2 to 4 to create the remaining two test variables, using the settings listed in the following table:

Variable Name	Initial Value	Assign in
HiLimit	1	Main Test
LowLimit	-1	Main Test

Adding Elements

Elements are the actions that a test performs. The SystemTest software includes the following set of elements, listed in alphabetical order.

- General Plot Used to plot any type of data over multiple iterations.
- IF Implements a logic control operator.
- Limit Check Specifies the comparison to be performed of the value(s) under test and their expected value(s), or limit(s).
- MATLAB Executes any MATLAB statements.

- Simulink Runs a Simulink model. Note that you need to have a license for Simulink to use this element.
- Stop Implements a logic control operator.
- Subsection Creates a new section in a test that you can use to group elements within.

Note Some MathWorks products, such as the Image Acquisition Toolbox[™] software, the Data Acquisition Toolbox[™] software, and the Instrument Control Toolbox[™] software, provide their own elements that integrate those products' capabilities within the SystemTest software. If you have licenses for those products, those elements will also appear in the elements list.

For more information about using the basic elements, see Chapter 3, "Working with the Basic Elements".

You add elements to a section in your test; however, not all elements can be added to all sections. For example, you can use a MATLAB element anywhere within a test, but you can only use the Limit Check element in the Main Test section.

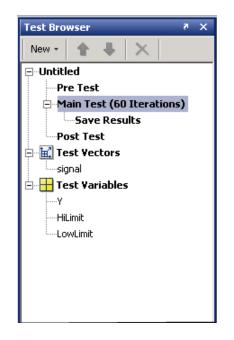
To illustrate using elements, let's continue with this example. This test uses three elements in the Main Test section.

Element	Description
MATLAB	Use a MATLAB expression to assign data to Y that is dependent on the test vector signal.
Limit Check	Compare the value generated in the MATLAB element to the specified limit and see if the Y test variable exceeds the upper or lower limit you defined in your HiLimit and LowLimit test variables.
General Plot	Plot the current test variable values and see whether the test variable exceeds the upper and lower limits.

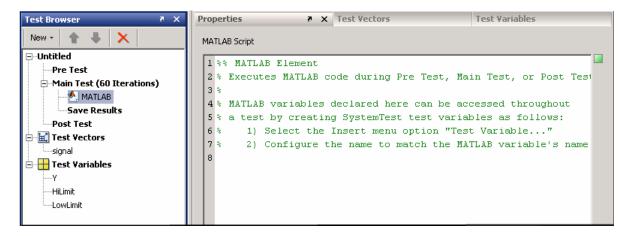
To add these elements:

T

1 Select the section of the test in which you want to add the element. For this example, click **Main Test** in the **Test Browser**.



2 Specify the element you want to add to the test section. For this example, click the **New > Test Element** button and select **MATLAB**. A MATLAB element appears in the Main Test section of your test and the MATLAB element property page opens in the **Properties** pane of the SystemTest desktop.



3 In the **Properties** pane, type the following M-code in the MATLAB Script edit box. This MATLAB code calculates a value for Y that is dependent on the test vector signal.

Y = sin(signal) + rand - .5;

Properties 7 × Test Vectors Test Variables	
MATLAB Script	
1 %% MATLAB Element 2 % Executes MATLAB code during Pre Test, Main Test, or Post Tes	31
3 % 4 % MATLAB variables declared here can be accessed throughout 5 % a test by creating SystemTest test variables as follows:	
 6 % 1) Select the Insert menu option "Test Variable" 7 % 2) Configure the name to match the MATLAB variable's name 	2
8 9 Y = sin(signal) + rand 5 ;	

During each iteration, the SystemTest software evaluates the MATLAB expression and assigns a value to Y.

1

4 Add the Limit Check element to the Main Test section of the test. With the MATLAB element selected, click the New > Test Element button, and click Limit Check. A Limit Check element appears in the Main Test section of the test and the Limit Check properties page opens in the Properties pane. For this example, the Limit Check element must follow the MATLAB element in the test.

Note You can reposition an element in a test by selecting the element and then clicking the up and down arrows in the **Test Browser** toolbar. You can also drag and drop elements within **Main Test**. You cannot move elements between test sections.

Test Browser 🛛 🤻 🗙	Properties 🛪 🛪 T	est Vectors	Test Variables
New 🔹 🛖 🦊 🗙	Conditions		
⊡Simple_Demo4	Conditions		
Pre Test	General Check Tolerance Ch	eck	
⊡-Main Test (60 Iterations)	New 🛧 🞩 🗙		1
🛃 MATLAB			
	Test Variable	Operator	Limit
Save Results			
Post Test			
🗐 🔛 Test Yectors			
signal			
E			
HiLimit			
LowLimit			
	For this element to pass:		
	All rows must evaluate to true	(logical AND)	•
	If this element fails:		
	Current iteration continues		
	Assign data to:		
			•
	J		

In the **General Check** tab, click the **New** button to add a limit check. Notice that the Limit Check element icon in the **Test Browser** shows a red x, which indicates that information is missing. The corresponding red outlining in the **Properties** pane highlights any fields that require configuration. A test cannot run unless everything is properly configured.

- **5** Specify the limit comparison operations in the Limit Check element.
 - **a** In the **Test Variable** column, click the drop-down list and select a test variable you created in step 4. For this example, select Y.
 - **b** In the **Operator** column, click the drop-down list and select the comparison you want to perform. For this example, pick the less-than-or-equal-to operator, <=.
 - In the Limit column, click the drop-down list and select the test variable you want to compare to. For this example, select HiLimit, which is the test variable you created earlier.

The following figure shows the configuration of this limit.

Properties 🛛 🤻	×	Test Vectors	Test Variables
Conditions			
General Check Tolera	ance	Check	
New 🔶 🐥	×		
Test Variable		Operator	Limit
Y		< = -	HiLimit 🗾

6 To add another limit comparison operation, click the New button again in the General Check Properties pane. A new row appears below the last limit you specified. In this new row, set Test Variable to Y, set Operator to >=, and set Limit to LowLimit.

Pro	perties	7 × 5	est Vectors	Test Variables	
	General Check	Tolerance Ch	neck		
	Test Var		Operator	Limit	
	Y	-	<=	HiLimit	
	Υ	-	>= 💌	LowLimit	

The following figure shows the configuration of this second limit.

For each iteration of the Main Test, the MATLAB element's expression is evaluated and a new value assigned to Y. When the Limit Check element runs, it determines whether the value of Y falls between the HiLimit and LowLimit values. If Y is outside this range, the test iteration fails. The default pass/fail criteria for the overall test passes the test only if both expressions in the limit check evaluate to true.

7 To view the test variables as the test runs, plot the data. To add a Plot element to the test, click the New > Test Element button, and select General Plot. A General Plot element appears in the Main Test section, and the properties page for the element opens in the Properties pane.

Test Browser 🍖 🛪	Properties 7 X Test Vectors	Test Variables
New - 🕇 🖡 🗙	General Options	
 Simple_Demo4 Pre Test Main Test (60 Iterations) MATLAB Main Limit Check Post Test Save Results Post Test Test Vectors signal Test Variables Y HiLimit LowLimit 	Add Axes Add Plot • Delete	
	Properties Figure name:	

With each Main Test iteration of the test, the General Plot element updates a figure window with data you selected.

- **8** Click the **Add Plot** button, and choose **plot** from the list to create a line plot.
- **9** We will set up three axes. For the first axes, use the one automatically created. Configure it as follows:

Click the arrow in Y Data Source and select Y.

Keep the default **Line color** of blue, and keep the default **Line style** of solid.

Change **Line marker** to point (the first selection in the list that shows one dot).

On the Options tab, select Keep any existing data on the figure.

- **10** Add the second and third axes by clicking the **Add Plot** button again twice and choosing **plot** from the list to create a line plot.
- 11 Configure the second and third axes to match the following table, and using <Iteration Number> as the X Data Source for each one and selecting

the **Keep any existing data on the figure** option for each one. The configured element looks like the figure following the table.

Y Data Sorce	Line Color	Line Style	Line Marker
Y	Blue	Solid	Point
HiLimit	Red	Dashed	No Marker
LowLimit	Black	Dashed	No Marker

Properties	Test Vectors		Test Variables	
General Options				
				1
Add Axes Add Plot +	× Delete			
⊡Figure ⊡Axes				
	eration Number>, Y)			
	eration Number>, HiLimit) eration Number>, LowLimit)			
	erador Humber >, containie y			
Properties				1
Plot Type:	plot			
	pior			
X Data Source: <iteratio< td=""><td>on Number></td><td></td><td>▼</td><td></td></iteratio<>	on Number>		▼	
Optional	I			
Y Data Source: LowLimit	:		T	
,				
Line color: 🥒 🗸	Line style:	Line marker: non	•	
			_	

To see the resulting plot, see "Tracking Output" on page 1-37.

Defining Pass/Fail Criteria

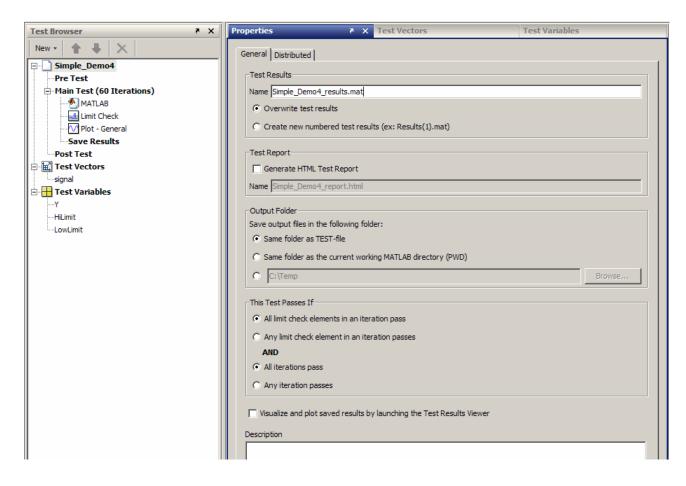
You can define whether your test passes or fails by monitoring the outcome of any or all Limit Check elements during any or all Main Test iterations. Your test's threshold of success can range from the passing of any Limit Check in any single test iteration to the passing of all Limit Check elements in all test iterations. If your test contains no Limit Check elements, there is no notion of pass/fail and no pass/fail information is displayed. (Testing of this type is useful for experimenting with a system or to explore its behavior rather than validate its performance.)

You can set any of the following conditions to define when your test passes:

- All Limit Check elements pass in all test iterations.
- All Limit Check elements pass in any test iteration.
- Any Limit Check element passes in all test iterations.
- Any Limit Check element passes in any test iteration.

You can configure this behavior within the test's **Properties** pane. Click the test name in the **Test Browser** (named **Untitled** by default) to open the test's properties and look for the section labeled **This Test Passes If**.

Using the signal test example that you constructed in this section, set the test to pass if all Limit Check elements pass in all test iterations.



Saving Test Results

You can save the results from the iterations of your test in a MAT-file. You must explicitly specify which test variables you want to save as test results.

The SystemTest software lets you save results at the end of each iteration. Before you run your test, select the **Save Results** section in your test and specify which test variables to save as test results. Click the **New Mapping** button and then select from the drop-down list the name of the test variable you want to map to a result. You can optionally specify a name for the results that you want to save. By default, the name of the saved result will be the

Test Browser	×	Properties	Test Vectors	Test Vari	ables
New - 🛉 🖡 🗙		Map Test Variables to Results			
🖙 🗋 Simple_Demo4		Specify the test variables you wa name.	ant to save at the end of eac	Main Test iteration by mapping a	test variable to a test result
Pre Test					
Main Test (60 Iterations)		Note, test vectors do not need to	o be specified. By default, the	y are made available with saved	test results.
MATLAB					
Limit Check		New Mapping 👚 🐥	X		
Plot - General		Test Var	riable	Resu	lt
Save Results		Y	•	Y	
Post Test					
🖻 🔛 Test Vectors		HiLimit		HiLimit	
signal		LowLimit	•	LowLimit	
🗄 🕂 Test Variables					
Y					
····HiLimit					
LowLimit					

same as the test vector or test variable. The following figure shows the mapping of test variables to test results.

After you specify which test variables to save as test results, you can specify the name of the MAT-file to use. Using this MAT-file you can reload the test results into the base workspace. By default, the SystemTest software names the file Untitled_results.mat and puts the file in the same directory as the TEST-File. To change the name or location of the MAT-file, click the test name in the **Test Browser**, then click the **Properties** pane.

Use the **Test Results** section to name the results file and to select overwrite behavior. By default, each time you run the test you overwrite this file unless you select the **Create new numbered test results** option. If you select that option, the name will be appended by successive numbers for each test run. For example, if the results file name is MyResults.mat, the next test run results will be called MyResults(1).mat, followed by MyResults(2).mat, etc.

Use the **Output Folder** section to designate the location to save the results file, as follows:

• Same folder as TEST-File – This is the default setting and saves any output files to the same location as the TEST-File. In this case your test and any output files it generates will all be in the same location. You set

this location when you use the **File > Save** menu to save your test, or if prompted to save when you close the SystemTest software.

- Same folder as the current working MATLAB directory Save any output files to the current working directory in MATLAB. You can see the current working directory when you open SystemTest from MATLAB.
- **Browse** Select the third option and then click the **Browse** button to choose an absolute directory location for the output files. This should be a location that is stable and is not read-only.

Note that the location you select here is also where the Test Report will be saved if you generate one.

Note If a file or folder location is read-only, you will get an error when the test runs. For results files and Test Reports to be generated, the files and folder locations must be writable.

Note Test variables that are not saved as a test result will be lost at the end of the test execution.

Test Report

When you run your test, status of the test appears in the **Run Status** pane. This display contains basic information about your test:

- Time elapsed since your test started running.
- Which section your test is in.
- How many test iterations have passed or failed as defined by any limit checks.
- Whether your test completed successfully.
- Any errors that cause your test to stop.

You can generate and save more detail about the running test by enabling the Test Report, which is a test execution log file in html format. This report is especially useful when you use limit checks in your test and you want to see specific test iterations that passed or failed. For example, instead of just finding that a test iteration failed, the report helps you determine how far a test variable varied from the upper or lower limit defined in a Limit Check element. It also displays any plots that were generated. This report is also useful for documenting and sharing your test results.

To enable the Test Report:

- 1 Click the test name in the Test Browser, then click the Properties pane.
- 2 In the Test Report section of the Properties pane, check the Generate HTML Test Report option.
- **3** Keep the default name or type a new one in the **Name** field.
- **4** Use the **Output Folder** section to designate the location to save the Test Report, as follows:
 - Same folder as TEST-File This is the default setting and saves any output files to the same location as the TEST-File. In this case your test and any output files it generates will all be in the same location. You set this location when you use the **File > Save** menu to save your test, or if prompted to save when you close the SystemTest software.
 - Same folder as the current working MATLAB directory Save any output files to the current working directory in MATLAB. You can see the current working directory when you open SystemTest from MATLAB.
 - **Browse** Select the third option and then click the **Browse** button to choose an absolute directory location for the output files. This should be a location that is stable and is not read-only.

The Test Report will be stored in a subfolder in this directory, along with all dependent files, such as plot or Simulink model snapshots. The overwrite options you set for your test results MAT-file also apply to the file name and directory of your report file. See "Saving Test Results" on page 1-31 to learn how to change these options.

Note that the location you select here is also where the test results will be saved.

Note If a file or folder location is read-only, you will get an error when the test runs. For results files and Test Reports to be generated, the files and folder locations must be writable.

The Test Report contains the following information about the test run, organized by iteration in the report:

- The test description, if you entered one in the **Description** field of the **Properties** pane of the test.
- A test summary, including start and stop times, number of iterations completed, number of iterations that passed and failed, and final status of the test.
- Pass/fail results of Limit Check elements, by iteration.
- Values for any saved results you captured by setting up mappings in **Saved Results**, by iteration.
- Test vector values, by iteration.
- A snapshot of your model if you use a Simulink element in the test.
- A snapshot of your plot if you use a Vector Plot, Scalar Plot, or General Plot element in your test, by iteration.
- A summary of generated files, with links to them. These can include a Simulink model coverage report and the test results launched in the Test Results Viewer.

Note Because the Test Report generates while the test is running, this option results in the test taking longer to execute.

See "Viewing the Test Report" on page 1-40 to see what information the report generates.

Saving Your Test

You can save tests so that you can reuse them later. For example, to save the signal test:

- 1 Select File > Save As to open the Save file as dialog box.
- 2 Select a directory location and enter mySavedTest in the File name field.
- 3 Click Save.

The SystemTest software saves the test as mySavedTest.test and renames your test as it appears in the **Test Browser**. This does not rename the test results MAT-file or the Test Report file. Their names are controlled separately from the name of the test, as explained in "Saving Test Results" on page 1-31.

Running Your Test

After you build a test, you are ready to run it. At run time, the SystemTest software assigns values to test vectors and test variables in the order they appear in the **Test Vectors** and **Test Variables** panes. Each test section runs elements in the order that they appear in the **Test Browser**.

To execute your test, do one of the following:

- Click the **Run** button.
- Select Run > Run.
- Press the F5 key.



Note While a test is running, you can stop its execution by pressing **Ctrl+C** or clicking the **Stop** button on the toolbar.

Tracking Output

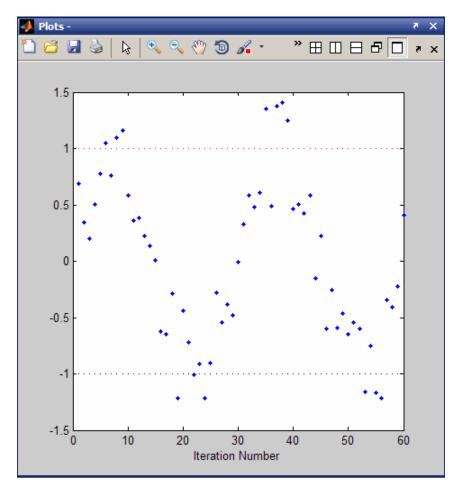
While the test runs, the **Run Status** pane shows summary test output, including start and stop times, number of iterations completed, number of iterations that passed and failed, and final status of the test. It will also display any error messages if the test has an error.

Run Status 🧧 🤻	×	Getting Started	Desktop Help
Generated Files		generated in C:\Temp\	
Open	Filen	ame	
<u>Test Results</u> <u>Viewer</u>	Sim	ole_Demo_results.mat	
Test Report	Sim	ole_Demo2_report\Simple_	_Demo2_report.html
Final Test Status			

Final Test Status Property Value Start Time 05-Jul-2007 10:51:25 Stop Time 05-Jul-2007 10:51:43 Iterations 60 Completed Iterations Passed 48 Iterations Failed 12 Final Status Failed Test Status: Failed Time Elapsed: 00:00:17 100 %

If your test includes a Plot element, the SystemTest software creates the plot and updates the plot during each iteration. Since Limit Check elements evaluate whether an iteration passed or failed, they directly affect the data that appears in the Test Report and the **Run Status** pane.

In the example test, the plot includes the high and low limits defined in the Limit Check element, to show which test iterations exceed the limits.



When the test is done running, the **Run Status** pane provides links to generated output. The **Generated Files** section contains a summary of

generated files, with links to them. These can include the Test Report; the test results, opened in the Test Results Viewer; and a Simulink model coverage report, if your test uses the model coverage feature.

Analyzing Your Test Results

After the SystemTest software runs your test, you can explore the results that are generated. This section shows how to:

- View and interpret the Test Report.
- Inspect your test results.

Viewing the Test Report

When you enable the Test Report, the SystemTest software saves information about each test iteration in an HTML file. To enable the Test Report, check the **Generate HTML Test Report** option on the **Properties** pane before running your test. The report contains summary information about the test run, snapshots of any plots you used, snapshots of any models you used, pass/fail results of Limit Check elements, and other information. See Test Report for a full description of what the report contains. After a test runs, you can see the contents of this file by clicking the **Test Report** button on the SystemTest toolbar or using the **Test Report** link in the **Run Status** pane. The generated output resembles the following.

{} file:///C:/MATLAB/Sim File Edit View Go Deb			_Demo_Getting_Started_repo	rt.html
				tting Started report.html
Simple_Demo_				
Pre Test				
Iteration 1				
Test Vectors				
Name	Value			
signal	0.209	344		
Limit Check				
Test Varia	ible	Operator	Limit	Evaluates To
Y 0.65804	4	<=	HiLimit 1	TRUE
Y 0.6580/	4	>=	LowLimit -1	TRUE
<u>Scalar Plot</u>				
¹ [
0.8 -				
0.6 -			•	
•[
Done				1.

The Main Test section of the report shows each iteration. You see the value of the test vector signal and determine the values the Limit Check element used in evaluating whether the test passed. For the first several iterations, the value of Y did not exceed either the high or low limits so the iterations passed. You can also see this in the scalar plot drawn while the test ran. For other iterations that failed, you can scroll through the report to find the values of Y.

Viewing Test Results

The SystemTest software allows you to view the results you have chosen to save for your test using a workspace variable called stresults. It provides access to the test results object, which is useful for comparing the results of separate test runs and for postprocessing test results.

For more information, see Chapter 10, "Accessing Test Results from the MATLAB Command Line".

To continue the example of Simple Demo, after you run the test, return to MATLAB and type stresults. The following summary of the results is returned.

```
>> stresults
stresults =
Test Results Object Summary for 'Simple_Demo':
    NumberOfIterations: 60
    TestVectorNames: signal
    SavedResultNames: HiLimit, LowLimit, Y
        ResultsDataSet: [60x4 dataset]
There are no Test Vector Groups associated with this test result object.
Artifacts associated with this test result object:
    TEST-File (Simple Demo.test)
```

You can see that the test contains 60 iterations, that it contains a test vector signal, and the names of the three saved results are HiLimit, LowLimit, and Y.

To see a more complete list of properties, type:

get(stresults)

That displays the following.

```
>> get(stresults)
    ResultsDataSet: [60x4 dataset]
    DerivedResultNames: {}
    NumberOfIterations: 60
    SavedResultNames: {'HiLimit' 'LowLimit' 'Y'}
    StartTime: [2009 6 17 14 54 18.1980]
    StopTime: [2009 6 17 14 54 26.4170]
    TestFile: 'H:\Documents\Simple_Demo.test'
    TestVectorNames: {'signal'}
    Artifacts: {'TEST-File' 'H:\Documents\Simple_Demo.test'}
    Tag: ''
    UserData: []
    Grouping: {''}
```

The ResultsDataSet property contains the test results data in the form of a dataset array. This is what you set up using the **Saved Results** node in the **Test Browser**. See "Saving Test Results" on page 1-31 for more information on setting up saved results.

To access the ResultsDataSet property, type:

stresults.ResultsDataSet

This returns the test results data in the form of a dataset array.

In the Simple Demo example, a portion of the test results data looks like this:

1

```
>> stresults.ResultsDataSet
```

ans =

	signal	HiLimit	LowLimit	Y
I1	[0.2094]	[1]	[-1]	[0.5226]
12	[0.4189]	[1]	[-1]	[0.8125]
13	[0.6283]	[1]	[-1]	[0.2148]
I4	[0.8378]	[1]	[-1]	[1.1565]
15	[1.0472]	[1]	[-1]	[0.9984]
16	[1.2566]	[1]	[-1]	[0.5486]
17	[1.4661]	[1]	[-1]	[0.7730]
18	[1.6755]	[1]	[-1]	[1.0414]
19	[1.8850]	[1]	[-1]	[1.4086]
I10	[2.0944]	[1]	[-1]	[1.3309]

In the dataset array, each row represents a test iteration, labeled using the convention of ['I' + Iteration_Number]. This example shows the first 10 iterations. Test vector values are listed first, in alphabetical order, followed by test results, listed in alphabetical order, as shown in the above figure. This is a simple way to view the results you set up in **Saved Results**. The test results for all iterations are displayed at the command line, even though only the first ten are only shown here.

You can now plot the results. See "Plotting Results Data" on page 10-10 to see plots created from these results.

Working with Test Vectors

- "Creating MATLAB Expression Test Vectors" on page 2-2
- "Creating Grouped Test Vectors" on page 2-5
- "About Test Vectors and the MATLAB Workspace" on page 2-12
- "Creating MAT-File Test Vectors" on page 2-13
- "Creating Randomized Test Vectors with Probability Distributions" on page 2-18
- "Creating Spreadsheet Data Test Vectors" on page 2-44
- "Creating Simulink Design Verifier Data File Test Vectors" on page 2-53
- "Creating Signal Builder Block Test Vectors" on page 2-67
- "Editing a Test Vector from within an Element" on page 2-73

Creating MATLAB Expression Test Vectors

Test vectors define the parameter space or set of test cases you want to run. Test vectors are composed of values that can be derived from a MATLAB expression. You can use any MATLAB expression that evaluates to a 1-by-N matrix or cell array to define your test vector. You must have at least one test vector defined to run a test.

The total number of Main Test iterations is determined by permuting all test vector values. For example, if one test vector is a 1-by-3 array and another is 1-by-2, it would result in a total of six iterations covering all the test vector value combinations.

To add a test vector:

1 Click the New Vector button in the Test Vectors pane.

In the Insert New Test Vector dialog box, keep the default test vector type of **MATLAB Expression**.

📣 Insert Test Vector	X
Select Test Vector type: MATLAB Expression Probability Distribution Signal Builder Block Simulink Design Verifier Data File Spreadsheet Data	General Grouping Name: TestVector1 Type: MATLAB Expression Expression: [1:1:10] Test Vector successfully evaluated to a 1x10 double Evaluate Test Vector each time the test is run
	OK Cancel

- 2 Assign a name to the vector in the Name field.
- **3** Enter the value by typing in values or a MATLAB expression in the **Expression** field.

The Size field fills in automatically based on what you entered if you press **Enter** or click outside of the Size field. For example, if you entered 1 : 1 : 10 in the **Expression** field, the Size would be a 1 x 10 double, which means 10 iterations.

4 Select the **Evaluate Test Vector each time the test is run** option if you want to use new values every time the test is run. For example, if your expression included a rand function, a new set of random numbers would be calculated each time. Leave it unselected if you want to use the same values each time the test is run.

5 Click OK in the Insert Test Vector dialog box.

The new vector appears in the **Test Vectors** pane.

Note Grouping test vectors determines how they will be iterated through when the test runs. For information on grouping vectors, see "Creating Grouped Test Vectors" on page 2-5.

For an example of creating test vectors in a test, see "Creating a Test Vector" on page 1-15.

Creating Grouped Test Vectors

When you create a test vector, it is an ungrouped vector by default, except for Probability Distribution test vectors. You can also create grouped vectors, in order to affect the way iterations are run. By grouping test vectors, they will be indexed simultaneously with the other vectors in their group. Each set of grouped values are then permuted with all the ungrouped test vectors. This gives more control over the flow of tests and is useful for Design of Experiments (DOE) or Monte Carlo-based testing as well as defining signal groups, similar to those defined in the Simulink Signal Builder block.

For example, if you are testing a throttle body controller, you may want to sweep across a range of input level or gain values, while simultaneously selecting different throttle body types, each defined by their mass and damping characteristics.

An example of the vectors in this scenario could look like this:

gain = [1 10 100] mass = [a b c d] damping = [w x y z]

If the gain vector is ungrouped, and the mass and damping vectors are grouped, it will result in mass and damping being indexed simultaneously for each value of gain. The test runs would look like this:

```
Run 1: (1, a, w)
Run 2: (1, b, x)
Run 3: (1, c, y)
Run 4: (1, d, z)
Run 5: (10, a, w)
Run 6: (10, b, x)
Run 7: (10, c, y)
Run 8: (10, d, z)
Run 9: (100, a, w)
Run 10: (100, b, x)
Run 11: (100, c, y)
Run 12: (100, d, z)
```

Note Grouped test vectors must be the same length.

You create a grouped test vector as you do any other vector, by clicking the **New Vector** button in the **Test Vectors** pane. To group a vector, change the selection using the **Grouping** tab in the Insert Test Vector dialog box. You can group any type of test vector, and you can create multiple test vector groups. You can also group or ungroup test vectors after you create them.

In general, it doesn't usually make sense to group Signal Builder Block test vectors or Simulink Design Verifier Data File test vectors. There are advantages to grouping MATLAB Expression, Probability Distribution, and Spreadsheet Data test vectors at times, depending on your test goals. One of the main advantages to grouping is for Monte Carlo-based testing, as described by the example above.

To group a test vector:

- **1** Create a test vector and configure it in the **General** tab of the Insert Test Vector dialog box.
- 2 Click the Grouping tab in the Insert Test Vector dialog box.
- 3 Select the Assign test vector to a group option.

A group is created and given the default name of Group1, as shown here.

✤ Insert Test Vector	X
Select Test Vector type: MATLAB Expression Probability Distribution Signal Builder Block Simulink Design Verifier Data File Spreadsheet Data	General Grouping Ungrouped test vectors will be permuted with other test vectors in every possible combination. Grouped test vectors will be combined sequentially with all test vectors in the same group, and then permuted with all other test vectors. ✓ Assign test vector to a group Clouble click to enter new group> Scoup1 Test vectors in group: Delete Name Length TestVector1 10 Note: All test vectors in the group must be of equal length. Note: All test vectors in the group must be of equal length.
	OK Cancel

- **4** To change the name, type the new name over the default name and press **Enter**.
- 5 Click OK in the Insert Test Vector dialog box.

In the Test Vectors pane, the name of the group is displayed in the table.

- **6** Now if you create another test vector, you can add it to the same group as the first one. To do this, click the **New Vector** button again.
- 7 Select the test vector type and configure it in the General tab.
- 8 Click the **Grouping** tab, and select the **Assign test vector to a group** option.

Note that test vectors in a group must all be the same length.

If you already have one test vector group, the new vector is placed in that group by default.

📣 Insert Test Vector			×
Select Test Vector type: MATLAB Expression Probability Distribution Signal Builder Block Simulink Design Verifier Data File Spreadsheet Data	Grouped test vectors will be combined with all other test vectors.	ed with other test vectors in every possible com sequentially with all test vectors in the same gro	
	<double click="" enter="" group<br="" new="" to="">Group1 Test vectors in group:</double>	>	
	Name	Length	
	TestVector2	10	
	TestVector1	10	
	Note: All test vectors in the group	must be of equal length.	
			OK Cancel

9 Click **OK** in the Insert Test Vector dialog box.

You can create multiple test vector groups. Once you have multiple groups, when you create new test vectors, you can select which group to put them in as you create them. The following figure shows Group1 containing TestVector1 and TestVector2, and Group2 containing TestVector3 and TestVector4.

roperties	Test Vectors	₹ X	Test Variables
Nov. IN Columb			
New X Evaluate			
Name	Length	Group Name	Туре
TestVector1	10	Group1	MATLAB Expression
TestVector2	10	Group1	MATLAB Expression
TestVector3	25	Group2	MATLAB Expression
TestVector4	25	Group2	MATLAB Expression
	combined sequentially with a	vectors in every possible combi all test vectors in the same grou	nation. p, and then permuted with all other Delete
	iame	Length	
TestVector4 TestVector3		25	
Note: All test vectors in I	the group must be of equal	length.	

You can also create groups after test vectors are already created by editing a test vector in the **Test Vectors** pane. Select a test vector in the table to edit its properties in the editor area below the table. There you can add it to a group using the **Grouping** tab. You can also add it to a group in the table by clicking in the **Group Name** column.

Managing Test Vector Groups

You can modify groups to ungroup a test vector, move a test vector to another group, rename a group, or delete a group.

- Ungroup a test vector To remove a test vector from a group, select it in the test vectors table, then click the **Group Name** column. Use the down-arrow to select the first entry, which is a blank space. The **Group Name** column will then be empty for that test vector, indicating it is no longer in a group.
- Move a test vector to another group To move a test vector from one group to another, select it in the test vectors table, then click the Group Name column. Use the down arrow to select the group to move it to. The Group Name column will then show the new group name.
- **Rename a group** You can change the name of a test vector group either in the table or in the editor area. Renaming a group in the table results in the group name for a single test vector being changed. Renaming a group in the editor area results in the name being changed for all vectors in the group.

To rename a group for a single test vector, select that vector in the table, then click in the **Group Name** column. Type a new name and press **Enter**.

To rename a group for all test vectors in the group, select one of the test vectors in the table. Then in the **Grouping** tab in the editor area, select that group name in the upper section and type a new name. Press **Enter**. You then see all of the test vectors in that group change to the new name in the table.

• **Delete a group** — To delete a test vector group, select one of the test vectors in the table that is in that group. Then in the editor area, under the **Grouping** tab, that group name will be selected. Click the **Delete** button on the **Grouping** tab. The group is deleted and all test vectors belonging to that group become ungrouped.

About Test Vectors and the MATLAB Workspace

The SystemTest software has its own internal workspace that it uses to manage test variables and test vectors independently. However it does leverage the MATLAB workspace during test execution, and when using a MATLAB element.

During test execution, SystemTest test variables and test vectors are evaluated in the MATLAB base workspace. Then at the end of test execution, they are cleared out and the MATLAB base workspace is restored to what it was before the test execution.

When using a MATLAB element in the SystemTest software, you can reference a variable in the base workspace without having to create a test vector or test variable in the SystemTest software. However the SystemTest software will not be aware of this data, so you could not make use of it in any other element type or in saved results. You can only access it from a MATLAB element. If you need to use it in other elements, you can create test variables or test vectors in the SystemTest software.

Creating MAT-File Test Vectors

The MAT-File test vector offers an easy way for you to use data from a MAT-file in the SystemTest software.

To add a test vector:

1 Click the New Vector button in the Test Vectors pane.

In the Insert New Test Vector dialog box, select the test vector type of **MAT-File**.

🥠 Insert Test Vector		×
Select Test Vector type:	General Variables Grouping	_
MATLAB Expression MAT-File	Name: TestVector1	
Probability Distribution Signal Builder Block	Type: MAT-File	
Simulink Design Verifier Data File Spreadsheet Data	MAT-Files to Read	
	Add File(s) 🛖 🦶 🗙 Remove File Select All Clear All	
	Unable to evaluate Test Vector. Configuration may be incomplete or in error.	
	OK Cancel	1

The red border indicating that the element is in an error state is normal, and will go away once you add file(s) in step 4.

- 2 Assign a name to the vector in the Name field.
- **3** Click the **Add File(s)** button.
- **4** In the Select MAT-File dialog box, browse for your MAT-file(s). You can select multiple files at the same time. Only MAT-files can be added. Other file types produce an error. After selecting the file(s), click the **Open** button to bring them into the test vector.

In the **MAT-Files to read** table on the **General** tab, MAT-files that are checked will be used in the test. Unchecking a file means it will not be included in the test.

5 Click the **Variables** tab. All the common variables contained in all the selected MAT-file(s) you added appear in the table.

🥠 Insert Test Vector		×
Select Test Vector type:	General Variables Grouping	
MATLAB Expression MAT-File	The following variables are in all the MAT-Files:	
Probability Distribution Signal Builder Block	Variables	
Simulink Design Verifier Data File	Distance	
Spreadsheet Data	✓ Pressure	
	Speed Speed	
	Torque	
	ans ans	
	OK Cancel	

Note that the variables are sorted in alphabetical order. If you have multiple MAT-files, only variables that are common across all files appear in the table.

Variables that are checked will be used in the test. Unchecking a variable means it will not be included in the test. In the example above, all variables except for ans will be used in the test.

Checking or unchecking the checkbox in the table header will select or unselect all variables. It is a Select All/Unselect All toggle option.

6 MAT-File test vectors are ungrouped by default. On the **Grouping** tab, you can select the **Assign test vector to a group** option if you want to group the test vector.

Grouping test vectors is useful for reducing the number of iterations to execute. It means that the SystemTest software will sequentially combine values for all grouped test vectors, instead of permuting their values. See "Creating Grouped Test Vectors" on page 2-5 for more information on grouped test vectors.

7 Click OK in the Insert Test Vector dialog box.

The new vector appears in the Test Vectors pane.

Important Usage Notes

- If you use multiple MAT-Files in a test vector, only commonly named variables included in all of the files will be read and used. For example, if you have variables in MAT-file A called Speed, Distance, and Pressure, and in MAT-file B you have variables Speed, Pressure, and Torque, only Speed and Pressure will be shown since they are included in both MAT-Files. Distance and Torque will not be used since they do not exist in both files.
- If the order of execution of the MAT-files is important, then use the up and down arrows to order the files accordingly in the test vector table. Each MAT-file is one iteration of the test vector, and they are executed in the order they appear in the table.
- The test vector is evaluated every time the test is run that means the data is read from the MAT-File(s) every time the test is run.
- If a MAT-File test vector is mapped to the inport blocks in a Simulink element using the **All Inport blocks are mapped** option, the model is simulated using all the variables that are selected in the **Variables** table in the test vector. If it is mapped to the inport blocks using the **Individual Inport blocks are mapped** option, the model is simulated with individually selected variables from the MAT-file.

• Checking or unchecking the checkbox in the **Variables** table header will select or unselect all variables. It is a Select All/Unselect All toggle option. This option affects the variables selection behavior when you add or remove or select or unselect MAT-files in the MAT-file list on the **General** tab.

For example, if the checkbox is selected (to Select All variables) and then a MAT-file is added/removed or selected/unselected, all common variables will be selected by default.

If the checkbox is unselected (to Unselect All variables) and then a MAT-file is added/removed or selected/unselected, all common variables will be unselected by default.

Creating Randomized Test Vectors with Probability Distributions

In this section...

"Using Probability Distributions in Test Vectors" on page 2-18

"Creating a Test Vector with Probability Distributions" on page 2-18

"Viewing Data While Configuring the Test Vector" on page 2-23

"The Probability Distributions" on page 2-26

"Example: Creating Test Vectors with Probability Distributions" on page $2{\text -}34$

Using Probability Distributions in Test Vectors

The SystemTest software provides an easy way to generate randomized test vector values for your test. You can use probability distribution functions to set up test vectors, which is useful for performing Monte Carlo analyses.

If you have the Statistics Toolbox[™] software, the SystemTest software integrates with it to provide use of some of its probability distribution functions, such as exponential, gamma, lognormal, T (Student's t), and Weibull. If you do not have the Statistics Toolbox software, you can use the MATLAB probability distribution functions normal (Gaussian) and uniform.

Creating a Test Vector with Probability Distributions

You can use a probability distribution when you create or edit a test vector. To use a probability distribution:

- 1 In the Test Vectors pane, click the New Vector button.
- **2** In the Insert Test Vector dialog box, select **Probability Distribution** as the test vector type.
- **3** Enter a name for the new vector in the **Name** field.
- 4 Select a distribution function from the **Distribution** list.

📣 Insert Test Vector		X
Select Test Vector Select Test Vector type: MATLAB Expression Probability Distribution Signal Builder Block Simulink Design Verifier Data File Spreadsheet Data	Distribution: Mean: Standard deviation: Number of values:	tor1 lity Distribution Normal (Gaussian) Exponential Gamma Lognormal
	Evaluate Test Vec	tor each time the test is run OK Cancel

If you have the Statistics Toolbox software, all of the functions shown in the figure appear in the list. If you do not have this toolbox, you can use normal (Gaussian) and uniform.

For information on the distribution functions, see "The Probability Distributions" on page 2-26.

5 Once you select a distribution, the relevant options appear. Fill in the parameters for your distribution.

General Grouping			
Name: TestVe	ctor 1		
Type: Probab	ility Distribution	View Data	
Distribution:	Normal (Gaussian)	-	
Mean:	1.0		
Standard deviation:	1.0		
Number of values:	10		
Test Vector successfully evaluated to a 1x10 double			

For example, normal (Gaussian) allows you to set **Mean** and **Standard deviation**.

6 After setting the relevant probability parameters, type in the **Number of values** you want to use. That is the number of values you would like to generate for the test vector.

The **Number of values** must be a positive integer. It must also be the same value for all of your probability distributions because the vector is grouped.

7 If you want to see the data you have configured before running the test, click the **View Data** button. This displays a histogram visualization of the probability distribution data. If you are not satisfied with the data as it is configured, you can adjust one or more of the parameters and hit **Enter** to see the changes in the figure window.

For more information on viewing the data, see "Viewing Data While Configuring the Test Vector" on page 2-23.

8 Select the **Evaluate Test Vector each time the test is run** option if you want to use new values every time the test is run. For example, for the

probability distribution, a new set of values for the parameters (such as Mean) would be calculated each time. Leave it unselected if you want to use the same values each time the test is run.

If you are doing Monte Carlo testing and you want repeatability of the data, do not use this option.

9 On the Grouping tab, keep the default of Grouped, or select Ungrouped.

Randomized test vectors with probability distributions are grouped by default, as indicated by **Grouped** being selected.

Grouping test vectors is useful for reducing the number of iterations to execute. It means that the SystemTest software will sequentially combine values for all grouped test vectors, instead of permuting their values. In the case of randomized test vectors, grouping avoids introducing additional variation into your test. See Creating Grouped Test Vectors for more information on grouped test vectors.

10 Click OK in the Insert Test Vector dialog box.

The new vector then appears in the **Test Vectors** pane.

Pr	operties	Test Vectors	Te 🗙 Te	st Variables
_				
	1	valuate		
	Name	Length	Group Name	Туре
	TestVector1	10	Group1	Probability Distribution
ŕ	▲▼			
	General Grouping			
	Name: TestVe	ctor1		
	Type: Probab	ility Distribution		
	Distribution:	Normal (Gaussian)		
	Discribution.			
	Mean:	1.0		
	Standard deviation:	1.0		
	Number of values:	10		
		,		
	Test Vector successfu	lly evaluated to a 1x10 doul	ble	
		ctor each time the test is rur		
		tor each time the test is fur	I	
I.	•			

Viewing Data While Configuring the Test Vector

You can view your probability distribution data while configuring the test vector, without having to run the test. You can quickly inspect the test vector data for outliers, data range coverage, or correctness of the test function before running the test. This allows you to make necessary adjustments until you have data you are satisfied with, which saves time.

To view data while configuring a test vector:

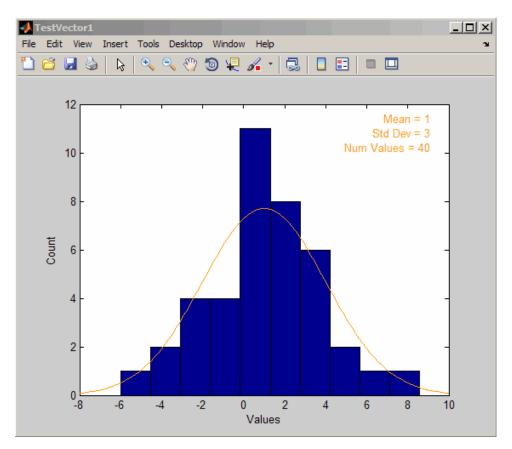
- 1 Create the test vector by clicking the New button in the Test Vectors pane.
- **2** In the Insert Test Vector dialog box, select **Probability Distribution** as the test vector type.
- 3 Select a distribution function from the Distribution list.
- **4** Once you select a distribution, the relevant parameters appear. Fill in the parameters for your distribution.

In this example, Normal (Gaussian) is shown, with a mean of 1.0, standard deviation of 3, and 40 values.

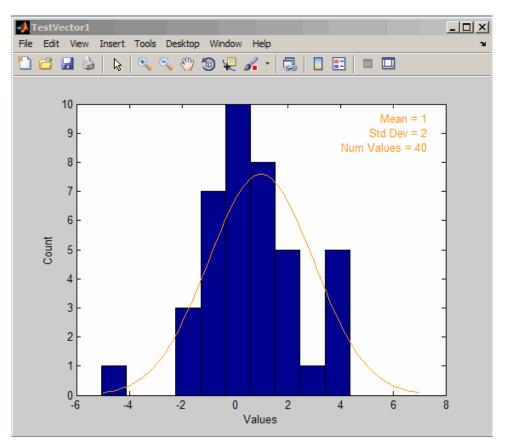
General Grouping			
Name: TestVe	ctor 1		
Type: Probab	ility Distribution View Data		
Distribution:	Normal (Gaussian)		
Mean:	1.0		
Standard deviation:	3		
Number of values:	40		
Test Vector successfully evaluated to a 1x40 double			
Evaluate Test Vec	tor each time the test is run		

5 Click the View Data button on the General tab.

6 The data viewer window displays the data you configured in a histogram visualization. The values are displayed on the *x*-axis, and in this case they range from approximately -6 to 9. The parameters are also displayed textually in the figure window in the upper right corner. For comparison purposes, a light orange line showing the "ideal" probability distribution is also displayed on top of your data.



- **7** When satisfied with the data that is shown, click **OK** to finish creating the test vector.
- 8 If you are dissatisfied with the data, change one or more parameters and redisplay it. In this case, change the standard deviation from 3 to 2. To change a value, type a new value in the parameter you want to change



and either press **Enter** or click outside of the field. The figure window automatically updates to display the new data.

You can also view and modify the test vector data any time after creating a test vector. Access the data viewer by clicking the **Test Vectors** tab in the **Properties** pane, then selecting a test vector from the list. That test vector then becomes editable, and you can click the **View Data** button on the **General** tab.

The Probability Distributions

If you have the Statistics Toolbox software, the SystemTest software integrates with it to provide use of some of its probability distribution functions, such as exponential, gamma, lognormal, T (Student's t), and Weibull. If you do not have the Statistics Toolbox software, you have access to the MATLAB probability distribution functions normal (Gaussian) and uniform.

The SystemTest software supports the distribution functions shown in the following sections. Select the **Probability Distribution** test vector type in the Insert Test Vector dialog box to access the functions.

The Insert Test Vectors dialog box shows fields specific to the distribution you pick in the list, as shown in the sections below. In each case, enter values for the function-specific parameters, and then enter the **Number of values** you want to generate for the test vector.

Normal (Gaussian)

The normal distribution is a two-parameter family of curves. The first parameter is the mean. The second parameter is standard deviation. Normal is often used for data that is symmetrical about the mean.

General Grouping			
Name:	Name: TestVector1		
Type:	Probability Distribution		
Distribution:	Normal (Gaussian)		
Mean:	1.0		
Standard de	viation: 1.0		
Number of v	alues: 10		
Test Vector successfully evaluated to a 1×10 double			
Evaluate Test Vector each time the test is run			

Normal uses the function randn and takes parameters for **Mean** and **Standard deviation**. The SystemTest software uses the following calculation for normal:

mean + Std_Dev * randn(1, #values)

For more information, see randn in the MATLAB documentation.

Uniform

The uniform distribution (also called rectangular) has a constant probability density function between its two parameters, the minimum and the maximum.

The uniform distribution is appropriate for representing the distribution of round-off errors in values tabulated to a particular number of decimal places.

eneral Grouping		
Name: TestVector2		
Type: Probability Distribution		
Distribution:		
Minimum Value: 1.0		
Maximum Value: 1.0		
Number of values: 10		
Test Vector successfully evaluated to a 1×10 double		

Uniform uses the function rand and takes parameters for **Minimum** value and **Maximum value**. The SystemTest software uses the following calculation for uniform:

min + (max-min) * rand(1, #values)

For more information, see rand in the MATLAB documentation.

Exponential

The exponential distribution is a special case of the gamma distribution. The exponential distribution is special because of its utility in modeling events that occur randomly over time.

Exponential is often used to model the time between independent events that happen at a constant average rate. For example, you could use it for the time it takes a radioactive particle decays, or the time between messages sent over a network.

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General Grouping		
Name: TestVector2 Type: Probability Distribution		
Distribution: Exponential		
Mean: 1.0		
Number of values: 10		
Test Vector successfully evaluated to a 1×10 double		

Exponential uses the function exprnd and takes one parameter for Mean.

For more information, see Exponential Distribution in the Statistics Toolbox documentation.

Gamma

The gamma distribution models sums of exponentially distributed random variables.

General Grouping			
	Wector2		
Type: Prot	pability Distribution		
Distribution:	Gamma		
A:	1.0		
в:	1.0		
Number of values	: 10		
Test Vector successfully evaluated to a 1×10 double			
Evaluate Test Vector each time the test is run			

Gamma uses the function ${\tt gamrnd}$ and takes parameters for A and B.

For more information, see Gamma Distribution in the Statistics Toolbox documentation.

Lognormal

The normal and lognormal distributions are closely related. The lognormal distribution is applicable when the quantity of interest must be positive, since log(X) exists only when X is positive.

Lognormal can be used to model something that can be thought of as the multiplicative product of many small independent factors. A common example is the long-term return rate on a stock investment, because it can be considered as the product of daily return rates.

General Grouping			
Name: TestVector2			
Type: Probability Distribution			
Distribution: Lognormal			
Mean: 1.0			
Standard deviation: 1.0			
Number of values: 10			
Test Vector successfully evaluated to a 1×10 double			
Evaluate Test Vector each time the test is run			

Lognormal uses the lognrnd function and takes parameters for **Mean** and **Standard deviation**.

For more information, see Lognormal Distribution in the Statistics Toolbox documentation.

Т

The T (Student's t) distribution is a family of curves that depend on a single parameter v (the degrees of freedom). As v goes to infinity, the T distribution approaches the standard normal distribution.

T is often used to estimate properties when the sample size is small.

General Grouping
Name: TestVector2 Type: Probability Distribution
Distribution: T Degrees of freedom: 1.0 Number of values: 10
Test Vector successfully evaluated to a 1×10 double

T uses the trnd function and takes one parameter for Degrees of freedom.

For more information, see Student's t Distribution in the Statistics Toolbox documentation.

Weibull

The Weibull distribution is an appropriate analytical tool for modeling the breaking strength of materials. Current usage also includes reliability and lifetime modeling. The Weibull distribution is more flexible than the exponential distribution for these purposes.

General Grouping		
Name: TestVector2		
Type: Probability Distribution		
Distribution: Weibull		
A: 1.0		
B: 1.0		
Number of values: 10		
Test Vector successfully evaluated to a 1×10 double		

Weibull uses the function wblrnd and takes parameters for ${\bf A}$ and ${\bf B}.$

For more information, see Weibull Distribution in the Statistics Toolbox documentation.

Example: Creating Test Vectors with Probability Distributions

Many models must take into account the effect of evaluating uncertainty in model parameters. In this example the tester needs to account for uncertainty in electric motor characteristics that come off the production line so the tester defines the model's parameters as distributions of values, rather than as single fixed values. The tester then performs a Monte Carlo simulation, running the model repeatedly with random combinations of parameter values to account for variability in manufacturing.

In this case, the tester defines the uncertain motor parameters as test vectors. The test varies parameters for armature resistance, armature inductance, and shaft inertia.

To create the first vector, for armature resistance:

- 1 In the Test Vectors pane, click the New Vector button.
- **2** In the Insert Test Vector dialog box, select **Probability Distribution** as the test vector type.
- 3 Enter ArmatureResistance in the Name field.
- **4** In the Insert Test Vector dialog box, use the default distribution, normal (Gaussian).

You do not need to have the Statistics Toolbox software installed to use normal (Gaussian) since it is included with MATLAB.

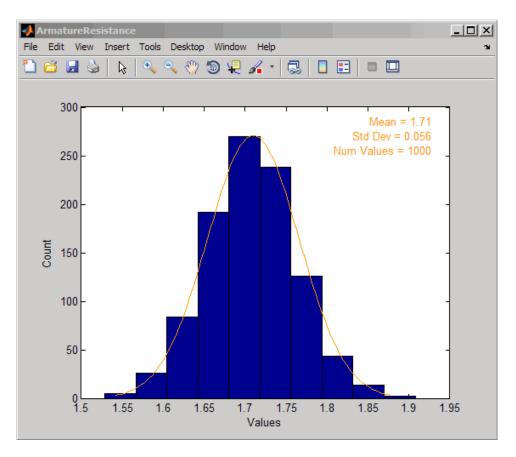
- **5** In the **Mean** field, enter 1.71.
- 6 In the Standard deviation field, enter .056.

General Grouping			
Name: Armatu	reResistance		
Type: Probab	lity Distribution	View Data	
Distribution:	Normal (Gaussian)	v	
Mean:	1.71		
Standard deviation:	.056		
Number of values:	1000		
Test Vector successfully evaluated to a 1x1000 double			
Evaluate Test Vec	tor each time the test is run		

7 In the Number of values field, enter 1000.

For this vector, the test is varying armature resistance up to a standard deviation of .056, around a mean of 1.71, and using 1000 values.

8 Click the View Data button to see a visualization of the test vector data that you configured. This displays a histogram visualization of the probability distribution data that will be used when the test is run. If you are not satisfied with the data as it is configured, you can adjust one or more of the parameters and hit **Enter** to see the changes in the figure window. In this case, we keep the data, as shown here.



For more information on viewing the data, see "Viewing Data While Configuring the Test Vector" on page 2-23.

9 Click OK in the Insert Test Vector dialog box.

The new vector appears in the Test Vectors pane.

Properties	Test Vectors	tes 🛪 🔁	t Variables
	valuate		
Name	Length	Group Name	Туре
ArmatureResistance	1000	Group1	Probability Distribution
			▲
General Grouping			
Name: Armatu	ureResistance		
Type: Probab	pility Distribution		
Distribution:	Normal (Gaussian)		
Mean:	1.71		
	·		
Standard deviation:	.056		
Number of values:	1000		
Test Vector successfu	ully evaluated to a 1×1000	double	
📃 Evaluate Test Ve	ctor each time the test is r	un	
			_
•			

To create the second vector, for armature inductance:

- 1 In the **Test Vectors** pane, click the **New Vector** button.
- **2** In the Insert Test Vector dialog box, select **Probability Distribution** as the test vector type.
- **3** Enter ArmatureInductance in the Name field.
- 4 Use the default distribution, normal (Gaussian).
- **5** In the **Mean** field, enter .3.
- 6 In the Standard deviation field, enter .01.

General Grouping	
Name: Armatu	reInductance
Type: Probabi	lity Distribution View Data
Distribution:	Normal (Gaussian)
Mean:	.3
Standard deviation:	.01
Number of values:	1000
Test Vector successful	ly evaluated to a 1x1000 double
🔲 Evaluate Test Vec	tor each time the test is run

7 In the Number of values field, enter 1000.

For this vector, the test is varying armature inductance up to a standard deviation of .01, around a mean of .3, and using 1000 values.

- **8** You can optionally click the **View Data** button to see a visualization of the test vector data that you configured.
- 9 Click OK in the Insert Test Vector dialog box.

The new vector appears in the **Test Vectors** pane.

Properties	Test Vectors	₹ X Tes	st Variables
New 🗙 E	valuate		
Name	Length	Group Name	Type
ArmatureResistance ArmatureInductance	1000	Group1 Group1	Probability Distribution
ArmatureInductance	1000	Group1	Probability Distribution
General Grouping			□
Name: Armat	ureInductance		
Type: Probal	bility Distribution		
i i i i i i i i i i i i i i i i i i i	Sincy Discribidation		
Distribution:	Normal (Gaussian)		
Mean:	.3		
Standard deviation:	.01		
Number of values:	1000		
	,		
Test Vector successfu	ully evaluated to a 1x1000	double	
Evaluate Test Ve	ctor each time the test is r	100	
		un	

To create the third vector, for shaft inertia:

- 1 In the Test Vectors pane, click the New Vector button.
- **2** In the Insert Test Vector dialog box, select **Probability Distribution** as the test vector type.
- 3 Enter ShaftInertia in the Name field.
- **4** Use the default distribution, normal (Gaussian).
- 5 In the Mean field, enter 44.5.
- 6 In the Standard deviation field, enter .443.

General Gr	ouping	
Name:	ShaftInertia	
Type:	Probability Distribution	View Data
Distributio	n: Normal (Gaussian)	-
Mean:	44.5	
Standard	deviation: .443	
Number o	f values: 1000	
	successfully evaluated to a 1x1000 double te Test Vector each time the test is run	

7 In the Number of values field, enter 1000.

For this vector, the test is varying shaft inertia up to a standard deviation of .443, around a mean of 44.5, and using 1000 values.

- 8 You can optionally click the **View Data** button to see a visualization of the test vector data that you configured.
- 9 Click OK in the Insert Test Vector dialog box.

The new vector appears in the **Test Vectors** pane.

roperties	Test Vectors	× 5	Test Variables			
	valuate					
Name	Length	Group Name				
ArmatureResistance	1000	Group1	Probability Distribution			
ArmatureInductance	1000	Group1	Probability Distribution			
ShaftInertia	1000	Group1	Probability Distribution			
▲▼						
General Grouping			<u> </u>			
Name: ShaftIr	nertia					
Type: Probab	ility Distribution					
Distribution:	Normal (Gaussian)					
Mean:	44.5					
Standard deviation:	.443					
Number of values:	1000					
Test Vector successfu	Test Vector successfully evaluated to a 1x1000 double					
Evaluate Test Ve	ctor each time the test is r	un				
4						

Creating Spreadsheet Data Test Vectors

In this section ...

"Introduction" on page 2-44

"Creating a Spreadsheet Data Test Vector" on page 2-44

"Configuring the Spreadsheet Data Test Vector" on page 2-48

"Replacing Strings" on page 2-51

Introduction

The Spreadsheet Data test vector type can be used to read data from Microsoft[®] Excel[®] files or .csv files into the SystemTest software. This feature also supports file formats used by the MATLAB xlsread function.

You can read spreadsheet data from multiple sheets, and can read whole sheets or a subset of a sheet.

For a detailed example using the Spreadsheet Data test vector, see "Example: Overriding Simulink Inport Blocks Using a Spreadsheet Data Test Vector" on page 4-27.

Note For additional technical information and limitations of this feature, see the SystemTest Release Notes.

Creating a Spreadsheet Data Test Vector

To create a Spreadsheet Data test vector:

- 1 In the **Test Vectors** pane, click the **New** button.
- **2** In the Insert Test Vector dialog box, select **Spreadsheet Data** as the test vector type.

🥠 Insert Test Vector		×
Select Test Vector type: MATLAB Expression Probability Distribution Signal Builder Block Simulink Design Verifier Data File Spreadsheet Data	General Data Selection String Replacement Grouping Name: TestVector: Type: Spreadsheet Data Files to Read Image:	
	OK Cance	el

3 On the **General** tab, click the **Add File** button.

Browse to your $Microsoft^{\circledast}$ $Excel^{\circledast}$ spreadsheet file or a $.\tt csv$ file and click ${\bf Open}.$

- **4** The first sheet of your file is selected by default. If the file has multiple sheets and you want to use them, select the other sheet(s). There is no limit to the number of sheets you can use.
- **5** Select the **Evaluate Test Vector each time the test is run** option if you want to read the file every time the test is run. Leave it unselected if you want to use the same values each time the test is run.

In the case of a Spreadsheet Data test vector, using this option means that data would be read from the spreadsheet file every time the test is run. If you expect the data to change and want to have it read every time, select this option. If you know the data is static or you do not want it to be read each time, unselect the option.

Note that you can use the **Evaluate** button in the **Test Vectors** pane any time for an immediate evaluation.

6 On the **Data Selection** tab, choose the range to use in the test vector. Enter this information in the **Data Range** section to select the range.

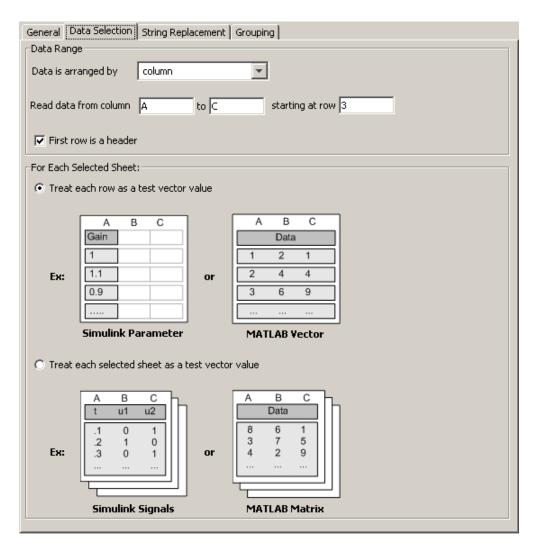
Specify whether your data is arranged by column or row using the **Data is** arranged by option.

Then select the specific range using the **Read data from** option. For example, if you have a file that has data in columns A, B, and C, and there is data in rows 3 through 13 and you want to read all the data, in the **Read data from column** option, fill in A to C. Then in the **starting at row** option, enter 3. The SystemTest software will read to the end of the data.

All data in the designated columns is read, from the start-at row through the end of data. Therefore you should only put data in the columns that you want to be read. Extraneous data should be removed if you do not want it to be read. Any blank cells within the read data range will be treated as NaN.

If the first row of your sheet is a header, you can select the **First row is a header** option to have the SystemTest software exclude it from the data.

7 In the **For Each Selected Sheet** section, select the option to determine how the data is arranged when the vector is created. You can have each row (or column) of the spreadsheet be a separate test vector value, or you can have the entire sheet be one test vector value.



See "Configuring the Spreadsheet Data Test Vector" on page 2-48 for more information about these two options.

8 You can optionally replace strings in the file with values using the **String Replacement** tab. The table is automatically populated with any strings contained in your sheet(s). If you want to replace each occurrence of a particular string with a value, type the value in the **Value** column of the table. Then when the test vector is evaluated, that string will be replaced with the value you indicated to populate the test vector.

See "Replacing Strings" on page 2-51 for more information about this option.

9 Click **OK** in the Insert Test Vector dialog box. The new vector then appears in the **Test Vectors** pane.

After creating a Spreadsheet Data test vector, you can edit it any time by selecting it in the table in the **Test Vectors** tab. If you make any changes to the configuration of the test vector in the SystemTest software, they will be applied immediately. If you make any changes to the underlying spreadsheet, you can have the data reread by clicking the **Evaluate** button above the test vectors table.

For a detailed example using the Spreadsheet Data test vector, see "Example: Overriding Simulink Inport Blocks Using a Spreadsheet Data Test Vector" on page 4-27.

Note If the data in your spreadsheet is numeric, it will be a double array in the test vector. If the data contains any strings, it will be a cell array. If the data contains header information and you specified the first row as a header, that will be excluded, and if the remaining data is numeric, it's treated as a double array.

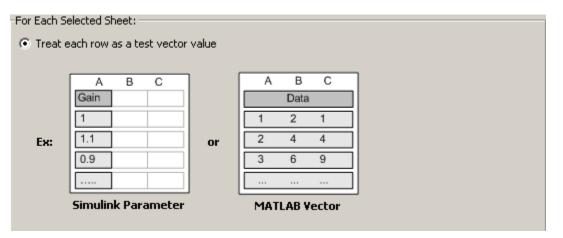
Configuring the Spreadsheet Data Test Vector

As shown in step 7 in "Creating a Spreadsheet Data Test Vector" on page 2-44, you can configure test vector values using the **Data Selection** tab when you create or edit a Spreadsheet Data test vector.

In the **For Each Selected Sheet** section, you select the option to determine how the vector is created. You can have each row (or column) of the spreadsheet be a separate test vector value, or you can have the entire sheet be one test vector value.

Treat each row as a test vector value

The **Treat each row as a test vector value** option means that each row or column (depending on what you selected in the **Data is arranged by** option) is one test vector value.

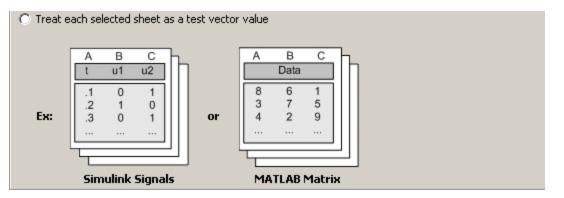


In the first case shown here, column A contains values for the parameter Gain. Suppose this column contains 10 values, in rows 2 through 11 (row 1 is a header). The resulting test vector would be a 1-by-10 array containing 10 values. The first value is 1, the second value is 1.1, etc. The ten populated rows result in a total of ten values, each row being one scalar value.

The same is true of the second example shown — that each row is a separate value, except that in this case each value is an array, instead of a single scalar. The first test vector value in this case is the array [1 2 1]. The second test vector value is [2 4 4], etc. If this sheet also had ten rows, there would be ten separate values (each an array of 3 numbers) and the test vector length would be 10.

Treat each selected sheet as a test vector value

The **Treat each selected sheet as a test vector value** option means that each entire sheet is one test vector value.



If the sheet contains multiple rows and columns, the resulting test vector value is a matrix. In the first example shown here, labeled Simulink Signals, this spreadsheet file contains 3 sheets. Suppose each sheet contained the three columns shown, t, u1, and u2, and had just the three rows of values shown. The resulting test vector would be of length 3 since each sheet is one test vector value and there are three sheets, and each of the three test vector values would be a 3-by-3 matrix.

Suppose the second example, labeled MATLAB Matrix, contained five sheets and each sheet had the three columns shown, each with ten rows of data. The resulting test vector would be of length 5 since each sheet is one test vector value and there are five sheets, and the five test vector values would each be a 10-by-3 matrix, since the sheets have ten rows of data and three columns.

Configuring each sheet to be one test vector value can be useful in a case where you have a test case in each sheet, and each test case is a matrix.

Using Multiple Sheets

If you configure a test vector to use multiple sheets in a file, and you use the **Treat each row as a test vector value** option, each sheet is read, turned into individual rows, and then appended together. For example, if your file has three sheets containing three, four, and five rows of data respectively, the resulting test vector is a set of row vectors as follows:

```
row 1 from sheet 1
row 2 from sheet 1
row 3 from sheet 1
row 1 from sheet 2
row 2 from sheet 2
row 3 from sheet 2
row 4 from sheet 3
row 2 from sheet 3
row 3 from sheet 3
row 3 from sheet 3
row 4 from sheet 3
row 5 from sheet 3
```

If you configure a test vector to use multiple sheets in a file, and you use the **Treat each selected sheet as a test vector value** option, the resulting test vector will have the same number of values as there are sheets in the file. The same file with three sheets would have three values:

```
sheet 1
sheet 2
sheet 3
```

Replacing Strings

As shown in step 8 in "Creating a Spreadsheet Data Test Vector" on page 2-44, you can optionally replace strings in the data you read from your spreadsheet files with values using the **String Replacement** tab when you create or edit a Spreadsheet Data test vector. The table lists any strings contained in your sheet(s), excluding headers if you've specified they are present.

If you want to replace each occurrence of a particular string with a value, type the value in the **Value** column of the table. Then when the test is run, that string will be replaced with the value you indicated to create the test vector.

An example use case for this feature is that you could have a spreadsheet that contains values for switches, and the values are designated by the strings ON and OFF.

	A	В	С
1	Switch A	Switch B	Switch C
2	OFF	ON	OFF
3	OFF	ON	OFF
4	ON	OFF	OFF
5			

In this example, you might want to replace each instance of ON with a 1 and each instance of OFF with a 0. The **String Replacement** tab of the Insert Test Vector dialog box would look like the following:

🥠 Insert Test Vector					2
Select Test Vector type:	General Data Selection	String Replacement	rouping		
MATLAB Expression Probability Distribution	Replace strings four	d in the read data with a s	calar numerical, scalar log	ical, or string value.	
Signal Builder Block		String		Value	
Simulink Design Verifier Data File	OFF		0		–
Spreadsheet Data	ON		1		Ī

If you want to map the same strings to different values, you have to create separate test vectors and do each replacement mapping separately. For example, in the previous case, you might want the values for Switch A to map to 1 and 0 as shown, but for Switch B you might want to use 100 and 0. In this case, create a test vector that reads only column A and replace ON and OFF with 1 and 0, and then create a second test vector for column B that maps Switch B values to 100 and 0.

Creating Simulink Design Verifier Data File Test Vectors

In this section...

"Prerequisites" on page 2-53

"Automatically Creating a SystemTest Test Harness from Simulink[®] Design Verifier" on page 2-53

"Creating a Simulink Design Verifier Data File Test Vector" on page 2-55

"Important Usage Notes" on page 2-65

Prerequisites

The Simulink Design Verifier Data File test vector can read test cases created by the Simulink[®] Design Verifier[™] software. In order to use this test vector, you need a Simulink Design Verifier data file with test cases.

To use this feature, you first run Simulink Design Verifier with the appropriate configuration. Then you can do one of two things:

- Generate a SystemTest harness for the model from Simulink. When it completes, a new test opens automatically in SystemTest and a Simulink Design Verifier Data File test vector is automatically created. This workflow is described in "Automatically Creating a SystemTest Test Harness from Simulink® Design Verifier" on page 2-53.
- If you already have a data file from Simulink Design Verifier, you can create a test vector in SystemTest that uses the test cases in the data file, and configure overrides in a Simulink element. This workflow is described in "Creating a Simulink Design Verifier Data File Test Vector" on page 2-55.

Automatically Creating a SystemTest Test Harness from Simulink Design Verifier

If you generate a SystemTest test harness from Simulink using Simulink Design Verifier, a new test opens automatically in SystemTest with a Simulink Design Verifier Data File test vector and a Simulink element automatically created for you. The following steps outline this workflow.

1 From your model, select **Tools > Design Verifier > Options**.

2 In the Configuration Parameters dialog box, select Design Verifier
 > Results, and then enable the Save test harness as SystemTest TEST-file option.

🍇 Configuration Parameters:	sldvdemo_cruise_control/Configuration (Active)
Select:	Lata nie options
Solver Data Import/Export	✓ Save test data to file Data file name: \$ModelName\$_sldvdata □ Include expected output values □ Randomize data that do not affect the outcome
	Harness model options Save test harness as model Harness model file name: Reference input model in generated harness SystemTest options SystemTest options Save test harness as SystemTest TEST-file (will reference saved data file)
Report Comments Symbols Custom Code Debug Interface Design Verifier Block Replacements Parameters	SystemTest file name: \$ModelName\$_harness
0	OK Cancel Help Apply

- 3 Click OK.
- 4 In Simulink, save the model.
- 5 From your model, select Tools > Design Verifier > Generate Tests to run the model and generate the SystemTest test harness.

After the model generates test cases, the SystemTest software opens automatically. A Simulink Design Verifier Data File test vector containing the generated test inputs is automatically created. A Simulink element is also created, configured with the model name, override mappings set, and model coverage enabled.

- **6** Optionally, in the SystemTest software, you can add other things to the test, such as a plot element. For an example of this, see "Creating a Simulink Design Verifier Data File Test Vector" on page 2-55.
- 7 Run the test in the SystemTest software by clicking the **Run** button.

Creating a Simulink Design Verifier Data File Test Vector

If you already have a data file from Simulink Design Verifier, you can create a test vector in the SystemTest software that uses the generated rest cases in the data file, and configure overrides in a Simulink element. The following steps outline this workflow.

- 1 In the **Test Vectors** pane, click the **New** button.
- 2 In the Insert Test Vector dialog box, select Simulink Design Verifier Data File as the test vector type.

📣 Insert Test Vector		×
Select Test Vector type: MATLAB Expression	General Details Grouping	
Probability Distribution Signal Builder Block Simulink Design Verifier Data File Spreadsheet Data	Name: TestVector1 Type: Simulink Design Verifier Data File	
Spreadsheet Data	Test Cases	
	Data File: Browse Test Cases Name	
	Unable to evaluate Test Vector. Configuration may be incomplete or in error.	
	OK Cancel	

- 3 Accept the default test vector name, or type a new one in the Name field.
- **4** Type the name of the Simulink Design Verifier data file in the **Type** field, or use the **Browse** button to locate it. It will be a .mat file.

Note that you must use a valid MAT-file – a Simulink Design Verifier data file created in version R2008b or later. If you try to use a data file created in an earlier version of the software or a MAT-file that is not generated from Simulink Design Verifier, you will get an error.

5	When the data file is read in, the test cases appear in the Test Case	es Name
	table. Click any test case to see its test case description below the	table.

🥠 Insert Test Vector		×
Select Test Vector type: MATLAB Expression Probability Distribution Signal Builder Block Simulink Design Verifier Data File Spreadsheet Data	General Details Grouping Name: TestVector1 Type: Simulink Design Verifier Data File Test Cases	
	Test Case 1	
	Test Case 1 Test Case 2 Test Case 3 Test Case 4 Test Case 5 Test Case 6 Test Case 7 Test Case 8 Test Case 9	
	Test Case 1 (8 Objectives) 1. enable logical value F @ T=0.00 2. logical trigger input true (output is from 1st input port) @ T=0.00 3. Logic: input port 1 T @ T=0.00 4. Logic: input port 1 T @ T=0.00 Unable to evaluate Test Vector. Configuration may be incomplete or in error. OK Can	ncel

6 To see information from the Simulink Design Verifier data file, click the **Details** tab. This provides analysis information on the data file, and the model Inport blocks associated with the test cases. If the test cases involve any model parameter configurations, they appear in the **Parameters** section. This section will list any parameters that are used as part of a test case. The information in this tab is not editable.

📣 Insert Test Vector		×
Select Test Vector type:	General Details Grouping	
MATLAB Expression	Analysis Information	
Probability Distribution	MaxProcessTime:	60
Signal Builder Block	Mode:	'TestGeneration'
Simulink Design Verifier Data File	SampleTimes:	0.01
Spreadsheet Data	Status:	'Completed normally'
	TestSuiteOptimization:	'CombinedObjectives'
	Input Port Information	
	Inport Block Name	Data Type
	enable	boolean
	brake	boolean
	set	boolean
	inc	boolean
	dec	boolean
	speed	double
	Parameters	
	Parameters Parameters in all the test cases:	
		OK Cancel
		OK Cancel

7 Click the **OK** button to finish creating the new test vector. It then appears in the **Test Vectors** pane in the SystemTest desktop.

Now that the test vector is created, you can create mappings in a Simulink element.

8 Create a Simulink element by clicking the Main Test node in the Test Browser, and clicking the New button. Select Test Element > Simulink. **9** Type the name of the model, or use the **Browse** button to locate it. This should be the same model that was used to create the Simulink Design Verifier data file.

If you browsed for the file, when you click **OK**, the model opens.

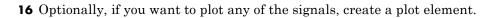
- 10 In the Override Inport Block Signals with SystemTest Data section of the Simulink element, select the All Inport blocks are mapped using option. You must select this option in order to correctly use the Simulink Design Verifier data file.
- **11** From the drop-down list, select the test vector you created earlier in this workflow.

Properties	X \$	Test Vectors	Tes	st Variables	
Simulink mod C:\MATLAB	del \sldvdemo_cruise_control.mdl				
sldvdemo_	cruise_control			Browse	
Mappings	Model Coverage				
					L
Over	ride Inport Block Signals	with SystemTest [)ata (all)	*	
The r	model contains 6 Inport block(s).			
0	Do not override Inport block s	ignals. (Use Inport si	anals defined by the model)		
	All Inport blocks are mapped (
	Individual Inport blocks are m	- ,			
		apped dsing.			
	Inport Block	Name	SystemTest (Data	
	enable		Inherit from model		
	brake		Inherit from model	<u> </u>	L
	set		Inherit from model		
	inc		Inherit from model	<u> </u>	
	Define test signal time:				
	Map test signal time t	p;		_	
	C Manually specify a tin	e step: 0.01			
	To calculate end time of simu Use model stop time	lation:			
	· · · · · · · · · · · · · · · · · · ·				
	C Use signal's end time				
Uver	ride Block Parameters wi	in System lest Da	ta	¥	
Over	ride MATLAB and Model V	/orkspace Variabl	es with SystemTest Data	• ×	
Run	Signal Builder test cases f	rom SystemTest		¥	
Assie	gn Model Outputs to Syste	emTest Data		*	
ASSI	gin roaci outputs to syste	annest D'ata			

In the example shown here, the model name is sldvdemo_cruise_control.mdl and the vector is TestVector1.

- 12 If you have the Simulink[®] Verification and Validation[™] software and you want to use the Model Coverage feature in the Simulink element, click the Model Coverage tab.
- **13** Select the **Enable Model Coverage** check box.
- 14 Select Override model coverage metric settings.
- 15 Select any metrics you want to cover in the Coverage Metrics section.

Properties	7 X Test Vectors	Test V	/ariables			
Simulink model			<u> </u>			
C:\MATLAB\sldvdemo_cruise_con	trol.mdl					
sldvdemo_cruise_control			Browse			
Mappings Model Coverage						
Enable model coverage						
C Inherit coverage metric set	tings from the model					
Override model coverage n	netric settings					
Overridden Coverage Metrics						
Coverage for this model:	Coverage for this model: sld	vdemo_cruise_control				
'	Select Subsystem					
Coverage for referenced	models					
All referenced models	are included					
	Select Models					
Coverage Metrics						
Decision Coverage		Condition Coverage				
MCDC Coverage		Look-up Table Coverage				
Signal Range Coverage						
Map Coverage Data to Test Var	iables					
New Mapping + 🛔 🖡	×					
Coverage Path	Metric	5	SystemTest Data			
			l <u> </u>			



Select the Simulink element you already created in the **Test Browser**, and select **New > Test Element > Plot – General**.

- **17** In the Plot element, click the **Add Plot** button.
- **18** Select **Simulink Data**.
- **19** From the **Simulink Data** field, expand the test vector that you created to see the individual signals.

Properties	Test Vectors	Test Variables
General Options	1	
<u> </u>	Add Plot + X Delete	
⊡-Figure ⊡-Axes		
	Simulink data ()	
Properties		
Disk Taraca	Simulink data	
Plot Type:		
	, 	
Simulink Data:		T T
		下 4
Line color:	<new test="" vector=""></new>	
	brake set	
	····inc	
	dec speed	

- 20 Select one of the signals, for example, speed.
- 21 Run the test by clicking the Run button on the SystemTest toolbar.

In this example, after the test runs, a model coverage report and a plot of the speed signal are generated.

Important Usage Notes

The following notes pertain to the integration between the SystemTest software and Simulink Design Verifier using the Simulink Design Verifier Data File test vector:

- **Model Coverage Report** The model coverage report generated by the model harness using Simulink Verification and Validation and that of the SystemTest harness generated by Simulink Design Verifier will be identical.
- **Data Format** The format of the data from a Simulink Design Verifier Data File test vector, if seen in a MATLAB element or in saved test results for example, is a subset of the Simulink Design Verifier data format.

It is a MATLAB structure with one field, TestCases. Then the TestCases field contains two fields, dataValues and paramValues. TestCases is a 1x1 structure. The following figure shows the data format for a Simulink Design Verifier Data File test vector called TestVector1:

```
K>> TestVector1
TestVector1 =
   TestCases: [1x1 struct]
K>> TestVector1.TestCases
ans =
   dataValues: {6x1 cell}
   paramValues: []
```

- **Data file Version** To use the Simulink Design Verifier Data File test vector, you must use a Simulink Design Verifier data file created in version R2008b or later. If you try to use a data file created in an earlier version of the software or a MAT-file that is not generated from Simulink Design Verifier, you will get an error.
- Evaluating the Test Vector If you make changes in the underlying Simulink Design Verifier test cases, you can click the Evaluate button in the Test Vectors pane any time to see the changes reflected in the SystemTest user interface. However this is not necessary to pick up the changes for running the test. When you run a test containing a Simulink Design Verifier Data File test vector, the SystemTest software automatically queries the data file for the latest information in the test cases.
- **Changing the Underlying Model** If you make changes in the underlying Simulink model, such as changes to Inport blocks, you should return to Simulink Design Verifier and regenerate the test cases and the test harness. Then return to SystemTest test harness to continue working with your test.
- Model End Time In the use case where you automatically generate the SystemTest test harness from Simulink Design Verifier, the end time used will be that of the test cases per iteration. However, in the use case where you create the test vector in SystemTest using a Simulink Design Verifier data file that you already have, the underlying model's end time will be used per iteration.
- **Bus Support** The Simulink Design Verifier Data File test vector supports the use of busses in Inport blocks. Bus support is only available in SystemTest through this feature.

2-66

Creating Signal Builder Block Test Vectors

If you have created a Simulink model test harness using a Signal Builder block, you can automate the running of all your test cases by integrating them into a SystemTest test. This also offers the ability to collect cumulative model coverage metrics for all your Signal Builder test cases.

The most common workflow for this feature is to create a Simulink element and then create the test vector from within the element, as follows:

- In the SystemTest desktop, create a Simulink element by clicking the Main Test node in the Test Browser, and clicking the New button. Select Test Element > Simulink.
- **2** Type the name of the model, or use the **Browse** button to locate it. This should be the model that includes the Signal Builder block whose test cases you are interested in.

When you click **OK**, the model opens.

This example uses the model systemtestsfcar.

- **3** In the Simulink element, click the up arrows in the banner of the **Override Inport Block Signals with SystemTest Data** section to close it.
- 4 Click the down arrows in the banner of the **Run Signal Builder test** cases from SystemTest section to expand it.
- **5** Enable the Signal Builder test cases by selecting the **Use test vector** check box.

6 Click the down arrow and select <New Signal Builder Block test vector...>.

Properties	8 X	Test Vectors	Test Variables	
Simulink model C:\MATLAB\systemtestsfcar.md systemtestsfcar	1		.	rowse
Mappings Model Coverage				
Override Inport Block	Signals	with SystemTest Data		*
Override Block Param	eters w	ith SystemTest Data		*
Override MATLAB and	Model	Workspace Variables with Sy	stemTest Data	×
🙀 Run Signal Builder t	est cas	ses from SystemTest		*
Use test vector	Iaw Ciar	al Builder Block Test Vector>	to run Signal Builder test cases.	
Assign Model Outputs				×

7 The Insert Test Vector dialog box opens and **Signal Builder Block** is the selected test vector type.

Keep the default test vector name or type a new one.

8 On the **General** tab, type the name of the model you used in the Simulink element, or click the **Browse** button to locate it.

Note You cannot use a Signal Builder Block test vector with a Simulink element that uses a different model. You must refer to the same model in both the test vector and the Simulink element.

9	When the model is found	, the Signal	Builder test	cases a	ppear in	the '	Test
	Cases section.						

📣 Insert Test Vector	
Insert Test Vector Select Test Vector type: MATLAB Expression Probability Distribution Signal Builder Block Simulink Design Verifier Data File Spreadsheet Data	General Test Signals Grouping Name: TestVector1 Type: Signal Builder Block Test Cases Simulink Model: Simulink Model: Systemtestsfcar.mdl Browse
	C:\MATLAB\systemtestsfcar.mdl Signal Builder Block: systemtestsfcar/User Inputs
	Test Vector successfully evaluated to a 1x4 cell array
	OK Cancel

If there are any test cases you do not want to test, you can disable them using the check boxes. Test cases that are checked will be tested.

10 You can click the **Test Signals** tab to view the test signals associated with your Signal Builder block.

- **11** Click **OK** to finish creating the test vector.
- 12 To view or edit the test vector after it is created, click the **Test Vectors** tab in the SystemTest desktop.
- **13** Optionally create other elements, test vectors, variables, or saved results, and run your test.

Note If you make changes in the underlying Signal Builder block in your model, you can click the **Evaluate** button in the **Test Vectors** pane any time to see the changes reflected in the user interface. However this is not necessary to pick up the changes for running the test. When you run a test containing a Signal Builder Block test vector, the SystemTest software automatically queries the model for the latest information in the Signal Builder block.

Note When you run the test, the Signal Builder test cases are run in the order in which they appear in the Signal Builder block in your model. This same order is reflected in the **Test Vectors** pane in the SystemTest software, unless you change the order in the table by sorting the columns.

Note You may have tested a Signal Builder block in previous SystemTest versions by using the **Override Block Parameters with SystemTest Data** section of a Simulink element. In that scenario you would create a new mapping to the Signal Builder block.

However, using the **Run Signal Builder test cases from SystemTest** section in the Simulink element and creating the Signal Builder Block test vector is a better and easier solution. Because the Signal Builder test cases are in a test vector, you can do more with them, such as plotting. Also, the signals are stored in the SystemTest results set, rather than the index of the test case.

Note that if you have a Simulink element that contains the mappings from the former way of including a Signal Builder block, and then you use the new Signal Builder Block test vector and use the new section in the same Simulink element, the test will use the new information in the **Run Signal Builder test cases from SystemTest** section in the Simulink element.

Editing a Test Vector from within an Element

If you want to edit a test vector while working within an element, you can open the editor by right-clicking on the name of the test vector in the table(s) on the **Properties** tab of some of the elements. This feature is included in the following elements:

- Limit Check General Check
- Limit Check Tolerance Check
- Simulink
- General Plot



Working with the Basic Elements

- "Working with the Sections of a Test" on page 3-2
- "Basic Elements" on page 3-5

Working with the Sections of a Test

In this section...

"Overview" on page 3-2

"Pre Test" on page 3-2

"Main Test" on page 3-3

"Post Test" on page 3-3

Overview

Each section of the test serves a different purpose and has different properties that can be set in the **Properties** pane. Click a part of the test or an element in the **Test Browser** to see the properties for that section or element.

The descriptions of the elements in this chapter include a list of which sections of the test you can use each element in. The following sections describe the sections of a test. They are followed by a description of how to use the basic elements.

Pre Test

The Pre Test runs once prior to any number of iterations through Main Test. Pre Test can be used to perform general test setup such as:

- Opening a model.
- Initializing variables.
- Accessing system resources, such as opening a file.
- Initializing external test equipment.

In Pre Test, only test variables defined as a Pre Test variable may be modified or assigned to. Pre Test variables are initialized during Pre Test and persist throughout the Main Test and Post Test.

In Pre Test you can add the following element types: Simulink, MATLAB, Subsection, Stop, IF, Video Input, the three Instrument Control Toolbox elements, and the four Data Acquisition Toolbox elements.

With Pre Test you can initialize Pre Test variables and run elements that you only want to run once before any Main Test iterations. For example, you can:

- Add a Simulink element to run a model and assign baseline data to a Pre Test variable.
- Add a MATLAB element to load a MAT-file or perform some other test setup.
- Create conditions with the IF element and follow up with a Subsection element to define what to do when those conditions are met.

Main Test

The Main Test is run one or more times based on the number of iterations. It is used to:

- Execute elements multiple times in order to perform batch testing or sweep through a parameter space.
- Perform batch testing or parameter sweeps that require multiple independent iterations using different test conditions for each iteration.

The number of iterations is defined by the number and length of test vectors you specify. The SystemTest software executes Main Test once for each permutation of values in the test vectors specified.

In Main Test you can add all of the element types.

Post Test

The Post test runs once after all Main Test iterations have executed or when a run-time error occurs in Pre Test or Main Test. Post Test can be used to perform test cleanup, such as:

- Closing a model.
- Cleaning up your workspace.
- Releasing system resources, such as closing a file.
- Returning external test equipment to a safe state.

In Post Test you can add the following element types: MATLAB, Subsection, IF, Video Input, the three Instrument Control Toolbox elements, and the four Data Acquisition Toolbox elements.

Basic Elements

In this section...

"Introduction" on page 3-5
"MATLAB Element" on page 3-6
"Limit Check Element — General Check" on page 3-7
"Limit Check Element — Tolerance Check" on page 3-11
"IF Element" on page 3-14
"General Plot Element" on page 3-15
"Vector Plot Element" on page 3-20
"Scalar Plot Element" on page 3-22
"Stop Element" on page 3-24
"Subsection Element" on page 3-25

Introduction

The sections listed above describe how to work with the basic elements.

The Simulink element is covered in detail in Chapter 4, "Using the Simulink Element". The hardware elements are covered in detail in "Introduction" on page 7-2 in Using the Image Acquisition Toolbox Element, "Introduction" on page 6-2 in Using the Data Acquisition Toolbox Elements, and "Introduction" on page 5-2 in Using the Instrument Control Toolbox Elements.

To see the MATLAB, Limit Check, and General Plot elements used in an example, see "Adding Elements" on page 1-20.

Tip You can rename any element or subsection by double-clicking its name in the **Test Browser**.

Invalid Characters in Element Names

The following characters are invalid to include within element names:

- '
- <
- >

You cannot use these three characters in element names. If you create a new test element with one or more of these characters in the element name, then the SystemTest software throws an error dialog and the element name is reset to the default value, which is the name of the element type.

If you try to load an existing test with an invalid element name (containing one or more of the three characters listed above), the SystemTest software displays an error dialog indicating that the element name is invalid. The test will load successfully, but the element with an invalid name is reset to use the default name for the element. If this occurs, simply rename the element to a name that does not contain any of the invalid characters.

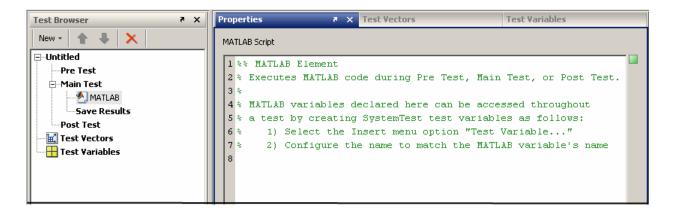
MATLAB Element

The MATLAB element lets you run MATLAB scripts from within a test. In addition to specifying any valid MATLAB script to execute, you can incorporate any test variable into your code, as well as access any variables residing in the MATLAB workspace.

Allowed Test Sections

The MATLAB element can be used in the following test sections:

- Pre Test
- Main Test
- Post Test



Properties Pane

In the MATLAB Script edit field, enter any valid MATLAB script.

Limit Check Element – General Check

The **General Check** tab of the Limit Check element determines test conditions are met by using scalar, vector, or matrix comparisons. It can be used to:

- Compare measured data to expected data.
- Stop an iteration or an entire test if a test constraint is violated.
- Assign a test variable the logical value derived from the comparison(s) for use by other elements.

You can do the following types of comparisons with the **General Check** tab of the Limit Check element:

- Scalar versus scalar
- Scalar versus vector
- Vector versus vector
- Matrix versus matrix

Note Use the Tolerance Check tab of the Limit Check element to test absolute and relative tolerance.

Allowed Test Sections

The Limit Check element can be used in the following test section:

• Main Test

Test Browser 🔭 🗙	Properties 🛛 🤊 🗙	Test Vectors	Test ¥ariables
Test Browser * New - • Untitled Pre Test Main Test	Properties N Conditions General Check Toleran New Test Variable		Test Variables
	For this element to pass: All rows must evaluate to If this element fails: Current iteration continu		
	Assign data to:		

How to Use

- **1** Click the **New** button on the **General Check** tab to add a general limit check.
 - Select an existing test variable or create a new one in the **Test Variable** column.

- Select an operator in the **Operator** column.
- Select an existing test variable or test vector or create a new one in the Limit column.
- 2 Set your test's passing conditions.
 - The element can pass if all comparisons complete successfully (a logical AND).
 - The element can pass if one or more of the comparisons complete successfully (a logical OR).
- **3** Set your fallback procedure if the element fails. You can:
 - Allow the current iteration to continue executing.
 - Stop the current iteration and proceed to the next iteration.
 - Stop the test and proceed to Post Test.
- **4** Identify the SystemTest test variable you want to assign the logical value derived from the comparison(s) in the **Assign data to** field.

Note Aside from setting limit checks on individual elements, you can set these properties for the entire test, reachable by clicking the test name in the **Test Browser**, to determine pass/fail criteria for the test as a whole.

Properties Pane – General Check

You can set the following properties for the Limit Check element:

- Test Variable Value to compare to limit using operator.
- **Operator** Boolean operator used to compare test variable to limit.
- Limit Value to compare to test variable using operator.
- For this element to pass Choose between a logical AND (all comparisons must pass) or a logical OR (at least one comparison needs to pass) for the element to pass.
- If this element fails Choose between continuing the test, stopping the current iteration, or stopping the entire test.

• Assign data to — Test variable assigned the logical value of this evaluation. The logical value will be 1 if the element passes or 0 if the element fails.

Limit Check Element – Tolerance Check

The **Tolerance Check** tab of the Limit Check element verifies test conditions are met by using absolute and relative tolerance comparisons. It can be used to:

- Compare measured data to expected data.
- Stop an iteration or an entire test if a test constraint is violated.
- Assign a test variable the logical value derived from the comparison(s) for use by other elements.
- Define pass/fail criteria for an iteration.

You can do the following types of comparisons with the **Tolerance Check** tab of the Limit Check element:

- Absolute tolerance
- Relative tolerance

For a definition of these tolerance types, see the Properties Pane section.

Note Use the General Check tab of the Limit Check element to test scalar, vector, and matrix comparisons.

Allowed Test Sections

The Limit Check element can be used in the following test section:

• Main Test

Test Browser 🛛 🛪 🗙	Properties	7 × Test Vectors	Те	st Variables
New - 👚 👢 🗙	Conditions			
⊡Untitled				
Pre Test	General Check Tolerance Check			
⊡Main Test	New 🛧 🖶 🗙			
Limit Check	Test Variabl	e Expected Value	Tolerance Type	Tolerance Limit
Post Test				
Test Vectors				
Test Variables				
	For this element t	o pass:		
	All rows must evaluate to true (logical AND)			
	If this element fails:			
	Current iteration continues			
				T
J				

How to Use

- **1** Click the **New** button on the **Tolerance Check** tab to add a tolerance limit check.
 - Select an existing test variable or create a new one in the **Test Variable** column.

- Select an existing test variable or test vector or create a new one in the **Expected Value** column.
- Select Absolute or Relative in the **Tolerance Type** column.
- Select an existing test variable or test vector or create a new one in the **Tolerance Limit** column.
- 2 Set your test's passing conditions.
 - The element can pass if all comparisons complete successfully (a logical AND).
 - The element can pass if one or more of the comparisons complete successfully (a logical OR).
- **3** Set your fallback procedure if the element fails. You can:
 - Allow the current iteration to continue executing.
 - Stop the current iteration and proceed to the next iteration.
 - Stop the test and proceed to Post Test.
- **4** Identify the SystemTest test variable you want to assign the logical value derived from the comparison(s) in the **Assign data to** field.

Note Aside from setting limit checks on individual elements, you can set these properties for the entire test, reachable by clicking the test name in the **Test Browser**, to determine pass/fail criteria for the test as a whole.

Properties Pane – Tolerance Check

You can set the following properties for the Limit Check element.

- **Test Variable** Variable to compare with expected value using a tolerance limit.
- **Expected Value** Expected value to compare variable to using a tolerance limit.
- **Tolerance Type** Tolerance type used to compare test variable to the expected value. Select Absolute or Relative. Absolute tolerance is

calculated using this formula: abs(test variable - expected value)
<= tolerance limit. Relative tolerance is calculated using this formula:
abs(test variable - expected value) <= tolerance limit.*
abs(expected value).</pre>

- **Tolerance Limit** Value used as the tolerance constraint to compare variable and expected value.
- For this element to pass Choose between a logical AND (all comparisons must pass) or a logical OR (at least one comparison needs to pass) for the element to pass.
- If this element fails Choose between continuing the test, stopping the current iteration, or stopping the entire test.
- Assign data to: Test variable assigned the logical value of this evaluation. The logical value will be 1 if the element passes or 0 if the element fails.

IF Element

The IF element provides logical control of a test by evaluating a condition.

The IF element allows sub-elements to run only when the IF element's condition evaluates to true. After adding an IF element, you should add one or more elements to perform a specific task.

Allowed Test Sections

The IF element can be used in the following test sections:

- Pre Test
- Main Test
- Post Test

Test Browser 🛛 🛪 🗙	Properties	Test Vectors	Test Variables
New - 🔺 🖶 🗙	Condition		
⊡…Untitled	false		
Pre Test			
⊡ • Main Test			
Save Results			
Post Test			
Test Yectors			
Test Yariables			

Properties Pane

You can set the following property for the IF element.

• **Condition** — Enter a valid MATLAB expression that will evaluate to true or false.

General Plot Element

The General Plot element is used to plot any type of data over multiple iterations.

Use this element during the Main Test to generate plots of any test vectors or test variables containing any type of data.

Allowed Test Sections

The General Plot element can be used in the following test section:

• Main Test

Test Browser 🛛 🛪 🗙	Properties	7 X Test Vectors	Test Variables
New - 🛊 🖡 🗙	General Options		
⊡ Untitled			
Pre Test	Add Axes Ad	d Plot 🔹 📉 Delete	
-Main Test	Figure Axes		
Test Vectors			
	Properties		
	Figure name:		
I			

General Tab

To add a plot:

- 1 Click the Add Plot button to create a plot.
- 2 From the drop-down list, select one of the following:
 - **plot** A standard line plot that uses a 2-D line graph with linear axes.
 - Simulink data Lets you plot data produced from a Simulink model. The supported data types are such [time signal] array, a structure, a structure with time, or a time series. Note that the element creates a line for each signal in the Simulink data. If time is not present, the signals are plotted against their indices.

You can also plot Simulink data provided by test vectors, such as the Signal Builder Block test vector, the Simulink Design Verifier Data File test vector, or the Spreadsheet Data test vector.

- **bar** A standard bar plot that creates a bar graph.
- scatter A standard scatter plot that creates a 2-D scatter graph displaying markers at x- and y-coordinates.
- **contour** A standard line plot that creates a 3-D contour graph displaying isolines of a surface in a 3-D view.
- **imagesc** An image plot with colormap scaling, which displays an image and scales it to use the full colormap.
- **surf** A standard surface plot that creates a 3-D surface plot that displays a matrix as a surface.
- **mesh** A standard surface plot that creates a 3-D mesh plot displaying a matrix as a wireframe surface.
- **More plots** Opens the Choose Plot Type dialog box, which lets you choose any MATLAB plot. Select a plot type category in the **Categories** list to display the plot types from the **Plot Types** list. Select an individual plot type to read the **Description**.

Add Axes Button

You can have multiple axes in a plot figure. To add an axes, click the **Add Axes** button. Then click the **Add Plot** button to create the plot for that axes. Each axes is added as a subplot to the parent figure.

You can set properties for each axes individually by selecting the axes and then configuring properties in the **Properties** area. With the axes selected, you can configure the X and Y labels and add a title and legend. With the plot under the axes selected, you can configure the plot.

Properties

When the **Figure** node is selected or you have not yet added a plot, the **Figure name** field is displayed. Optionally use this text field to name the plot.

When you select a plot type and it is added to the tree, the **Properties** section displays the properties of that plot type. Fill in any parameters you want to set. For more information on the parameters, see the help in the Choose Plot Type dialog box when you select **More Plots**.

When you select an axes the axes properties are displayed. Use the **X label** and **Y label** fields to enter names for the X and Y axes. Use the **Title** field to enter a title for the plot. If you select the **Include legend** option, a legend is added to the plot. The legend is located in the least used space outside of the plot.

You can set other options for the General Plot element by clicking the **Options** tab.

Plotting Simulink Data

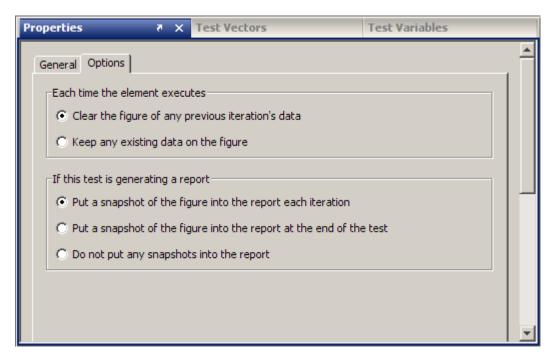
You can plot data produced from a Simulink model. The supported data types are such [time signal] array, a structure, a structure with time, or a time series. Note that the element creates a line for each signal in the Simulink data. If time is not present, the signals are plotted against their indices.

You can also plot Simulink data provided by test vectors, such as the Signal Builder Block test vector, the Simulink Design Verifier Data File test vector, or the Spreadsheet Data test vector. The Simulink data types are plotted as follows:

- For an array, it is plotted against its indices.
- For a structure in the format generated by a Simulink Outport, its signal values are plotted against its indices.
- For a structure with time in the format generated by a Simulink Outport, its signal values are plotted against its time.
- For a structure with time in the format generated by the Signal Builder Block test vector, its signal values are plotted against its time.
- For a Simulink.Timeseries object, the plot is determined by the plot() function of the Simulink.Timeseries object.

Options Tab

These options control the test behavior pertaining to plots.



The **Each time the element executes** option determines run-time behavior of the element.

- **Clear the figure of any previous iteration's data** Every time the element executes, the figure is cleared before plotting new data. This is the default.
- Keep any existing data on the figure Previous plots are not removed from the figure. New data is added to the same figure.

The **If this test is generating a report** option determines what happens to the snapshots of the plots that are created when each iteration runs.

- Put a snapshot of the figure into the report each iteration A snapshot of the plot is generated in each iteration and is displayed in its respective section of the report. This is the default.
- Put a snapshot of the figure into the report at the end of the test Only one snapshot of the plot is taken, at the end of the completed test run. It is displayed in the report section for Post Test.
- **Do not put any snapshots into the report** No snapshots of plots are added to the report.

Vector Plot Element

Note: The Vector Plot and Scalar Plot elements are being replaced by the General Plot element that was introduced in R2008b. The General Plot element supports all MATLAB plot types as well as Simulink data. Customers should no longer create new Vector Plot or Scalar Plot elements. For more information, see the R2009b section of the SystemTest Release Notes.

The Vector Plot element is used to plot array or vector data over multiple iterations.

Use this element during the Main Test to generate plots of any test variables containing array or vector data. You can change the number of iterations displayed to as many as 16 (in a 4-by-4 matrix) using the **Subplot Dimensions** fields. The default is one iteration.

Allowed Test Sections

The Vector Plot element can be used in the following test section:

• Main Test

Test Browser 🛛 🛪 🗙	Properties	7 × Test Vecto	rs	Test Variables
New - 🛊 🖡 🗙	Plot Type			
	plot			•
Save Results	X Axis			
Post Test	<none></none>			•
Test Vectors	Lines to Plot			
Test Variables				
	New 👚 🐥	×		
	Y Axis	Line Color	Line Style	Line Marker
	▼	<auto> 💌</auto>	Solid 📃 💌	No Marker 🗾
	Subplot Dimensions Rows 1 Clear axes between	• iterations	Col	umns

Plot Type

Choose one of the following plot types:

- **plot** Standard plot of X and Y.
- semilogx Semilogarithmic plot with logarithmic X-axis.
- semilogy Semilogarithmic plot with logarithmic Y-axis.
- loglog Log-log scale plot.
- stem Lines extending from a baseline along the X-axis.

Properties Pane

You can set the following properties for the Vector Plot element.

- X Axis Choose a test variable to use for an X-axis value.
- Y Axis Choose a test variable to use for a Y-axis value.
- Line Color Select a color to use for the line between each data point.
- Line Style Set the type of line to be drawn between each data point.
- Line Marker Choose a symbol to represent each data point.

Subplot Dimensions

- Rows The number of rows you want displayed in the Subplots window.
- **Columns** The number of columns you want displayed in the Subplots window.
- **Clear axes between iterations** Applies only when you have one row and one column to display. Selecting this option (default) rewrites the plot with new data during each iteration. Clearing this option adds new data to the plot during each iteration.

Scalar Plot Element

Note: The Scalar Plot and Vector Plot elements are being replaced by the General Plot element that was introduced in R2008b. The General Plot element supports all MATLAB plot types as well as Simulink data. Customers

should no longer create new Scalar Plot or Vector Plot elements. For more information, see the R2009b section of the SystemTest Release Notes.

The Scalar Plot element is used to plot scalar data for each iteration.

Use this element during the Main Test to generate a plot of one or more scalar test variables.

Allowed Test Sections

The Scalar Plot element can be used in the following test section:

Test Browser 🔭 🗙	Properties	X 5	Test Vecto	rs	Test Variables	
New - A A X	Plot Type	ot				•
⊡Main Test Scalar Plot Save Results Post Test	X Axis	er				
─── <mark>──</mark> Test ¥ectors ─────── Test ¥ariables	Maximum Number	r of Points to ()isplay at Onc	e		
	Lines to Plot	* ×	ine Color	Line Style	Line Marker	
		<aut< th=""><th></th><th>Solid</th><th>No Marker</th><th>•</th></aut<>		Solid	No Marker	•

• Main Test

Plot Type

Choose one of the following plot types:

• **plot** — Standard plot of X and Y.

- semilogx Semilogarithmic plot with logarithmic X-axis.
- semilogy Semilogarithmic plot with logarithmic Y-axis.
- loglog Log-log scale plot.
- stem Lines extending from a baseline along the X-axis.

Properties Pane

You can set the following properties for the Scalar Plot element.

- Maximum Number of Points to Display at Once Determine how many points to show simultaneously. By default this is infinite such that all points will be plotted. Use a MATLAB numeric that evaluates to a positive, nonzero integer to set this field's value.
- X Axis Choose a test variable to use for an X-axis value.
- Y Axis Choose a test variable to use for a Y-axis value.
- Line Color Select a color to use for the line between each data point.
- Line Style Set the type of line to be drawn between each data point.
- Line Marker Choose a symbol to represent each data point.

Stop Element

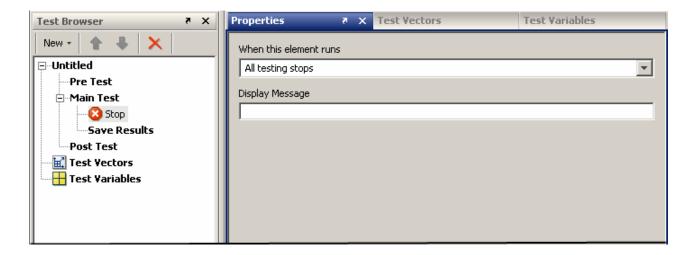
The Stop element stops an iteration or an entire test unconditionally.

You can use the Stop element with conditional logic elements, such as the IF element, to control the test's execution.

Allowed Test Sections

The Stop element can be used in the following test sections:

- Pre Test
- Main Test



Properties Pane

You can set the following properties for the Stop element.

• When this element runs — Select a stop action for use in Main Test. The Current iteration stops option stops the current Main Test iteration. The All testing stops option stops all Main Test iterations and runs Post Test.

Note that when a Stop element is used in Pre Test, **All testing stops** is the only option, since Pre Test does not have iterations.

• Display Message — Enter a message to display in the Test Report.

Subsection Element

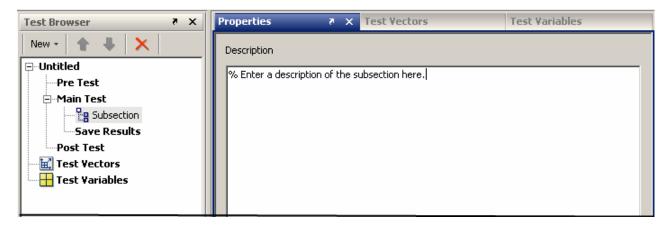
Use subsection elements to organize one or more elements to maintain readability of your test or to better manage complex test structures. Use a subsection to:

- Group elements under a single root element.
- Organize tests.
- Manage complex test structures.

Allowed Test Sections

The Subsection element can be used in the following test sections:

- Pre Test
- Main Test
- Post Test



Properties Pane

You can set the following properties for the Subsection element.

• **Description** — Type in your description of the subsection.

Using the Simulink Element

The Simulink element allows you to override the inputs to a Simulink model with SystemTest test vectors and test variables. You can further map the model's outputs to SystemTest test variables for later processing by other test elements. This means that you can use the SystemTest software to define, generate or load input data, feed it into Simulink, run the model while iterating over the input data, and map the outputs back into the SystemTest software.

Note To use the Simulink element, you must have a license for Simulink.

- "Before You Begin" on page 4-2
- "Mapping Test Vectors and Test Variables to a Simulink Model" on page 4-4
- "Overriding Inport Block Signals" on page 4-21
- "Using Simulink Model Coverage" on page 4-37
- "Using Simulink[®] Design Verifier Data Files in a Test" on page 4-44
- "Using Signal Builder Block Test Cases in a Test" on page 4-45

Note In Simulink elements, you cannot have more than one model with the same name. Each model referenced within a test must have a unique name. If you ran a test containing two models with the same name, the SystemTest software would only use one of the models.

Before You Begin

This chapter explains the Simulink setup by having you recreate the Simulink element that is part of the Inverted Pendulum demo. Before continuing, you should load this demo from MATLAB and delete the Simulink element from the demo.

The following steps describe how to do this:

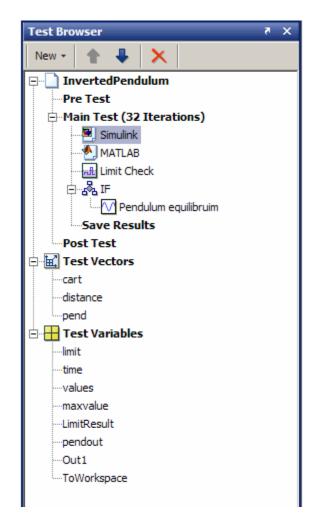
- 1 Start MATLAB.
- 2 Open the Inverted Pendulum demo.
 - **a** Select **Start > Demos** to open the Help browser.
 - **b** Expand the **MATLAB** list from the left frame of the browser.
 - **c** Select **SystemTest**. The SystemTest demos open in the right browser frame.
 - **d** Click "Simulink Mapping and Overriding Simulink Data Using an Inverted Pendulum Model." An overview of the demo opens.
 - Click the link "Open the demo in the SystemTest Desktop" at the bottom of the page.

Alternatively, you can enter the following command at the MATLAB command line:

systemtest InvertedPendulum

The SystemTest desktop opens with the Inverted Pendulum demo loaded.

3 Click the Simulink element in the Test Browser.



4 Click the **Delete element** button in the Test Browser button bar or press the **Delete** key.

Mapping Test Vectors and Test Variables to a Simulink Model

In this section...

"Introduction" on page 4-4

"Adding a Simulink Element" on page 4-5

"Specifying the Simulink Model" on page 4-6

"Overriding Simulink Model Inputs" on page 4-6

"Mapping Simulink Model Outputs to Test Variables" on page 4-12

"Using the Model Output Mappings Assistant" on page 4-19

"Editing a Test Vector or Test Variable from within the Element" on page 4-20

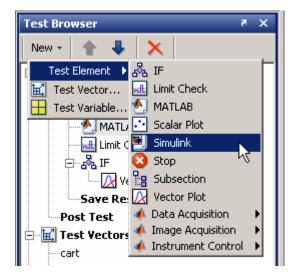
Introduction

To help you learn how to use the Simulink element, this section walks you through the configuration of the Simulink element for the Inverted Pendulum test. The Inverted Pendulum demo includes both a model of the pendulum and a model of a controller that keeps the inverted pendulum balanced. Moving the bottom of the pendulum disturbs the equilibrium, causing the pendulum to move and the controller to rebalance it. The Inverted Pendulum test varies the mass of the pendulum, the mass of the cart the pendulum is on, and the distance to the pendulum's center of mass, testing the robustness of the controller as it attempts to return the pendulum to equilibrium. Using the Simulink element in a test lets you vary the model inputs and assess the model outputs.

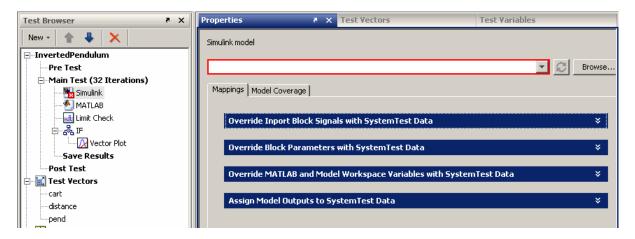
Note The following sections assume you have loaded the Inverted Pendulum demo and deleted the Simulink element, as explained in "Before You Begin" on page 4-2.

Adding a Simulink Element

To add a Simulink element to a test, click the **New > Test Element** button in the **Test Browser** and select the Simulink element. If you have a license for Simulink, the element list contains the Simulink element, as shown in the following figure.



The SystemTest software adds the Simulink element to the test and opens the Simulink element **Properties** pane.



Specifying the Simulink Model

When you first add the element, the icon in the **Test Browser** has a red x, meaning that the element requires some information. The **Simulink model** field in the Simulink element **Properties** pane is outlined in red, indicating that it is a required field. You must specify the model that the Simulink element will interact with. If the model is on the MATLAB path, you can type its name in the **Simulink model** field. If you are not sure of the name, or the model is not on the path, you can browse to its location using the browse button.

For the Inverted Pendulum example, type systemtestpendulum in the Simulink model field and press Enter. The SystemTest software opens the systemtestpendulum model in Simulink and opens the Pendulum Visualization window.

Overriding Simulink Model Inputs

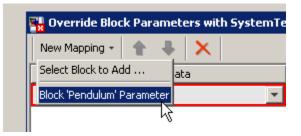
Using test vectors and test variables, you can override the following Simulink model inputs:

- Block parameters Described in "Overriding Simulink Block Parameters" on page 4-6
- Model and base workspace variables Described in "Overriding to Workspace Variables" on page 4-8
- Inport signals Described in "Overriding Simulink Model Inport Signals" on page 4-10

Overriding Simulink Block Parameters

You can override Simulink block parameters with SystemTest test vectors or test variables. When you run the test, Simulink runs the model using data provided by the SystemTest software. Overriding does not change your Simulink model file; it only overrides in the test. The procedure for creating block parameter overrides requires that you select your block in the Simulink model, but everything else you need to do happens within the Simulink element **Properties** pane. To override a Simulink block parameter:

- 1 In the **Mappings** tab of the **Properties** pane for the Simulink element in the SystemTest software, expand the **Override Block Parameters with SystemTest Data** section and click the **New Mapping** button, and select **Select Block to Add**. This opens the model in Simulink, if it is not already open.
- **2** In the Simulink model window, click the block containing the parameter you want to override. For this example, click the Pendulum block in the **systemtestpendulum** model window.
- **3** In the SystemTest software, return to the Simulink element **Properties** pane and, in the **Override Block Parameters** section, you'll see that the **Pendulum** was added. If you click the **New Mapping** button again, you'll see that the SystemTest software also adds an entry to this menu for the block.



In the override table, the **Simulink Data** field shows that this entry is linked to the Pendulum block but the question mark (?) indicates that no parameter for the block has been mapped.

🙀 Override Block Parameters with SystemTe	est Data (1) 🕺
New Mapping 🗸 🛔 🗼	
Simulink Data	SystemTest Data
Pendulum:?	-

- **4** Select the parameter from the block that you want to map. Click the **Simulink Data** field for the block and select a parameter from the list. For the Inverted Pendulum demo example, select Pendulum:Mass of cart (kg).
- **5** Specify the SystemTest test vector or test variable you want to map to this block parameter. Click the **SystemTest Data** field for the block parameter. This shows you all defined SystemTest test vectors and test variables available for mapping. For this example, select **cart**.

🙀 Override Block Parameters with SystemTe	est Data (1) 🛛 🔅
New Mapping 👻 🛖 🐥 🗙	
Simulink Data	SystemTest Data
Pendulum:Mass of cart (kg)	•
	maxvalue st_loggedsignal st_outportsignal st_toworkspace LimitResult pend
	cart distance

Overriding to Workspace Variables

You can use a SystemTest test vector or test variable to override either a MATLAB base workspace variable or a Simulink model workspace variable. This lets you define test values and conditions in the SystemTest software and have a Simulink model act on them.

This section describes how you can use the values in the pend and distance test vectors to override the model workspace variables masspend and penddistance in the Inverted Pendulum demo. To override workspace variables:

- 1 Expand the **Override MATLAB and Model Workspace Variables with SystemTest Data** area of the Simulink element **Properties** pane, and click the **New Mapping** button.
- 2 Select the workspace variable you want to override. Click the **Simulink Data** field of this row to see all available base workspace variables and Simulink model workspace variables. For the Inverted Pendulum example, select **masspend**.

🙀 Override MATLAB and Model Workspace V	ariables with SystemTest Data (1) 🛛 🔅
New Mapping 👚 🐥 🗙	
Simulink Data	SystemTest Data
v	•
masscart (model workspace) masspend (model workspace) penddistance (model workspace) ans (base workspace)	

3 Specify which SystemTest test vector or test variable you want to map to the Simulink workspace variable. Click the **SystemTest Data** field of this row to see all available test vectors and test variables. For this example, select **pend**.

🙀 Override MATLAB and Model Workspace V	ariables with SystemTest Data (1) 🛛 🔗
New Mapping 🔺 🐥 🗙	
Simulink Data	SystemTest Data
masspend (model workspace)	•
	maxvalue st_loggedsignal st_outportsignal st_toworkspace LimitResult
	pend cart distance

4 Repeat steps 1 to 3 to override the Simulink model workspace variable penddistance with the SystemTest test vector distance.

Override MATLAB and Model Workspace Variables with SystemTest Data (2)			*
New Mapping 🔒 👢 🗙			
Simulink Data		SystemTest Data	
masspend (model workspace)	•	pend	•
penddistance (model workspace)	•	distance	•

Overriding Simulink Model Inport Signals

As with block parameters and workspace variables, you can use the SystemTest software to override a model's inport signals. This lets you externally manipulate the input signal of a Simulink model.

The Inverted Pendulum demo example does not override any inport signals.

For information on how to override inport signals and an example, see "Overriding Inport Block Signals" on page 4-21.

Optimizing Test Vectors to Work with Inport Signals

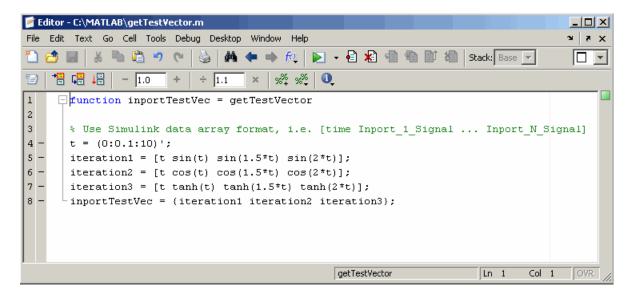
Simulink allows you to import input signal and initial state data from the MATLAB workspace and export output signal and state data to the MATLAB workspace during simulation. In the SystemTest software, you can specify the contents of a test vector so that it is used as a Simulink inport. To do that, use the vector as the mapping in your Simulink element, by selecting it in the **SystemTest Data** row as described above.

The Simulink documentation contains guidance on importing data to Simulink inport signals. You can create the same type of data in your SystemTest test vectors that you then map to inport signals. For more information on appropriate data types, see Importing and Exporting Simulation Data in the Simulink documentation.

Example for Overriding Inport Signals Using Data Arrays

One of the data formats described in Importing and Exporting Simulation Data in the Simulink documentation is the use of data arrays for specifying input data to an Inport block. This example uses the systemtestinputdemo.mdl model to illustrate how the SystemTest software can be used to override the three Inport blocks in the model with test signals.

The first step involves constructing a test vector that specifies the different signal test cases. This can be done by creating a MATLAB function that simply returns a test vector containing the different test cases you would like to use for each test iteration. A sample MATLAB function, called GETTESTVECTOR, that does this is provided below.



Once this function is saved as GETTESTVECTOR, you can create a SystemTest test vector whose expression is set to GETTESTVECTOR. This will create a 1-by-3 test vector cell array within the SystemTest software, where each entry in the cell array represents the time and signal data for the three Inport blocks.

For detailed information on the Simulink data array format, or other formats supported by Simulink Inport blocks, see Importing and Exporting Simulation Data in the Simulink documentation.

Mapping Simulink Model Outputs to Test Variables

Using test variables you can assign the output from the following types of Simulink model data:

- Logged signals Described in "Mapping Simulink Logged Signals to Test Variables" on page 4-13
- Outport signals Described in "Mapping Simulink Outport Signals to Test Variables" on page 4-15
- To Workspace blocks Described in "Mapping Simulink To Workspace Blocks to Test Variables" on page 4-17

After you map model outputs to test variables, you can incorporate the model data into the SystemTest software. This section shows you how to map this data for the Inverted Pendulum example.

Note The output from Simulink models can only be mapped to SystemTest test variables. You cannot map this output to SystemTest test vectors.

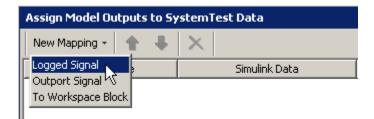
Note If you are mapping logged signals, outport signals, or To Workspace blocks to test variables, as shown in the following procedures, then you can optionally use the Mappings Assistant if you want the variables to have the same names as the inputs. This is useful if your model contains many signals or blocks and you want to name the outputs the same way. You no longer have to create test variables with matching names manually. See "Using the Model Output Mappings Assistant" on page 4-19 for more information.

Mapping Simulink Logged Signals to Test Variables

Logged signals are a way to obtain outputs from a model without adding more outports. Using logged signals, you can identify a particular signal and map the output to a SystemTest test variable.

To map logged signals to a SystemTest test variable:

 Expand the Assign Model Outputs to SystemTest Data section of the Simulink element Properties pane, and click the New Mapping button. From the list, select Logged Signal. The SystemTest software adds a row for a new mapping of this type.



2 Specify the signal you want to capture. Click the **Simulink Data** field to see all the signals in the model. For the Inverted Pendulum example, select **pendout**.

Note If you added logged signals to your model and they do not appear in this list, click the refresh button, on the **Properties** pane next to the model name, to update the list.

📲 Assign Model Outpul	s to SystemTest Data (1)	*
New Mapping 👻 🛖	↓ ×	
Mapping Type	Simulink Data	SystemTest Data
Logged Signal	•	▼
	All signals pendout	

3 Specify the SystemTest test variable to which you want to map the output. Click the **SystemTest Data** field and select a test variable. For the Inverted Pendulum example, select st_loggedsignal.

🉀 Assign Model Outputs to SystemTest Data (1)				*
New Mapping 👻 👚 🚽	* ×			
Mapping Type	Simulink Data		SystemTest Data	
Logged Signal	pendout	•		-
			<new test="" variable=""> limit st_time values maxvalue st_loggedsignal st_outportsignal</new>	

Assign Model Outputs to SystemTest Data (1)		
↓ ×		
Simulink Data	SystemTest Data	
pendout 💌	st_loggedsignal	-
	Simulink Data	Simulink Data SystemTest Data

The SystemTest software creates the mapping to the test variable.

Note If you are mapping logged signals to test variables, as shown in the above procedure, then you can optionally use the Mappings Assistant if you want the variables to have the same names as the inputs. This is useful if your model contains many signals or blocks and you want to name the outputs the same way. You no longer have to create test variables with matching names manually. See "Using the Model Output Mappings Assistant" on page 4-19 for more information.

Mapping Simulink Outport Signals to Test Variables

The SystemTest software lets you map all outport signals to a test variable for further processing in the SystemTest software.

To map Simulink outport signals to a test variable:

- In the Assign Model Outputs to SystemTest Data section of the Simulink element Properties pane, click the New Mapping button. From the list, select Outport Signal. The SystemTest software adds a row for a new mapping of this type.
- **2** Specify the outport signal you want to capture. Click the **Simulink Data** field and select a signal. For this example, select **Out1**.

🉀 Assign Model Outputs to SystemTest Data (2)				*
New Mapping 👻 🛖	₽ X			
Mapping Type	Simulink Data		SystemTest Data	
Logged Signal	pendout	•	st_loggedsignal	•
Outport Signal		-		-
	All signals Out1			

3 Specify the SystemTest test variable to which you want to map the outport signals. Click the **SystemTest Data** field and select a test variable from the list. For this example, select **st_outportsignal**.

The SystemTest software creates the mapping to the test variable.

Assign Model Outputs to SystemTest Data (2)					
New Mapping 👻 🛖 🐥					
Mapping Type	Simulink Data		SystemTest Data		
Logged Signal	pendout	•	st_loggedsignal	•	
Outport Signal	Out1	•	st_outportsignal	•	

Note If you are mapping outport signals to test variables, as shown in the above procedure, then you can optionally use the Mappings Assistant if you want the variables to have the same names as the inputs. This is useful if your model contains many signals or blocks and you want to name the outputs the same way. You no longer have to create test variables with matching names manually. See "Using the Model Output Mappings Assistant" on page 4-19 for more information.

Mapping Simulink To Workspace Blocks to Test Variables

When Simulink runs a model with To Workspace blocks, these blocks save model information in the MATLAB workspace as variables. Using the SystemTest software, this data can be mapped to SystemTest test variables.

This section shows how you create To Workspace block mappings in the SystemTest software using the Inverted Pendulum demo as an example.

To map the To Workspace block:

- In the Assign Model Outputs to SystemTest Data section of the Simulink element Properties pane, click the New Mapping button. From the list, select To Workspace Block. The SystemTest software adds a row for a new mapping of this type.
- **2** Specify the To Workspace block in the model that you want to capture. Click the **Simulink Data** field and select the block from the list. For this example, select **To Workspace**.

🎇 Assign Model Outputs to SystemTest Data (3)				
New Mapping 👻 🛖	↓ ×			
Mapping Type	Simulink Data		SystemTest Data	
Logged Signal	pendout	•	st_loggedsignal	•
Outport Signal	Out1	•	st_outportsignal	•
To Workspace Block		•		-
	To Workspace To Workspace1			

3 Specify the SystemTest test variable to which you want to map the To Workspace block. Click the **SystemTest Data** field and select a test variable from the list. For this example, select **New Test Variable** to create a test variable.

🙀 Assign Model Outputs to SystemTest Data (3)				
New Mapping - 🔒 🗙				
Mapping Type	Simulink Data		SystemTest Data	
Logged Signal	pendout	▼	st_loggedsignal	•
Outport Signal	Out1	▼	st_outportsignal	•
To Workspace Block	To Workspace	•		-
			<new test="" variable=""> limit st_time values maxvalue st_loggedsignal st_outportsignal</new>	•

The SystemTest software opens the Edit Variable dialog box. Assign a name to the test variable and optionally an initial value, and then click **OK**. Name the test variable ToWSResult.

ToWSResult	
nitial value	
Assigned in	
Main Test	

The SystemTest software creates the mapping to the new test variable and adds the new test variable to the list in the **Test Variables** pane.

New Mapping 👻 🛖	+ X			
Mapping Type	Simulink Data		SystemTest Data	
Logged Signal	pendout	•	st_loggedsignal	-
Outport Signal	Out1	-	st_outportsignal	-
To Workspace Block	To Workspace	-	ToWSResult	-

Note If you are mapping To Workspace blocks to test variables, as shown in the above procedure, then you can optionally use the Mappings Assistant if you want the variables to have the same names as the inputs. This is useful if your model contains many signals or blocks and you want to name the outputs the same way. You no longer have to create test variables with matching names manually. See "Using the Model Output Mappings Assistant" on page 4-19 for more information.

Using the Model Output Mappings Assistant

If you are mapping logged signals, outport signals, or To Workspace blocks to test variables, for example in the procedures in the above section "Mapping Simulink Model Outputs to Test Variables" on page 4-12, then you can optionally use the Mappings Assistant if you want the variables to have the same names as the inputs. This is useful if your model contains many signals or blocks and you want to name the outputs the same way. You no longer have to create test variables with matching names manually. Using the Mappings Assistant is the preferred method of setting up mappings since it is easier.

- 1 In the Assign Model Outputs to SystemTest Data section of the Simulink element, click the Mappings Assistant button above the table.
- **2** In the Model Output Mappings Assistant dialog box, choose your mapping(s) in the **Create mappings for each** section.

- If your model contains any logged signals, the **Logged Signals** option is available. Select the option to map the logged signal(s) to test variable(s). If the model contains no logged signals, this option is disabled.
- If your model contains any outport signals, the **Outport Signals** option is available. Select the option to map the outport signal(s) to test variable(s). If the model contains no outport signals, this option is disabled.
- If your model contains any To Workspace blocks, the **To Workspace Blocks** option is available. Select the option to map the block(s) to test variable(s). If the model contains no To Workspace blocks, this option is disabled.
- 3 Click OK to create the mappings.

The **Simulink Data** column then displays the names of the logged signals, outports, or To Workspace blocks that the model contained. The **SystemTest Data** column displays the test variables created with the same name.

For example, if the model contains two outports called Out1 and Out2, the Simulink Data column displays Out1 and Out2, and the SystemTest Data column displays Out1 and Out2 to represent the test variables that were created.

Editing a Test Vector or Test Variable from within the Element

If you want to edit a test vector or test variable while working in the Simulink element, you can open the appropriate editor by right-clicking on the name of the test vector or test variable in any of the tables on the **Mappings** tab.

Overriding Inport Block Signals

In this section...

"Introduction" on page 4-21

"Overriding Inport Block Signals in a Simulink Element" on page 4-22

"Using the Inport Block Mappings Assistant" on page 4-26

"Example: Overriding Simulink Inport Blocks Using a Spreadsheet Data Test Vector" on page 4-27

"Mapping Logged Signals from a Model to Inport Blocks" on page 4-35

"Editing a Test Vector or Test Variable from within the Element" on page 4-36

Introduction

The examples in "Mapping Test Vectors and Test Variables to a Simulink Model" on page 4-4 described how to override block parameters and workspace variables. Similarly, you can override signals to root-level Inport blocks in Simulink with SystemTest data.

Because the Simulink element uses the Inport block names, not the port numbers, your test works even if you reorder the Inport blocks in the model.

Some users store signal values in a Microsoft Excel spreadsheet or .csv file. You can create a test vector that reads values from a spreadsheet and use that as your Inport block signal mapping. The "Example: Overriding Simulink Inport Blocks Using a Spreadsheet Data Test Vector" on page 4-27 section shows such a scenario.

You can also store signal values in a MAT-file and then create a test vector that reads the values from the MAT-file. The "Mapping Logged Signals from a Model to Inport Blocks" on page 4-35 section shows this scenario.

Overriding Inport Block Signals in a Simulink Element

To override Inport block signals:

- 1 If you have a model that contains Inport blocks and you have created a Simulink element that uses that model, click the **Mappings** tab inside the Simulink element.
- **2** Expand the **Override Inport Block Signals with SystemTest Data** section by clicking the expander arrow on the right side of the section title.
- **3** Designate your mappings.

The user interface indicates how many Inport blocks your model contains. For example, the model used in the Simulink Input demo contains three Inport blocks, as shown here. You can open this demo by typing the following in the MATLAB command line:

systemtest SimulinkInputDemo1

Mappings Model Coverage							
Override Inport Block Signals with SystemTes	st Data 🏾 🛠						
The model contains 3 Inport block(s).							
\odot Do not override Inport block signals. (Use Inport signals defined by the model)							
All Inport blocks are mapped using: InputSign	al 💌						
C Individual Inport blocks are mapped using:							
Inport Block Name	SystemTest Data						
Ini	Inherit from model						
In2	Inherit from model						
In3	Inherit from model						
Define test signal time:							
Map test signal time to:							
C Manually specify a time step: 0.01							
To calculate end time of simulation:							
Ouse model stop time							
C Use signal's end time							

The first option, **Do not override Inport block signals**, is selected by default. That means the test will run the model without modifying any Inport block settings. Any data the Inport blocks are configured to use will be used during execution. If you want to override the model, use one of the other two options.

The **All Inport blocks are mapped using** option allows you to map data to all Inport blocks at once. Use the drop-down list to choose an existing test vector or test variable, or to create a new one. This supports any data format the Simulink model supports. For example, it could be a test vector that is an array of time and three signal values, such as [time, U1, U2, U3].

If you want to map individual Inport blocks, select the **Individual Inport blocks are mapped using** option.

Мар	pings Model Coverage								
	Override Inport Block Signals with Syste	mTest Data (individually)	*						
	The model contains 3 Inport block(s).								
	O Do not override Inport block signals. (Use Inport signals defined by the model)								
	C All Inport blocks are mapped using: InputSignal								
	Individual Inport blocks are mapped using:								
	Inport Block Name	SystemTest Data							
	In1	InputSignal	▼						
	In2	st_signal	•						
	In3	Inherit from model	▼						
	Define test signal time:								
	C Map test signal time to:		-						
	Manually specify a time step: 0.	01							
	To calculate end time of simulation:								
	Use model stop time								
	C Use signal's end time (based on a	time step of 0.01)							

When you select this option, the mapping table becomes editable. In the case shown here, In1 and In2 are being overridden with SystemTest data, and In3 is using the value in the model.

The table displays all Inport blocks contained in the model. By default, the **SystemTest Data** column is assigned as **Inherit from model**. This is especially convenient if you have a large number of Inport block signals and only want to override a small number of them in your test. You would just change the **SystemTest Data** column value for the ones you want to override.

You can update the list of Inport blocks that are displayed in the table by clicking the **Open and update model state** button in the Simulink element. The Inports listed in the table are sortable.

Note If you open a TEST-File and do not see the Inport blocks from your model reflected in the Simulink element, click the **Open and update model state** button:



to populate the Inport table.

Note If you have variables in a Spreadsheet Data test vector or a MAT-File test vector, you can optionally use the Mappings Assistant. Click the **Mappings Assistant** button above the table. For more information on using the Mappings Assistant, see "Using the Inport Block Mappings Assistant" on page 4-26.

4 If you are using the map all option or individual mappings, you need to define the test signal time and the end time. If you are using the inherit from model option, skip this step since the time options do not apply to inherited mappings.

In the **Define test signal time** option, you can specify the simulation time signal to provide to the model. To specify the time signal using a test vector or test variable, select **Map test signal time to**. To specify a time signal based on a desired simulation time step, select **Manually specify a time step** and then enter a valid time step, which must be a positive number.

In the **To calculate end time of simulation** option, either use the model's stop time, or use the signal's end time based on the time step you specified. The **Use model stop time** option stops the simulation of the model at the end time configured in the model. The **Use signal's end time** option stops the simulation of the model at the end of the test signal, temporarily overriding the end time of the model with the test signal end time.

Note The **Define test signal time** option and the **To calculate end time of simulation** option are disabled if all individual Inport mappings are set to inherit from the model.

Using the Inport Block Mappings Assistant

If you are overriding Inport block signals, as shown in "Overriding Inport Block Signals in a Simulink Element" on page 4-22, then you can optionally use the Mappings Assistant when you use the **Individual Inport blocks are mapped using** option.

- 1 When overriding Inport block signals, select the **Individual Inport blocks are mapped using** option.
- **2** Click the **Mappings Assistant** button above the table. This button is only available when you are configuring individual mappings.
- **3** In the Inport Block Mappings Assistant dialog box, choose your mapping in the **Override each Inport block using** section.
 - If you are using a Spreadsheet Data test vector, select the **A spreadsheet test vectors headers** option. Then in the drop-down list, select an existing Spreadsheet Data test vector, or create a new one.
 - If you are using a MAT-File test vector, select the **A MAT-File test vectors selected variables** option. Then in the drop-down list, select an existing MAT-File test vector, or create a new one.
 - If you have a test variable whose name matches the Inport block, select the **An existing test variable with a matching name** option.
- **4** The **If an Inport block name cannot be matched** section determines what happens in the case of one or more variables in the selected test

vector not matching an Inport block name. Select the option you want the Simulink element to perform. **Inherit from Model** is the default.

5 The **Summary** section displays information on how many root-level Inport blocks are found in the model, how many are mapped to the test vector you selected if you are mapping from a test vector, and how may will use the option you chose in step 4 in the case of non-matches.

When you are finished configuring the mappings and viewing the summary, click **OK** to create the mappings.

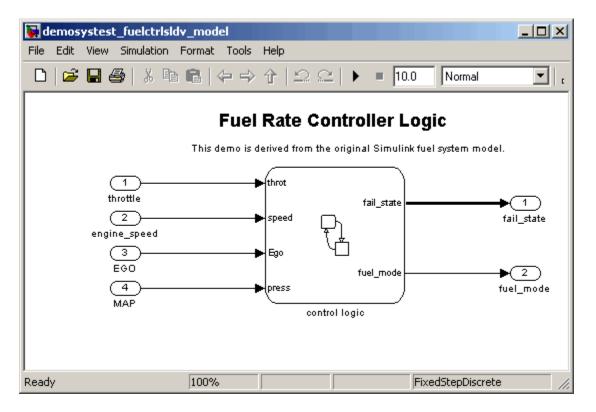
The mappings are then displayed in the table.

Example: Overriding Simulink Inport Blocks Using a Spreadsheet Data Test Vector

In this example, a Simulink element is being used to test a model of a fuel rate controller. To see the test and the model, open the demo by typing the following at the MATLAB command line:

```
systemtest('demosystest_fuelctrlsldv.test');
```

The model has four Inport blocks that represent throttle angle, engine speed, exhaust gas, and manifold pressure.



The tester has values for these four blocks in a Microsoft Excel spreadsheet. It contains 37 sets of generated values for the blocks. Each set of values is on a different sheet within the spreadsheet, representing a testing scenario for the model. One of the sheets is shown here.

	A	A B		D	E
1	Time	throttle	engine spe	EGO	MAP
2	0	0	0	0	0
3	0.01	4	0	1.4	0.002
4	0.02	4	629	1.4	0.002
5	0.03	91	0	0	1
6	0.04	3	0	0	2
7	0.05	4	1	0	0.002
8	0.06	4	1	1.4	1
9	0.07	90	0	1.4	0.002
10	0.08	90	0	1.4	0.002

Column A represents the simulation time signal. Columns B through E represent test data for the four Inports in the model. Each of the 37 sheets is set up the same way but contains different values.

To set up the test vector that reads the data from the spreadsheet:

- 1 Create the test vector by clicking the **New** button in the **Test Vectors** pane.
- **2** In the Insert Test Vector dialog box, select **Spreadsheet Data** as the vector type.
- **3** On the **General** tab, name the test vector **InputSignal**.
- 4 Click the Add File button and browse to the Microsoft Excel spreadsheet.

Insert Test Vector	
Insert Test Vector Select Test Vector type: MATLAB Expression Probability Distribution Signal Builder Block Simulink Design Verifier Data File Spreadsheet Data	General Data Selection String Replacement Grouping Name: InputSignal Type: Spreadsheet Data Files to Read Remove File Select All Clear Al Remove File Select All Clear Al Sheet1 Sheet2 Sheet3 Sheet4 Sheet5 Sheet5 Sheet10 Sheet10 Sheet11 Sheet10 Sheet11 Sheet10 Sheet11 Sheet10 Sheet11 Sheet11 Sheet13 Sheet13 Sheet14 Sheet15 Sheet15 Sheet16 Sheet16 Sheet17
	Test Vector successfully evaluated to a 1x210 cell array Evaluate Test Vector each time the test is run
	OK Cancel

- **5** Click the **Select All** button to select all sheets in the spreadsheet file.
- **6** On the **Data Selection** tab, keep the default of **column** in the **Data is arranged by** option.
- 7 In the Read data from column option, enter A to E, starting at row 1.

- **8** Select the **First row is a header** option, since you can see in the above figure of the spreadsheet that row 1 of the file contains text labels.
- 9 Select the Treat each selected sheet as a test vector value option.

The configured test vector appears as follows.

📣 Insert Test Vector		×						
Select Test Vector type: MATLAB Expression Probability Distribution Signal Builder Block Simulink Design Verifier Data File Spreadsheet Data	ATLAB Expression Obta Range Data Range Data is arranged by Column							
	For Each Selected Sheet:							
	A B C Gain 1 1 1 1.1 0.9 0.9 Simulink Parameter MATLAB Vector							
	Treat each selected sheet as a test vector value							
	$Ex: \begin{bmatrix} A & B & C \\ t & u1 & u2 \\ .1 & 0 & 1 \\ .2 & 1 & 0 \\ .3 & 0 & 1 \\ & & \end{bmatrix} or \begin{bmatrix} A & B & C \\ Data \\ 8 & 6 & 1 \\ .3 & 7 & 5 \\ 4 & 2 & 9 \\ & & \end{bmatrix}$							
	Simulink Signals MATLAB Matrix							
	ОК С	ancel						

10 Click **OK** in the Insert Test Vector dialog box.

The new vector appears in the table in the **Test Vectors** pane. You can see that the length is 37 because there are 37 sheets in the spreadsheet file and each sheet is being treated as one value in the vector.

Properties	Test Vectors	× 5	Test ¥ariables
New 👚 🖊 🕽	X Evaluate		
Name	Length	Grouped	Туре
InputSignal	37		Spreadsheet Data
	n String Replacement	Groupipa	<u> </u>
	· ·		
Name: InputSi			
Type: Spreads	sheet Data		
Files to Read			
Add File(s)		🗙 Remove File	Select All Clear All
	uments\SystemTest\sign		
			-1

Now that the test vector is set up, you can set up the Simulink element to override the Inport blocks using the test vector values from the underlying spreadsheet file.

- 1 Create a Simulink element by clicking New > Test Element > Simulink button in the Test Browser.
- 2 Click the browse button to locate the Fuel Rate Controller model.
- **3** On the **Mappings** tab, expand the **Override Inport Block Signals with SystemTest Data** section if it is not open.
- **4** Select the **Individual Inport blocks are mapped using** option. The four Inport blocks appear in the table.
- **5** For each Inport block, use the drop-down list in the **SystemTest Data** column to override the Inport block with the appropriate data in the test vector that was created earlier.

For example, for throttle, click the drop-down list, expand the InputSignal test vector entry, and select throttle. Do the same for the other three signals.

The entries under the InputSignal test vector represent the underlying columns in the spreadsheet. Since the Spreadsheet Data test vector called InputSignal was created using the columns and the headers, the columns appear named with their headers in the list for easy identification, for example, InputSignal(throttle).

6 In the **Define test signal time** option, select **Map test signal time to** and choose InputSignal(Time).

Time is the first column in the spreadsheet and contains the simulation time signal for the model. The test will use these time step values when the Simulink element is executed.

7 Select the **Use signal's end time** option, so that the end times provided in the spreadsheet are used.

The configured Simulink element appears as follows.

Properties	× s	Test Vectors	Test Variables	
	el ts\SystemTest\signals_ t_fuelctrisidv_model	test\demosystest_fi	uelctrisidv_model.mdi	Browse
Overn	Model Coverage ide Inport Block Sig iodel contains 0 Inport		Test Data (individually)	*
04	oo not override Inport l NI Inport blocks are maj ndividual Inport blocks	oped using:	port signals defined by the model)	y
	Inport Bl	ock Name	SystemTest Data	
	throttle		InputSignal (throttle)	–
	engine_speed		InputSignal (engineSpeed)	–
	EGO		InputSignal (EGO)	–
	MAP		InputSignal (MAP)	
) Define test signal time:			
	 Map test signal 	time to: Inpu	tSignal (Time)	–
	C Manually specif ⁴	y a time step: 0.01		
	To calculate end time o O Use model stop O Use signal's end		utSignal (Time))	
	ide Block Paramete ide MATLAB and Mo		st Data ariables with SystemTest Data	*
Assig	n Model Outputs to	SystemTest Data		*

When the test is executed, the Simulink element will test the model using the Inport block signals mapped from the spreadsheet.

Mapping Logged Signals from a Model to Inport Blocks

You can map logged signals from a Simulink model, including bus signals, to Inport blocks of a model using the Simulink element and a test vector or test variable that contains the logged signal data.

A common usage scenario is to log the signals while running a model and store them in a MAT-file. Then you can acquire them from the Mat-file using a MAT-File test vector and map that data to Inport blocks in the Simulink element. The following high-level steps outline this usage scenario.

1 Do one of the following:

Run your model that contains signals. The signals are logged as variables in the MATLAB workspace. Save the variables as a MAT-file.

OR

Alternatively, use MAT-file(s) that have already been created and saved.

- **2** In the SystemTest software, create a MAT-File test vector using the MAT-file that your signals are saved in. See "Creating MAT-File Test Vectors" on page 2-13 for more information on MAT-File test vectors.
- **3** Add a Simulink element to your test, and select the model that you want to test.
- **4** In the **Override Inport Block Signals with SystemTest Data** section, select the **All Inport blocks are mapped** option.
- **5** From the drop-down list, select the MAT-File test vector you created, and drill down into the variable that represents the signal you want to use. This is how you map the logged signals to the Inport blocks.

Note that the logged signal(s) and the Inport block(s) must have exactly the *same* name(s) for the Simulink element to simulate the model successfully. See the usage notes below.

6 Run the test.

Important Usage Notes

- The logged signal(s) and Inport block(s) must have identical names that match exactly. To use this feature, each Inport block name must match a corresponding signal name within the logged data. If it does not, you can rename the Inport block or the signal in the logged data to avoid an error. You can have other signals in the logged data, but each Inport block must exactly match a signal name.

- The following data types are supported:
- Simulink.Timeseries.
- Simulink.TsArrays.
- Simulink.SubsysDataLogs.

Editing a Test Vector or Test Variable from within the Element

If you want to edit a test vector or test variable while working in the Simulink element, you can open the appropriate editor by right-clicking on the name of the test vector or test variable in any of the tables on the **Mappings** tab.

Using Simulink Model Coverage

The model coverage feature provided by the Simulink Verification and Validation software allows you to generate coverage analysis metrics for a Simulink model, which can be incorporated directly into your SystemTest test. Model coverage metrics allow you to validate your model by identifying unexecuted subsystems, unselected switch positions, or untaken conditional transition paths. You can generate a cumulative coverage report, specify individual coverage options, or inherit a model's coverage settings.

Note To use the model coverage feature, you need a license for Simulink Verification and Validation.

The following basic steps describe the typical work flow to use this feature:

- Use an existing Simulink element or add one by clicking the New > Test Element button and selecting Simulink.
- **2** On the **Properties** pane, browse for your Simulink model using the browse button next to the **Simulink model** field.

To see an example, you can run the Signal Builder demo by typing systemtest demosystest_sigblder in MATLAB.

- **3** Configure the Simulink element as described in this chapter, using the **Mappings** tab of the **Properties** pane to define model overrides and map Simulink data to test variables.
- **4** On the **Model Coverage** tab, which appears if you have a license for the Simulink Verification and Validation software, select the **Enable model coverage** check box. The following figure shows the Signal Builder demo.

Simulink model C:\MATLAB\systemtestsfcar.mdl systemtestsfcar Mappings Model Coverage ✓ Enable model coverage ✓ Inherit coverage metric sel ✓ Override model coverage n Inherited Coverage Metrics ☐ Coverage for this model: / Coverage for referenced All referenced models	systemtestsfcar Select Subsystem models		× C	Browse
systemtestsfcar Mappings Model Coverage ✓ Enable model coverage ● Inherit coverage metric set ● Override model coverage n Inherited Coverage Metrics □ Coverage for this model: / □ Coverage for referenced	systemtestsfcar Select Subsystem models]	<u></u>	Browse
systemtestsfcar Mappings Model Coverage ✓ Enable model coverage ● Inherit coverage metric set ● Override model coverage n Inherited Coverage Metrics □ Coverage for this model: / □ Coverage for referenced	systemtestsfcar Select Subsystem models			Browse
Enable model coverage Inherit coverage metric set Override model coverage netrics – Inherited Coverage Metrics – Coverage for this model: Coverage for referenced	systemtestsfcar Select Subsystem models]		
Enable model coverage Inherit coverage metric set Override model coverage netrics – Inherited Coverage Metrics – Coverage for this model: Coverage for referenced	systemtestsfcar Select Subsystem models]		
Inherit coverage metric sel Override model coverage n Inherited Coverage Metrics Coverage for this model: / Coverage for referenced	systemtestsfcar Select Subsystem models]		
Override model coverage n Inherited Coverage Metrics Coverage for this model: Coverage for referenced	systemtestsfcar Select Subsystem models]		
Inherited Coverage Metrics	systemtestsfcar Select Subsystem models			
Coverage for this model: /	Select Subsystem]		
/	Select Subsystem]		
	models]		
	models			
All referenced models a				
	Select Models			
Coverage Metrics	_	_		
Decision Coverage		Condition Covera		
MCDC Coverage	F.	Look-up Table Co	overage	
Signal Range Coverage				
Map Coverage Data to Test Var	ables			
New Mapping +				
	~			
Coverage Path	Metric		SystemTest Da	ita 👘

5 If you want to use the model coverage settings you already have on the Simulink model, select the Inherit coverage metric settings from the model option. Then go to step 11.

- 6 If you want to override the existing settings, select the Override model coverage metric settings option.
- 7 Select Coverage for this model: <modelname>.

Mappings Model Coverage							
Enable model coverage							
O Inherit coverage metric settings from the model							
Override model coverage metric settings							
Overridden Coverage Metrics							
Coverage for this model: systemtestsfcar							
Select Subsystem							
Coverage for referenced models							
All referenced models are included							
Select Models							
Coverage Metrics							
✓ Decision Coverage ✓ Condition Coverage							
MCDC Coverage Vok-up Table Coverage							
Signal Range Coverage							

8 Click the Select Subsystem button in the Overridden Coverage Metrics section to specify the root of your coverage data.

📣 System Selector		×					
Image: System test. Image: System tes	ld Calcula puts ogic(State						
•	OK Cancel						

9 If you have one or more referenced models and you want coverage for them, select the **Coverage for referenced models** option.

Then click the **Select Models** button to select the referenced model(s) for coverage. Make your selection in the Select Models for Coverage Analysis dialog box and click **OK**.

Note that you can record coverage only for referenced models that operate in Normal mode. You cannot enable coverage for referenced models operating in Accelerated mode.

10 In the **Coverage Metrics** area, select the types of coverage your test requires. The selected coverage types will be generated and shown in the coverage report.



- 11 Use the Map Coverage Data to SystemTest Variables field to map coverage metrics to test variables. Click New Mapping and select Full Coverage Instrumentation Path if you want coverage data below the root you specified under Coverage for this model, or select Select Path to Map if you want to pick an alternate coverage path, which must be within the coverage instrumentation path. If you select the latter, your Simulink model will open and you can select a block to specify an alternate root for your coverage path.
- 12 Select the Metric you want to map to a test variable, and specify the test variable to use under the SystemTest Data column.

-Map Coverage Data to SystemTest Variables		
New Mapping 👻 👔 👫 📑		
Coverage Path	Metric	SystemTest Data
systemtestsfcar/Threshold Calculation/interp_down	Look-up Table Coverage 💌	coverage 🗾

Note that if you select <**New Test Variable**> in the **SystemTest Data** column, the default name will match the input. For example, if the model name is systemtestpendulum from the **Coverage Path** column, and the metric you select in the **Metric** column is MCDC Coverage then the default name for the new variable would be systemtestpendulum_mcdcinfo. The logical default name reflects the name of the model and the metric. You can use the default name or change it.

13 Run your test.

14 View the coverage report by clicking the link in the Run Status pane.

Run Status	7 X Getting Started	Desktop Help
Generated Files		
The following files were genera	ted in CA	
Open	Filename	
Model Coverage Report generated by Run the model	SignalBuilderDemo14962053.cvt	
Test Results Viewer	SignalBuilderDemo_results.mat	
Test Report	SignalBuilderDemo_report\SignalBuilderDemo	o_report.html
Final Tast Status		
Final Test Status		
Property	Value	
Property Start Time	05-Jul-2007 14:00:34	
Property Start Time Stop Time	05-Jul-2007 14:00:34 05-Jul-2007 14:00:51	
Property Start Time Stop Time Iterations Completed	05-Jul-2007 14:00:34 05-Jul-2007 14:00:51 4	
Property Start Time Stop Time	05-Jul-2007 14:00:34 05-Jul-2007 14:00:51	
Property Start Time Stop Time Iterations Completed	05-Jul-2007 14:00:34 05-Jul-2007 14:00:51 4	
Property Start Time Stop Time Iterations Completed	05-Jul-2007 14:00:34 05-Jul-2007 14:00:51 4 Completed Successfully	

For more information on the model coverage feature, see "Using Model Coverage" in the Simulink Verification and Validation documentation.

Edit View Go) De	bug Desktop	Window Help					
• C 🖨	#	Location: C:/	TEMP/SignalBuild	lerDemo_result:	s14962053.html		•	
Summary D	etails	E Signal R	anges <u>He</u> l	p				
ummary								
Model								
ierarchy/Comple	xity:		Те	est 1				
		D1	C1	MCDC	TBL	D1	C1	
<u>systemtestsfcar</u>	24	88%	67%	33%	31%	59%	33%	
<u>Engine</u>	0	NA	NA	NA	14%	NA	NA	
<u>Threshold</u> alculation	1	100%	NA	NA	20% -	100%	NA	
<u>shift_loqic</u>	22	87%	67%	33%	NA	58%	33%	
<u>SF:</u> if <u>t_logic_</u>	21	87%	67%	33%	NA	58%	33%	
<u>SF:</u> ar <u>state</u>	9	88%	NA	NA	NA	63%	NA	
<u>SF:</u> election_state	12	87%	67%	33%	NA	53%	33%	
<u>transmission</u>	0	NA	NA	NA	92%	NA	NA	
<u>Torque</u>	0	NA	NA	NA	95%	NA	NA	
) ansmission ratio	0	NA	NA	NA	60%	NA	NA	
etails:								
Model "syst	emto	estsfcar''						
Child Syster	ns:	Engir	ne, <u>Threshold</u>	Calculation,	<u>shift_logic, t</u>	ransmission		
Metric			verage (this			. descendants)		
Cyclomatic C				2	•			
Condition (C1	·	NA				dition outcomes		
Decision (D1) MCDC (C1))	NA NA			· · ·	cision outcomes itions reversed the o	utcomo	
						interpolation/extrapo		
Look-up Tabl	е	NA			ntervals			

Using Simulink Design Verifier Data Files in a Test

The Simulink Design Verifier Data File test vector can read test cases created by Simulink Design Verifier. In order to use this test vector, you must have a Simulink Design Verifier data file with test cases.

To use this feature, you first create a Simulink Design Verifier test harness and set the generate SystemTest harness option in the Configuration Parameters in Simulink. Then you can do one of two things:

- Generate a SystemTest harness for the model from Simulink. When it completes, a new test opens automatically in SystemTest and a Simulink Design Verifier Data File test vector is automatically created for you. A Simulink element is also automatically created, with links to the model, override mappings set, and model coverage enabled if your model uses that feature. This workflow is described in "Automatically Creating a SystemTest Test Harness from Simulink® Design Verifier" on page 2-53.
- If you already have a data file from Simulink Design Verifier, you can create a test vector in SystemTest that uses the data, and create a Simulink element and configure overrides in it. This workflow is described in "Creating a Simulink Design Verifier Data File Test Vector" on page 2-55.

Using Signal Builder Block Test Cases in a Test

If you use a Signal Builder block in a Simulink model, you can use the test cases in a SystemTest test.

The most common workflow for this feature is to create a Simulink element using the model containing the Signal Builder block, and create a Signal Builder Block test vector from within the element. For an example of this procedure, see "Creating Signal Builder Block Test Vectors" on page 2-67.

Using the Instrument Control Toolbox Elements

The Instrument Control Toolbox software provides several elements to use in the SystemTest software.

- "Introduction" on page 5-2
- "Example: Measuring a Generator's Frequency" on page 5-4

Introduction

In this section...

"Instrument Control Toolbox Elements" on page 5-2

```
"Accessing Resources" on page 5-2
```

Instrument Control Toolbox Elements

This chapter describes how to use the Instrument Control Toolbox elements with the SystemTest software.

The Instrument Control Toolbox elements provide a way to bring data from instruments into a SystemTest test, or to transmit data from your instrument. You can use these elements along with the other elements in the SystemTest software to create tests for Simulink models and other applications.

Note To use the Instrument Control Toolbox elements, you need a license for the Instrument Control Toolbox software. These three elements will not appear in the SystemTest software without this license.

The Instrument Control Toolbox software provides three of elements that you can use in the SystemTest software:

- To Instrument For sending commands or data to your instrument
- From Instrument For reading data from your instrument
- Query Instrument For querying your instrument status or properties

You can configure these elements to communicate with your instruments by using SystemTest resources supported by the Instrument Control Toolbox software.

Accessing Resources

If your MATLAB installation includes elements that require resources, the SystemTest desktop includes a **Resources** pane that lets you access the

resources available through these toolboxes. For example, if your MATLAB installation includes the Instrument Control Toolbox software, you can see the **Resources** pane, if you open it from the **Desktop** menu. Select **Desktop** > **Resources** to open the pane. It will tab with the **Test Vectors** and **Test Variables** on the lower-left corner of the desktop. Resources are toolbox-specific. For example, an Instrument resource might be configured to connect to a device over your computer's serial port.

Example: Measuring a Generator's Frequency

In this section	•
-----------------	---

"Introduction" on page 5-4

"Setting Up the Signal Generator" on page 5-5

"Setting Up the Oscilloscope" on page 5-9

"Taking the Measurement" on page 5-11

"Saving Test Results" on page 5-12

"Running the Test and Viewing Test Results" on page 5-13

Introduction

To illustrate how to use some of the Instrument Control Toolbox elements in the SystemTest software, this section provides a step-by-step example.

In this example a SystemTest element configures a signal generator to produce signals of various frequencies, which are measured by an oscilloscope configured by other SystemTest elements.

The signal generator is a Hewlett-Packard 33120A at GPIB address 5, and the oscilloscope is a Tektronix TDS 210 at GPIB address 4. For this example, the generator output is fed directly to the scope input. The generator will be programmed to generate signals of 1500, 5000, and 7500 Hz, while the oscilloscope will measure each signal's frequency.

The following sections explain the steps in this example.

Setting Up the Signal Generator

The first element in the test programs the generator to output signals of various frequencies. To test at three frequencies, the test be comprised of three test cases, i.e., three iterations. This is a one-way communication to the generator, so you use a To Instrument element.

- 1 Open the SystemTest software from MATLAB by selecting Start > MATLAB > SystemTest > SystemTest Desktop. You can also just type systemtest at the MATLAB command line.
- 2 When the SystemTest software opens, ensure that the Visualize and plot saved results by launching the Test Results Viewer check box is selected in the Properties pane.
- **3** No setup is required in the Pre Test, so the elements of this test are all in the main test, so click **Main Test** in the **Test Browser**.
- 4 Add an element by clicking New Test Element > Instrument Control > To Instrument.

Test Browser		
New - 👚 🐥	×	
👔 🛛 Test Element 🕨 💑	IF	
🔣 Test Vector 🛛 🖽	Limit Check	
🕂 🕂 Test Variable 🐁	MATLAB	
Save R 📑	Scalar Plot	
Post Test 関	Simulink	
🛛 🖃 Test Yecto 🙆	Stop	
Test Variat 🔡	Subsection	
	Vector Plot	
4	Data Acquisition 🔹 🕨	
4	Image Acquisition 🔹 🕨	
1	Instrument Control	🛃 From Instrument 👘
		🛃 Query Instrument 🛛
		📑 To Instrument
	-	1
		v

The element appears in the browser as To Instrument.

- 5 Double-click To Instrument, rename it Set Generator, and press Enter.
- **6** From the **Properties** pane's **Select an instrument resource** list, select New Instrument Resource. The instrument resource is the communication channel between MATLAB and your instrument, in this case the generator at GPIB address 5.
- 7 In the Edit: Instrument1 dialog box, enter Generator in the Name field.
- 8 Click Create to create an instrument resource.
- 9 In the New Object Creation dialog box, select GPIB in the Instrument object type list. Select the appropriate Vendor (in this example, ni for National Instruments), Board index (0), and instrument Primary address (in this example, 5).

📣 New Object Creati	ion		×
Define object			
Instrument object type:	GPIB		–
Configure object creati	on		
Vendor:	ni		•
Board index:	p		-
Primary address:	5		_
		ок	Cancel

10 Click **OK** to return to the Edit: Instrument1 dialog box, where the instrument object is now filled in and selected for this resource (GPIB0-5).

Editing: Instrument1	×
Name:	
Generator	
Instrument Object	
Select an instrument object for this res	source.
GPIB0-5	Create
	OK Cancel

- **11** Click **OK** to apply this resource and return to the **Properties** pane in the SystemTest desktop.
- 12 In the **Command text** field, enter frequency followed by a space to separate the text from the variable that will follow. This is the command to set the frequency of the 33120A generator, as described in the instrument's reference manual proved by the vendor.
- 13 Click Data source and select New Test Vector. The name of the vector you create for setting the generated frequencies is called genfreq. In the Insert Test Vector dialog box, enter that text in the Name field, and set the Expression field to [1500 5000 7500], including the brackets.

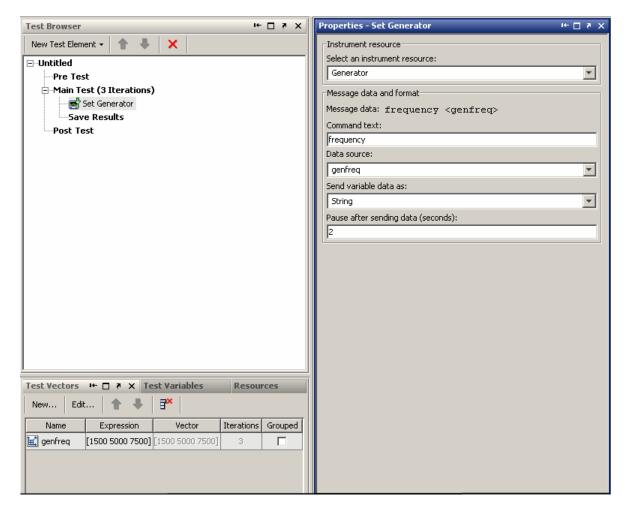
📣 Insert Test Vector	×
Insert Test Vector Select Test Vector type: MATLAB Expression Probability Distribution Spreadsheet Data	
	 OK Cancel

14 Click OK to return to the SystemTest desktop.

Notice that the **Main Test** node in the tree now says (3 Iterations). Because you entered three values in the test vector, the test is comprised of three iterations, one for each frequency value in the test vector.

- **15** Keep the **Send variable data as** setting as **String**. The generator is expecting string values for its commands.
- **16** Set a pause value of 2 seconds. This allows the generator to settle before you measure its output.

The element should now resemble the following figure:



Setting Up the Oscilloscope

You use a To Instrument element, which provides a one-way communication to the oscilloscope, to program the scope to measure frequency.

1 Add an element by clicking New Test Element > Instrument Control > To Instrument.

- **2** Double-click **To Instrument** in the tree, rename it **Set Scope**, and press Enter.
- **3** As before, create a new instrument resource, but this time call it **Scope**. Create a new instrument object for it using Board index 0, and GPIB primary address 4.
- **4** For the command text, enter measurement:immed:type frequency. This puts the scope in the frequency measurement mode, as described in the instrument's reference manual provided by the vendor.

There is no test variable or pause required for this element, so the element looks like the following figure:

📣 SystemTest - Untitled.test*	
File Run Tools Desktop Window Help	
💿 💿 🗋 🖆 🖬 🔤 🌮 🎁 💡 📘	 E
Test Browser 🛛 🛪 🗙	Properties - Set Scope 🛛 🧖 🗙
New Element Untitled Pre Test Herations (3) Hain Test Set Generator Set Scope Save Results Post Test	Instrument resource Select an instrument resource: Scope Message data and format Message data: measurement:immed:type frequency Command text: measurement.immed:type frequency Data source: Send variable data as: String
	Pause after sending data (seconds):
Test Vectors 7 X	
New Edit 👚 🖶 🛒	
Name Vector Values Iterations	
Image: Second	

To see the resources you created for communications with your two instruments, click the **Resources** tab at the bottom of the SystemTest window. You can see the ${\tt Generator}$ and ${\tt Scope}$ resources, along with their GPIB settings.

Resources	× 5	San San Pau	
New - Edit			
Name	Resource Identifier		
📰 Generator	GPIB0-5		
🛒 Scope	GPIB0-4		
Test Vectors Test Variables Resources			

Taking the Measurement

With the generator and scope set up, you can take the measurement with the scope using a Query Instrument element, which sends the command to the scope for taking the measurement.

- 1 Add an element by clicking New Test Element > Instrument Control > Query Instrument.
- 2 Double-click **Query Instrument** in the tree, rename it Measure with Scope, and press Enter.
- **3** Use the existing instrument resource called **Scope**, by selecting it in the **Instrument resource** list.
- 4 Enter the command to query for a measurement by typing measurement:immed:value? in the Instrument query command field.
- 5 Select Store complete response, and select the Empty input buffer after read check box.
- **6** From the **Interpret data as** list, select **String** (this scope returns ASCII strings), and select the **Convert string value to a numeric result** check box.

7 From the Assign data to list, select New Test Variable. For the oscilloscope's frequency measurement, name the test variable scopefreq. It needs no initial value.

The element now looks like the following figure:

📣 SystemTest - Untitled.test*	
File Run Tools Desktop Window Help	
🕞 🐵 🗋 🖆 🖬 🔤 🎲 🔋 📘	💌 🛄 🛍
Test Browser 7 X	Properties - Measure with Scope 🛛 🧖 🗙
New Element 👻 🛖 🐥 🗙	Instrument resource
🖃 🗋 Untitled	Select an instrument resource:
Pre Test	Scope
⊡-Iterations (3) ⊡-Main Test	Query command
Set Generator	Instrument query command:
Set Scope	measurement:immed:value?
Measure with Scope	Reading data
	Store complete response
	C Remove the following header
	O Number of bytes to remove from start of response
Test Variables 🛛 🔻 🗙	Empty input buffer after read
New 🕶 Edit 🏦 🐥 🛱 🎽	r Data format
Name Initial ∀alue Assigned In	Interpret data as:
H scopefreq Main Test	String
	Convert string value to a numeric result
	Assign data
	Assign data to:
	scopefreq
Test Vectors Test Variables Resources	

Saving Test Results

To view the results of your test, you must first specify the test variables you want to save as test results. This is done in the **Save Results Properties** pane.

1 Click Save Results in the test browser tree.

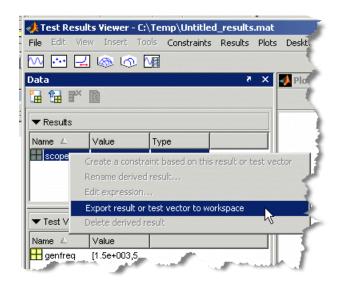
- 2 In the Properties pane, click New Mapping.
- **3** From the **Test Variable** list, select **scopefreq**. This test variable contains the frequency measurements provided by the oscilloscope during each Main Test iteration, as shown in the following figure:

Properties - Save Results		× ĕ □ ≁	
Map Test Variables to Results			
Specify the test variables you want to save at the end of each Main Test iteration by mapping a test variable to a test result name.			
Note, test vectors do not need to be specified. By default, they are made available with saved test results.			
New Mapping 🔺 🖡 🖥			
Test Variable		Result	
scopefreq	•	scopefreq	

Running the Test and Viewing Test Results

Now that the test elements are all created, you can run the test.

- **1** Run your test. When the test is complete, the Test Results Viewer displays your test results.
- 2 You can explore and plot your test results using the Viewer. Alternatively, in the **Data** pane, right-click the name scopefreq and select **Export**. This makes the variable available in your MATLAB workspace.



3 To see the measurement results, at the MATLAB prompt type

```
format short g
scopefreq
scopefreq =
1501.5
5000
7500
```

This verifies that the signal generator is producing the expected signal frequencies.

Using the Data Acquisition Toolbox Elements

The Data Acquisition Toolbox software provides several elements to use in the SystemTest software.

- "Introduction" on page 6-2
- "Example: Testing a Voltage Regulator" on page 6-3

Introduction

In this section...

"Overview" on page 6-2

"Data Acquisition Toolbox Test Elements" on page 6-2

Overview

This chapter describes how to use the Data Acquisition Toolbox elements with the SystemTest software.

The Data Acquisition Toolbox elements provide a way to bring analog and digital data from a data acquisition device into a SystemTest test, or to send analog or digital data from your device. You can use these elements along with the other elements in the SystemTest software to create tests for Simulink models and other applications.

Note To use the Data Acquisition Toolbox elements, you need a license for the Data Acquisition Toolbox software. These four elements will not appear in the SystemTest software without this license.

Data Acquisition Toolbox Test Elements

The Data Acquisition Toolbox software provides four elements that you can use in the SystemTest software:

- Analog Input For reading analog data from your data acquisition device
- Analog Output For sending analog data to your data acquisition device
- Digital Input For reading digital data from your data acquisition device
- Digital Output For sending digital data to your data acquisition device

You can configure each test element to communicate with your data acquisition devices for sending or receiving digital or analog data.

Example: Testing a Voltage Regulator

In this section...

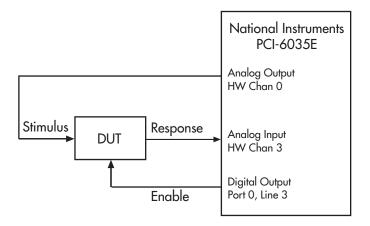
"Introduction" on page 6-3
"Sending Analog Stimulus Data to the DUT" on page 6-4
"Enabling the DUT with Digital Data" on page 6-7
"Receiving Analog Response Data from the DUT" on page 6-9 $$
"Disabling the DUT with Digital Data" on page 6-10
"Performing Data Analysis" on page 6-12
"Defining Post Test Elements" on page 6-13
"Saving and Viewing Test Results" on page 6-14

Introduction

To illustrate how to use some of the Data Acquisition Toolbox test elements in the SystemTest software, this section provides a step-by-step example. The example shows how to use the elements that send data to a device under test (DUT) and receive data from a device under test, using both analog channels and digital lines.

This example samples the response of a 5-V voltage regulator that is stimulated with three different voltages of 4, 5, and 7.5 volts. The regulator has an enable function controlled by a digital signal. In this example, you collect 22,000 samples per second of the DUT response for 2 seconds.

All data going to and from the DUT is handled by a National Instruments[®] PCI-6035E data acquisition card. The example uses this card's analog output for the DUT stimulus, analog input for capturing the DUT response, and digital output for controlling the DUT's enable line. The test configuration is shown in the following figure:

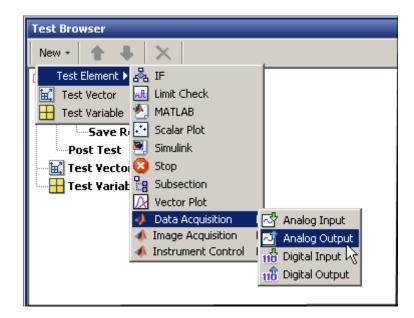


The following sections contain the steps in this example.

Sending Analog Stimulus Data to the DUT

Stimulus data is sent to the DUT from an analog output channel of your data acquisition card.

- 1 Open the SystemTest software in MATLAB by selecting Start > MATLAB > SystemTest > SystemTest Desktop. You can also type systemtest at the MATLAB command line.
- 2 This example does not use the Pre Test section, so select the Main Test section in the Test Browser pane.
- **3** Add an Analog Output element by selecting **New Test Element > Data** Acquisition > Analog Output.



The new element appears in the browser tree, and its properties appear in the **Properties** pane. The SystemTest software scans your computer for installed data acquisition adaptors and devices. This can take several seconds.

- **4** Double-click the new Analog Output node in the browser tree, and enter a new name for this element, such as Stimulate DUT.
- 5 Since we have three test cases, we need to create a test vector containing the three voltage settings to test against. Click the Test Vectors tab. The voltage values for the stimulus to the DUT are held in a test vector. Click New Vector to create a new test vector.
- **6** In the Insert Test Vector dialog box, click the name TestVector1 and enter a new name for your vector, such as DUTstimulus.
- 7 Click the default 1 : 1 : 10 entry in the **Expression** field, and replace it with the values for your test: [4, 5, 7.5] (be sure to include the brackets) and click **OK**. Notice that because there are three values in your vector, the browser tree now indicates that the Main Test will run three

iterations. Each iteration will use one of the three values in the vector for the DUT stimulus voltage.

- 8 In the **Properties** pane, select the adaptor and device to use for the test. This example uses the nidaq adaptor, and the device is a PCI-6035E.
- **9** The example hardware configuration uses the card's analog output hardware channel 0 to provide the DUT's stimulus. So select the check box for this channel. The element will generate signals of 4, 5, and 7.5 volts, so keep the default output range of [-10.0 10.0].
- 10 From the Data source list, select the DUTstimulus test vector.
- 11 Enter a value of 1 for **Output rate**. You are using a single static value rather than a sampled waveform, so this is not critical.
- 12 Enter a value of 1 for Number of times to output data. The card will hold its last programmed value, so you need to send it only once.

📣 SystemTest - Untitled.test*	
File Run Tools Desktop Window Help	
🕑 💿 🗋 🖆 🖬 🔤 🗊 🌹 💡 📘	<u> </u>
	Properties - Stimulate DUT 7 ×
New Element	Select Hardware: Adaptor: nidaq Device: Dev2 (PCI-6035E) MW Channel Output Range Ø 0 [-10.0 10.0] 1 [-10.0 10.0]
Test Vectors A New Edit Name Vector Values Iterati DUTstimulus [4, 5, 7.5] Image: Test Vectors Test Vectors	Select All Unselect All Data source: DUTstimulus DUTstimulus Image: Complex (Samples / Second): 1 The actual output rate will be 1. Number of times to output data: 1

The **Properties** pane now looks like the following figure:

Enabling the DUT with Digital Data

To send a digital enable signal to the DUT, use a digital output element.

- 1 Select New Test Element > Data Acquisition > Digital Output.
- **2** Double-click the new Digital Output element in the browser tree, and type a new name for this element, such as Enable DUT.
- **3** Click the **Test Variables** tab.
- **4** Click the **New** button to create a new variable. You will create two variables: one for enabling and one for disabling the DUT.
- 5 Click the name Var1, and replace it with the text DUTenable.

- 6 Click its empty Initial Value entry, and enter 1.
- **7** Repeat steps 4 to 6 to create a second test variable, but name it DUTdisable with an initial value of 0.
- 8 In the **Properties** pane for the Enable DUT element, select the adaptor and device for sending this data. Again, you are using the nidaq adaptor, and the device is a PCI-6035E.
- **9** The hardware configuration uses the card's digital output port 0, line 3 for the enable signal, so select the check box for this line.
- 10 From the Data source list, select the variable DUTenable.

The **Properties** pane now looks like the following figure:

📣 SystemTest - Untitled.test*		_ _ _ _ _
File Run Tools Desktop Window Help		
🕞 💿 🗋 😅 🖬 🚾 🎲 🌹 💡 🗌		💌 🛄 🔁
Test Browser 🍖 🗙	Properties - Enable DUT	X 5
New Element 👻 🛔 🐥	Select Hardware:	
🖃 🗋 Untitled		
Pre Test	Adaptor:	
Enterations (3)	nidaq	•
⊟Main Test 	Device:	
	Dev2 (PCI-6035E)	▼
Save Results		
Post Test	Port	Line
		0
		2
		3
		4
Test Variables 7 X		5
		6
New 🕶 Edit 👚 🐥 🗄		7
Name Initial Value Assigned In		
DUTenable 1 Main Test		
DUTdisable 0 Main Test		
Hun root	Select All Unselect	0.11
		80
	Data source:	
	DUTenable	•
Test Vectors Test Variables Resources	J	_

Receiving Analog Response Data from the DUT

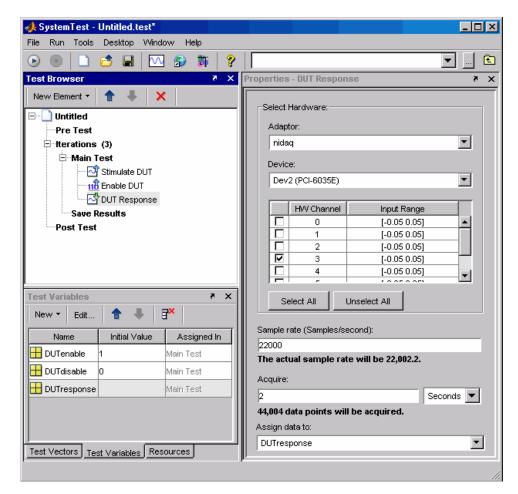
The next element in the test samples the output from the DUT and assigns the acquired data to a test variable.

- 1 Select New Test Element > Data Acquisition > Analog Input.
- **2** Double-click the new **Analog Input** element in the browser tree, and enter a new name for this element, such as DUT Response.
- **3** In the **Properties** pane, select the adaptor and device to use for the test. This example uses the nidaq adaptor, and the device is a PCI-6035E.
- **4** The hardware configuration uses the card's analog input hardware channel 3 to read the DUT's response, so select the check box for this channel. The expected signal will be about 5 volts, so keep the default output range of [-10.0 10.0].
- **5** Set a sample rate of **22000**. Because of hardware limitations, the actual sample rate may not exactly match the value you specify.
- **6** In the **Acquire** field, specify to acquire data for 2 seconds. Set seconds in the unit list to the right of the value field.
- 7 In the Assign data to field, select New Test Variable from the list. This is where you specify what test variable to assign the acquired data to. The Edit dialog box appears.

Editing: Var1	×
Name	
Var1	
Initial value	
NaN	
Assigned in	
Main Test	
	OK Cancel

8 Enter a name for the test variable, such as DUTresponse, then click OK to create the test variable.

The **Properties** pane now looks like the following figure:



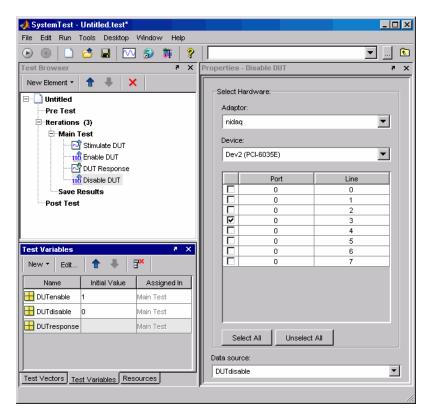
Disabling the DUT with Digital Data

The next step is to disable the DUT with a digital output element that turns off the DUT's enable line. This element is similar to the Enable DUT element, except it sends a different value to the DUT.

- 1 Select New Test Element > Data Acquisition > Digital Output.
- **2** Double-click the new **Digital Output** element in the browser tree, and enter a new name for this element, such as **Disable DUT**.

You already created the test variable DUTdisable, which you will use in this element.

- **3** In the **Properties** pane for the **Disable** DUT element, select the adaptor and device for sending this data. Again, you are using the nidaq adaptor, and the device is a PCI-6035E.
- **4** The hardware configuration uses the card's digital output port 0, line 3 for the enable signal, so select the check box for this line.
- **5** From the **Data source** list, select the variable **DUTdisable**.



The **Properties** pane now looks like the following figure:

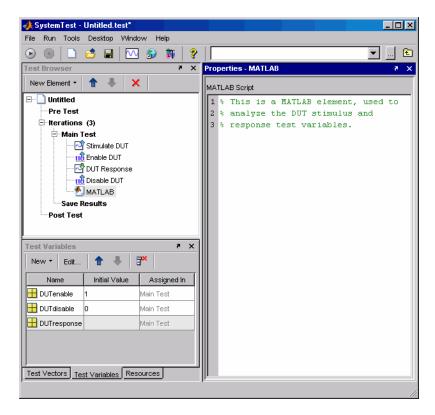
Performing Data Analysis

At this stage, you might perform any analysis or visualization routines on the data generated by the DUT. You can do this in a MATLAB element.

- 1 Select New Test Element > MATLAB.
- **2** Double-click the new **MATLAB** element in the browser tree, and enter a new name for this element, such as **Process Data**.
- **3** In the **MATLAB Script** edit field of the **Properties** pane, enter any MATLAB code that you need for analyzing your test variables. You might be interested in measuring ripple, noise, regulation, or many other

characteristics. You can access the DUT response by referring to the test variable DUTresponse. The stimulus data is available in the test variable DUTstimulus.

The following figure shows a MATLAB element with only some comments added in the **Properties** pane.



Defining Post Test Elements

In this example, it is recommended to include an element in the Post Test section to disable the DUT.

- 1 Click the **Post Test** section in the browser tree.
- **2** Create a digital output element set up like the element you made in "Disabling the DUT with Digital Data" on page 6-10.

With the extra **Disable DUT** element, the test now looks like the following figure:

🙏 SystemTest - Untitled.test*		
File Run Tools Desktop Window Help		
Description of the second sec	Properties - Disable DUT	▼ €
New Element - 1 - X	Properties - disable bot	<u> </u>
	Select Hardware:	
Pre Test	Adaptor:	
⊡-tterations (3)	nidaq	•
- Main Test	Device:	
⊡ Stimulate DUT 118 Enable DUT	Dev2 (PCI-6035E)	•
DUT Response		
11 Disable DUT	Port	Line
		0
Save Results		2
Post Test Disable DUT		3
		<u> </u>
Test Variables 7 X		6
New 🕶 Edit 👚 🐥 🕂		7
Name Initial Value Assigned In		
DUTenable 1 Main Test	Select All Unselect /	0.1
DUTdisable 0 Main Test		5.1
DUTresponse Main Test	Data source:	
Test Vectors Test Variables Resources	DUTdisable	_
	μ <i>'</i>	

The Post Test section of the test could also perform any analysis that requires completion of all the iterations of the Main Test.

Saving and Viewing Test Results

Before running a test, you must specify which test variables you want to save as a test result. In the **Save Results Properties** pane, you select the test variable that you want to save and map it to a test result name.

The SystemTest software allows you to view the results you have chosen to save for your test using a workspace variable called stresults. It provides access to the test results object, which is useful for comparing the results of separate test runs and for postprocessing test results.

For more information, see Chapter 10, "Accessing Test Results from the MATLAB Command Line".



Using the Image Acquisition Toolbox Element

The Image Acquisition Toolbox software includes a SystemTest element that you can use to bring live video data into a SystemTest test.

- "Introduction" on page 7-2
- "Example: Acquiring Video Data in a Test" on page 7-3

Introduction

This chapter describes how to use the Image Acquisition Toolbox element with the SystemTest software.

The Image Acquisition Toolbox element, called Video Input, provides a way to acquire live video data in a SystemTest test. You can use this element along with the other elements in the SystemTest software to create tests for Simulink models and other applications.

To learn how to use the Image Acquisition Toolbox element in the SystemTest software, see "Example: Acquiring Video Data in a Test" on page 7-3.

Note To use the Image Acquisition Toolbox element, you need a license for the Image Acquisition Toolbox software. The Video Input element will not appear in the SystemTest software if you do not.

Example: Acquiring Video Data in a Test

In this section ...

"Adding the Video Input Element to a Test" on page 7-3

"Saving and Viewing Test Results" on page 7-8

"Running the Test" on page 7-9

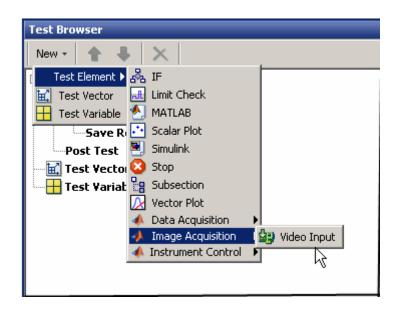
Adding the Video Input Element to a Test

This example illustrates how to use the Video Input element in the SystemTest software. The example uses the Video Input element to acquire a single frame of video for each iteration of the test and uses the MATLAB element to display the acquired image.

The first step is to add the element, as shown in this section. The two following sections contain the remaining steps.

To create a test using the Video Input element:

- 1 Open the SystemTest software by selecting Start > MATLAB > SystemTest > SystemTest Desktop in MATLAB. You can also just type systemtest at the MATLAB command line.
- 2 In the SystemTest desktop, start to create your test by selecting Main Test and adding the Video Input element. In the Test Browser, click New Test Element > Image Acquisition > Video Input.



The SystemTest software adds the Video Input element to the Main Test section of the test and displays the **Properties** pane for the Video Input element. (You can also add elements to the Pre Test or Post Test sections of a test but this example does not require it.)

In the following figure, note the red x in the Video Input element icon in the Test Browser. This red x indicates that the element is in an error state. The SystemTest software outlines the required fields in red in the **Properties** pane.

Test Browser 🔭 🗙	Properties - Video Input 🛛 🦻 🗙
New Element • • • • • • • • • • • • • • • • • • •	Image Acquisition Device Adaptor: winvideo Device: 1 (IBM PC Camera) Video Format: RGB555_128×96 Selected Source: input1
Test Variables ₹ × New ▼ Edit 1 <th>Preview Window</th>	Preview Window
Name Initial Value Assigned In	Number of frames: 1 Assign data to:

3 Specify the device you want to use to acquire image data in the **Properties** pane for the Video Input element. You must specify the name of the adaptor you want to use in the **Adaptor** field, which is a required field. (The SystemTest software uses red outlining to indicate required fields that are not filled in yet.) The SystemTest software can detect any image acquisition devices supported by the Image Acquisition Toolbox software that are connected to your system and fills in this field with a default value based on the alphabetical list of devices, if one is available. For our example, in the figure, the SystemTest software sets the **Adaptor** field to winvideo. If your system has other adaptors that can connect to devices, select the adaptor that you want to use from the **Adaptor** list.

After the **Adaptor** field is set, the SystemTest software fills in the **Device**, **Video Format**, and **Selected Source** fields with default values. The SystemTest software populates the drop-down lists associated with each field with all available options for the field. Adaptors can support multiple devices and devices can support multiple formats. The SystemTest software preselects the default values for these fields but lists all available options in the drop-down lists associated with these fields. The following figure shows the list for the **Video Format** field:

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- **4** Specify the number of frames you want to acquire at each iteration of the test in the **Number of frames** field, which is a required field. For this example, we only need to acquire one frame for each iteration, so set this field to 1.
- **5** Specify the name of the SystemTest test variable that the acquired video data will be assigned to at each iteration. This is a required field. You can select a test variable from the list or create a new test variable by selecting **New Test Variable**.

<new test="" variable=""></new>	n data to:	
sNew Test Variable is		•
<new is<="" td="" test="" variable=""><td></td><td></td></new>		
	/ Test Variable>	

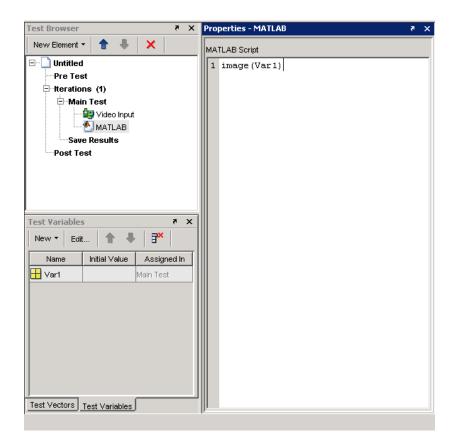
If you select **New Test Variable**, the SystemTest software opens the Edit dialog box. Assign a name to the test variable, or accept the default name, and click **OK**. You do not need to assign the test variable an initial value.

Editing: Var1	×
Name	
Var1	
Initial value	
Assigned in	
Main Test	
	OK Cancel

The SystemTest software adds the new test variable to the list in the **Test Variables** pane.

- **6** Optionally, verify the Video Input element settings by clicking the **Preview Window** button. The SystemTest software opens a Video Preview window and displays a live video stream from your camera. You can use this to verify that your hardware is configured correctly. You should close the preview window before running the test.
- 7 To complete this example test, add a MATLAB element to the Main Test section. In this MATLAB element, call the MATLAB image function to display the image frame acquired at each iteration.

7



This completes this example test illustrating how to incorporate image data into the SystemTest software. In a real testing application, you can define test vectors that determine the number of iterations of your test that the SystemTest software performs. You can also compare test variables against defined limits in the Limit Check element and specify pass/fail criteria.

Saving and Viewing Test Results

Before running a test, you must specify which test variables you want to save as a test result. In the **Save Results Properties** pane, you select the test variable that you want to save and map it to a test result name. The SystemTest software allows you to view the results you have chosen to save for your test using a workspace variable called stresults. It provides access to the test results object, which is useful for comparing the results of separate test runs and for postprocessing test results.

For more information, see Chapter 10, "Accessing Test Results from the MATLAB Command Line".

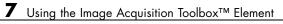
Test Browser 🍖 🗙	Р	operties - Save Results		7	х
New Element 👻 🛔 🗼	[Map Test Variables to Results			
⊡ Untitled Pre Test		New Mapping 🛉 👫	¢		
	Ш	Test Variable	Result		
Generation Save Results		Var1	Var1		

Running the Test

To run the test, do one of the following:

- Click the **Run** button.
- Select Run > Run.
- Press the $\mathbf{F5}$ key.

While the test executes, the SystemTest software reports on the progress of the test in the **Run Status** pane.



Distributing Tests Using Parallel Computing Toolbox Integration

- "SystemTest Software and Parallel Computing Toolbox Integration" on page 8-2
- "Enabling Distributed Testing" on page 8-3
- "Selecting a User Configuration" on page 8-5
- "Setting Up File Dependencies" on page 8-7
- "Setting Up Path Dependencies" on page 8-9
- "Distributing Iterations Across Tasks" on page 8-12
- "Running a Distributed Test" on page 8-14
- "Example: Distributing a Test" on page 8-17

SystemTest Software and Parallel Computing Toolbox Integration

You can distribute SystemTest tests across multiple computers or processors. You can set up a test and then distribute Main Test iterations as tasks, which are performed concurrently by different workers. This can help speed up the total time the test takes to execute.

Note To distribute tests in the SystemTest software, you need a license for the Parallel Computing Toolbox[™] software.

You set up a distributed test as you would set up any test, using the SystemTest desktop. Then you use the **Distributed** tab on the **Test Properties** pane to set up the test distribution.

To access the distributed testing functionality in the SystemTest software, do one of the following:

- Select your test name in the **Test Browser**. This is the top node in the **Test Browser**, that lists the name you give the test when you save it, or "Untitled," if you have not saved it yet. Then click on the **Distributed** tab in the **Test Properties** pane.
- Select **Tools > Distributed Testing** on the SystemTest menu. This opens the **Distributed** tab.

Note that if you do not have the Parallel Computing Toolbox software installed, the tab displays a message indicating you cannot use the distributed testing functionality.

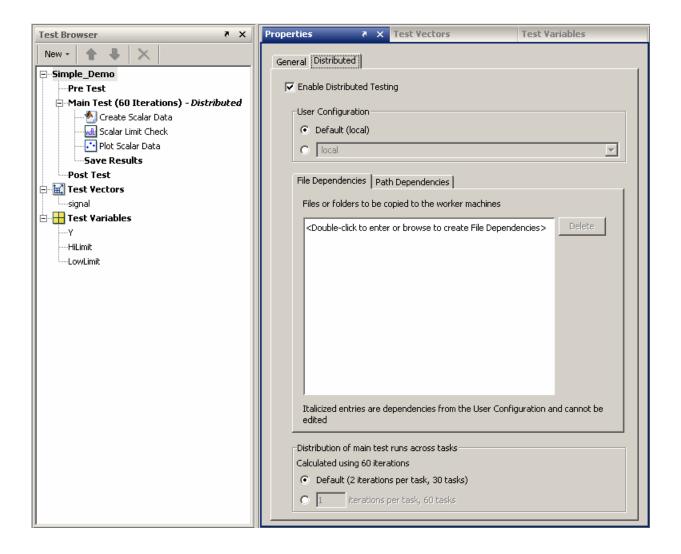
Note To see a diagram that shows how distributed testing with the SystemTest software works and illustrates the relationship between the SystemTest software, the scheduler, and the workers, see "Running a Distributed Test" on page 8-14.

Enabling Distributed Testing

You must select the **Enable Distributed Testing** check box to distribute a test. Once enabled, the rest of the fields on the **Distributed** tab are activated.

The check box is not enabled by default on new tests. However, once you have set up a distributed test, if you save and close a test with the check box enabled, it will reload in the enabled state.

The **Main Test** node on the **Test Browser** indicates if your test is set up to be distributed. For example, if you have a distributed test containing 60 iterations, the node displays **Main Test (60 Iterations)** – *Distributed*, as shown in the following figure.



Selecting a User Configuration

You or an administrator must set up a user configuration in the Parallel Computing Toolbox software before distributing tests in the SystemTest software. The user configuration determines certain administrative options, such as what scheduler is used. You can use The MathWorks[™] job manager that comes with MATLAB[®] Distributed Computing Server[™], and the local scheduler that comes with the Parallel Computing Toolbox software. You can also use a third-party scheduler, such as Windows CCS, Platform Computing LSF, mpiexec, or a generic scheduler.

In the **User Configuration** field on the **Distributed** tab, select the user configuration that will be used when you distribute tests.

- The **Default** option indicates the configuration that is designated as the default in the Parallel Computing Toolbox software. The name of the configuration appears in parentheses.
- If you have any other configurations defined, they will appear in the drop-down list under **Default**. Either use the default, or click the second radio button and choose a user configuration from the list.

In the following example, this user has several different schedulers and has a separate user configuration for each scheduler. In this example, the user configurations are named for the schedulers they use.

Properties	- Simple_Demo	2	х
General	Distributed		_
🔽 Enab	le Distributed Testing		
User	Configuration	_	
0	Default (local)		
•	jobmanager	7	
	jobmanager	2	
File D	lsf		
	ccs	1	
File	generic		
<0	mpiexec		
<	local		

User configurations contain other information in addition to scheduler selection, and are used to define other distributed computing parameters. See Programming with User Configurations in the Parallel Computing Toolbox documentation for details on setting up the user configuration.

If you load a test containing a user configuration that no longer exists, this option will be in an error state. You can correct the error by selecting a valid user configuration.

Setting Up File Dependencies

Use the **File Dependencies** table to indicate files or folders of files to be copied to the worker machines. If the worker machines need to access files that your test is dependent on, you can add the names of the files or directories of files as dependencies in the SystemTest software and they will be copied to each worker.

Note: There is overhead in copying files for each task. If there are files that can be accessed from a shared location by the worker machines, use **Path Dependencies** instead. For example, if you use a Simulink element that references a large model available from a shared network folder, you should set a path dependency to the directory containing your model.

File dependencies can be defined in the **File Dependencies** table, as described below, or can be defined in the user configuration that is set up in the Parallel Computing Toolbox software. If there are any file dependencies specified by the currently selected user configuration, they will also be listed in this table, but will appear in italics and are not editable here. File names you enter through the SystemTest software appear in regular text and are editable here.

To set up a file dependency:

- 1 Click the File Dependencies tab within the Distributed tab.
- **2** Double-click the entry row in the table (the top row).

The row becomes a text field.

- **3** Do either:
 - Type the full path and file or folder name in the field, and then press **Enter**.
 - Click the browse button in the entry row, browse to the file or folder, then click **Open** in the browse dialog box.

The dependency you entered then appears as a new row in the list.

The example below shows file dependencies for an M-file and a small model to be copied to the worker machines.

File Dependencies Path Dependencies					
Files or folders to be copied to the worker machines					
<double-click browse="" create="" dependen<="" enter="" file="" or="" p="" to=""></double-click>	Delete				
H:\MATLABfiles\AI_system.mdl					
H:\MATLABfiles\scalartest.m					
Italicized entries are dependencies from the User Configuration and cannot be edited					

If you want to delete a file dependency, select it and click the **Delete** button. You can delete only dependencies added in the SystemTest software. You cannot delete any that are specified by the user configuration.

Setting Up Path Dependencies

Use the **Path Dependencies** table to indicate directories to be added to the workers' MATLAB path. If the worker machines need to access certain files during the test, you can add the directories here. These directories are added to the workers' MATLAB path such that the necessary files can be located. For example, if you use a Simulink element that references a large model available from a shared network folder, you should set a path dependency to the directory containing your model.

Note: If there are files that cannot be accessed from a shared location, use **File Dependencies** instead.

You can enter path dependencies in the **Path Dependencies** table, as described below, or in the user configuration that is set up in the Parallel Computing Toolbox software. If there are any path dependencies specified by the currently selected user configuration, they will also be listed on this tab, but will appear in italics and are not editable in the SystemTest software. Paths you enter through the SystemTest software appear in regular text and are editable here.

To set a path dependency:

- 1 Click the Path Dependencies tab within the Distributed tab.
- **2** Double-click the entry row in the table (the top row).

The row becomes a text field.

- **3** Do either:
 - Type the path in the field, and then press Enter.
 - Click the browse button in the entry row, browse to the directory, then click **Open** in the browse dialog box.

The dependency you entered then appears as a new row in the list.

In the following example, because the model is very large the user set up a path dependency for the directory containing the model that the test uses.

File Dependencies Path Dependencies
Directories to be added to the worker's MATLAB path
<pre><double-click browse="" create="" depende="" engine_block_model<="" enter="" h:\simulinkfiles\engine_block_model="" home="" or="" path="" pre="" simulinkfiles="" to=""></double-click></pre>
Italicized entries are dependencies from the User Configuration and cannot be edited

Notice in this example that the path is listed twice, once in Windows[®] format and once in UNIX[®] or Linux[®] format. If you have a heterogeneous cluster that contains both Windows and UNIX or Linux worker machines, you need to add the path twice so that all workers can use it. **Note** Path dependencies must be listed in the format supported by the type of worker machines the cluster contains, as shown in the previous figure (which shows both styles). Also, for Windows machines that cannot be directly accessed by all the workers, you need to specify the path as a UNC path.

If you want to delete a path dependency, select it and click the **Delete** button. You can delete only dependencies added in the SystemTest software. You cannot delete any that were specified by the user configuration.

Distributing Iterations Across Tasks

The **Distribution of main test runs across tasks** option on the **Distributed** tab determines the distribution of Main Test iterations into tasks that the workers perform. The calculation is based on the total number of iterations your test contains.

By default, the **Default** option is selected and the text in parentheses shows the number of iterations per task and number of tasks. The default is calculated by dividing the number of iterations in your test by 32 (an approximation based on a setup of 8 workers, with a target of 4 tasks per worker), and using the closest number to that. For example, if your test has 90 iterations, the default will be 3 iterations per task and 30 tasks, as shown below.

Distr	ribution o	of main test runs across tasks
Calc	ulated us	sing 90 iterations
Θ	Default	(3 iterations per task, 30 tasks)
0	1	iterations per task, 90 tasks

If you run your test and this does not seem efficient, you can change the number of iterations per task and number of tasks. To change it:

- 1 Select the second option. The number field becomes editable.
- 2 Enter the number of iterations per task you want to use.

3 Press Enter.

The number of tasks is then calculated (total number of iterations divided by number of iterations per task) and shown in parentheses. For example, if you had the same test with 90 iterations, but changed iterations per task to 6, you get 15 tasks.

Distribution of main test runs across tasks
Calculated using 90 iterations
O Default (3 iterations per task, 30 tasks)

Running a Distributed Test

You run a distributed test as you would run any other test, by clicking the **Run** button in the SystemTest toolbar.

When you run a distributed test:

- Pre Test executes once, on the client machine (the machine from which you run the test).
- Main Test iterations execute on the cluster of worker machines defined by the user configuration.
- The SystemTest software waits for the distributed test to complete.
- If there are errors when the distributed test iterations run, only the first error from the tasks will be reported to the **Run Status** pane in the SystemTest software once all tasks have completed.
- At the end of each Main Test iteration, test results are saved and returned to the client machine once all Main Test iterations have finished executing.

Note Because Main Test iterations run across a number of tasks, there is no guarantee as to the order the tasks (Main Test iterations) will execute. Tests should not be written with the assumption that iterations will execute in a fixed order.

Also, because Pre Test runs on the client machine, and tasks run independent of each other, Main Test iterations should not rely on data persisting across multiple iterations.

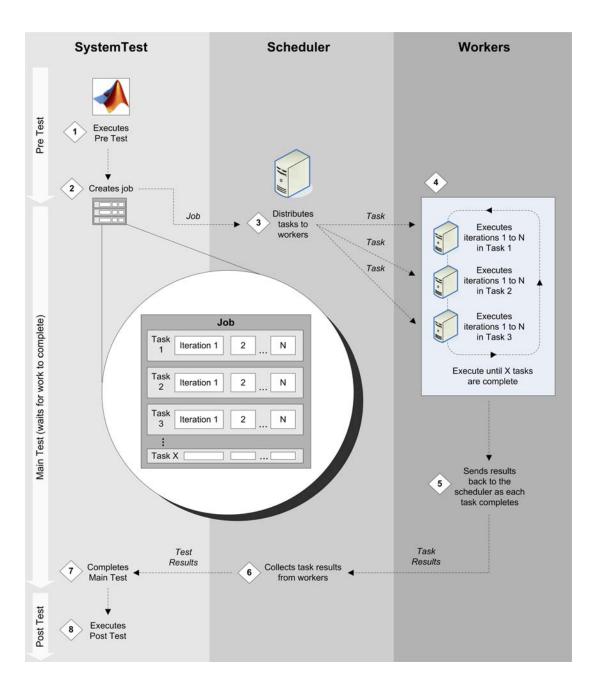
- Post Test executes once on the client machine, after Main Test executes or has errored while running.
- Test execution reports are generated at the end of the test, if enabled by the test.
- Generated plots are not shown on the client machine while the test runs, but are captured and displayed in the Test Report. Note that plots generated on worker machines will only reflect information generated as part of the task. Plotting multiple data points or lines on a single plot will

only reflect the data pertaining to iterations executed as part of a single task.

Note that MATLAB and the SystemTest software remain in a busy state until the distributed test is done running or is stopped.

Caution It is recommended that you do not run a test containing hardware-related elements in distributed mode. That includes the Image Acquisition Toolbox element, the Data Acquisition Toolbox elements, and the Instrument Control Toolbox elements. These elements will likely error out because the connected hardware will not be available on the workers.

The following diagram illustrates the relationship between the SystemTest software, the scheduler, and the workers. Task 1 to Task X and Iteration 1 to Iteration N are determined by what is shown in the **Distribution of main** test runs across tasks section in the **Distributed** tab. For example, if the **Distribution of main test runs across tasks** for a test with 90 iterations is set to **Default (3 iterations per task, 30 tasks)**, that means your test will execute 3 iterations for each of 30 tasks. In this case, Task 1 might run iterations 1, 2, and 3, and Task 2 might run iterations 4, 5, and 6, etc.



Example: Distributing a Test

The following general example shows how you can distribute any test you have created.

You create and set up a distributed test as you would set up any test, using the SystemTest desktop. If you determine that the test takes a long time to execute, you may benefit from distributing it. You then use the **Distributed** tab on **Test Properties** to set up the test distribution.

To distribute a test:

- 1 Select your test name in the **Test Browser**. Then click the **Distributed** tab in the **Test Properties** pane.
- **2** Select the **Enable Distributed Testing** check box to enable distributed testing and activate the other options on the tab.
- **3** The SystemTest software uses the user configurations set up in the Parallel Computing Toolbox software. User configurations identify various settings, such as which scheduler to use.

In the **User Configuration** section, keep the default user configuration, or select the second radio button and choose a different configuration from the drop-down list.

For more details, see "Selecting a User Configuration" on page 8-5.

4 If your test is dependent on files, such as models, M-files, or MAT-files, in order to execute, you need to specify the dependent files so that the worker machines can access the files while the test is running.

If there are files that need to be copied onto the worker machines, use the **File Dependencies** tab. If there are files available on a shared network location that need to be accessed by the worker machines, use the **Path Dependencies** tab instead. For example, if you use a Simulink element that references a large model available from a shared network folder, you should set a path dependency to the directory containing your model.

Enter the necessary file or path dependencies into the respective tabs by double-clicking the top row in the tables. For more details, see "Setting

Up File Dependencies" on page 8-7 and "Setting Up Path Dependencies" on page 8-9.

5 The SystemTest software will calculate number of iterations per task for you, or you can specify that, in the **Distribution of main test runs across tasks** section.

Use **Default**, or change it by selecting the second option, which enables the number field. Enter the number of iterations per task you want to use and press **Enter** or click outside the field.

For details on how these values are calculated, see "Distributing Iterations Across Tasks" on page 8-12.

6 Run the distributed test as you would run any other test, by clicking the Run button in the SystemTest toolbar.

For information on what happens when you execute a distributed test, see "Running a Distributed Test" on page 8-14.

Using the Test Results Viewer

This chapter explains how to use the Test Results Viewer to explore and analyze your test results.

- "Viewing Test Results" on page 9-2
- "Before You Begin" on page 9-3
- "A Quick Tour of the Test Results Viewer" on page 9-6
- "Viewing Your Test Results" on page 9-8
- "Refining Your Test Results" on page 9-29
- "Viewing Simulink Time Series Data" on page 9-38
- "Saving and Reloading Test Results" on page 9-43

Viewing Test Results

This chapter is about the Test Results Viewer, which may be an efficient way to view results for some tests. However, we recommend viewing results via the command line in MATLAB instead of using the Test Results Viewer.

The SystemTest software allows you to view the results you have chosen to save for your test using a workspace variable called stresults. It provides access to the test results object, which is useful for comparing the results of separate test runs and for postprocessing test results.

For more information, see Chapter 10, "Accessing Test Results from the MATLAB Command Line".

If you choose to use the Test Results Viewer, the following sections document its use.

Before You Begin

The examples in this chapter use saved test results from the Throttle demo. You can follow the explanations by loading and running the Throttle demo from the MATLAB command line. The Throttle demo is configured to open the Test Results Viewer upon completing a test.

See the SystemTest Demos page for an explanation of the Throttle demo.

Note This demo will not be listed if you do not have Simulink installed.

To prepare for the rest of this chapter:

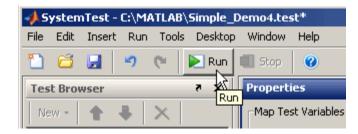
- 1 Start MATLAB.
- **2** In MATLAB, select **Start > Demos** to open the Help browser opens.
- **3** Expand the **MATLAB** list from the left frame of the browser.
- 4 Click SystemTest. The SystemTest demos open in the right browser frame.
- **5** Under **Simulink**, click **Validating a Throttle Body Model**. An overview of the demo opens.
- **6** Click the link **Open the demo in the SystemTest desktop** at the bottom of the page.

Alternatively, you can enter the following command at the MATLAB command line:

systemtest demosystest_throttle

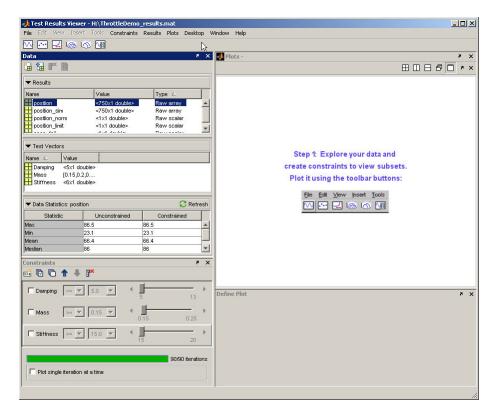
After the SystemTest desktop appears, run the loaded test. Do one of the following:

• Click the **Run** button.



- Press the F5 key.
- Select **Run > Run**.

The SystemTest software runs the Throttle demo test, saves the specified test results, and opens the Test Results Viewer when it finishes.



Note The most common use case is to have the Viewer open automatically after a test run, as described here. But you can also open the Viewer directly from MATLAB by typing stviewer at the MATLAB command line. The Viewer would open in an empty state. To open test results then, use the **File** > Load Test Results menu command.

A Quick Tour of the Test Results Viewer

The Test Results Viewer is organized to show you the test vectors you specified as inputs to your test, the results saved from your test, and tools you can use to plot and examine your test results.



Plot display options

The test results and test vectors from your test are available in the **Data** pane, which is a compact data browser. You choose your plot type, set your display options to include what appears on the different axes, and plot your data. The plotting tools let you select data from the plot to examine, and you can see the actual values that resulted in individual plot points in the **Current Iteration** pane, which will open automatically when you select a plot point. If this pane is not visible, select **Desktop > Current Iteration**.

"Viewing Your Test Results" on page 9-8, "Refining Your Test Results" on page 9-29, and "Viewing Simulink Time Series Data" on page 9-38 explain how to use the Test Results Viewer to plot and examine your test results.

Viewing Your Test Results

In this section ...

"Reserved Keywords" on page 9-8

"Browsing Results" on page 9-8

"Generating Plots" on page 9-9

"Exploring Plots" on page 9-16

Reserved Keywords

The Test Results Viewer has several reserved keywords that you cannot use as a test result name or as a derived result name. These keywords are:

- time
- testrun
- testruns
- metadata
- data

If any of these keywords are used as a test result name, they will be prepended with "st_" when loaded in the Test Results Viewer. If you try to use these keywords as a derived result name in the Test Results Viewer, you will get an error message.

Browsing Results

"Viewing Test Results" on page 1-42 notes that the Test Results Viewer contains a data browser within the **Data** pane. This area of the viewer is one of the first things you see when the Test Results Viewer opens. It shows you the test variables and test vectors your test used, and it shows information about their values in the **Data Statistics** area.

These data statistics summarize the values of a test result or test vector across all of the tests. For example, the Throttle demo varies the parameters for mass, damping, and stiffness of a Simulink model. Test vectors vary

9-8

Simulink block parameters for 90 test iterations, and the SystemTest software saves how these changes affect the position of a simulated throttle opening in the position_sim test result.

If you click position_sim in the **Results** area of the **Data** pane, the **Data Statistics** area shows you a summary of statistical information for all 90 iterations. In this example, you have not defined any constraints on your data, so statistical information for the constrained and unconstrained columns is the same. See "Creating and Applying Constraints" on page 9-29.

▼ Data Statistics:	C Refres		
Statistic	Unconstrained	Constrained	
High	86.5	86.5	
Low	23.4	23.4	
Mean	65.1	65.1	
Median	84.8	84.8	
STD	26.6	26.6	

"Generating Plots" on page 9-9 explains how you can further explore your test results.

Generating Plots

The Test Results Viewer has a plotting capability that helps you understand your test results. You can determine how values of different inputs (test vectors) affect the overall test results.

To generate any plot:

 Click the button corresponding to the type of plot you want to generate. The plot buttons are below the menu bar. For example, click the Line Plot button. See "Choosing a Plot" on page 9-15 for an explanation of your choices. You can also use the Plots menu to generate plots.

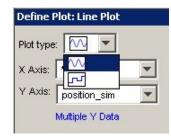


2 Choose the data to use for your X-axis and Y-axis in the **Define Plot** pane. For example, select ***Auto*** from the **X Axis** list and **position_sim** from the **Y Axis** list to show the simulated throttle position trajectories at each test iteration. See "Choosing a Plot" on page 9-15 to understand which data types are available on each axis.

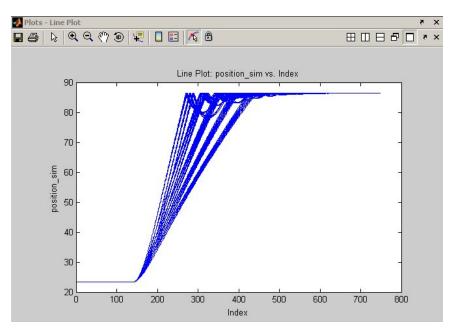
Define Pl	ot: Line Plot 1	× ج
Plot type:	Line 💌	Valid plot of unconstrained data with 90 line(s)
X Axis:	*Auto*	Show as subplo
Y Axis:	position_sim	and as subplo +
	Multiple Y Data	Copy Settings Refresh Plot

Note Selecting ***Auto*** when creating a plot means the plot will show the exact number of values in the test vector or result you are plotting. For example if you are plotting a test vector that has 50 values, and you select ***Auto*** for one of the axes, that axis will display 50 points.

- **3** Choose a different plot type if you do not want to use the default. To choose a different plot type:
 - **a** Click **Plot type** in the **Define Plot** pane.



- **b** Click the plot type you want to use. For the Throttle demo example, use the default sine wave.
- **4** Click the **Plot** button. The Test Results Viewer renders a plot based on your selections.



Each line in the plot represents a test iteration. If it appears that there are not as many lines as you had test iterations, it is possible that two or more iterations generated similar enough results that they overlap.

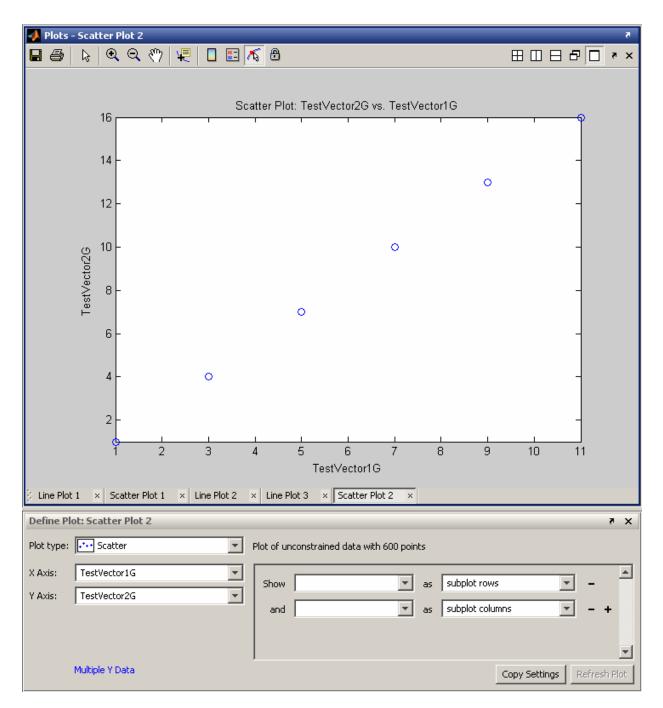
Now you can analyze the plot. To help you with this task, you can:

- Explore the plot using the plotting tools available to you as explained in "Exploring Plots" on page 9-16.
- Refine what results are shown in your plot as explained in "Refining Your Test Results" on page 9-29.

Plotting Grouped Test Vectors

You can plot grouped test vectors on both the X and Y axes of scatter plots. Using grouped test vectors in plot configurations allows you to see the relationship between the grouped vectors.

The following figure shows an example of a test that has two grouped test vectors, TestVector1G and TestVector2G. The scatter plot allows both grouped vectors to be shown in the plot, one on each axis. That is useful for Monte Carlo simulation testing. For example, if you have two vectors that vary the mass of two different components in a model, you could see them in relation to each other.



To plot two grouped test vectors in the viewer:

- **1** Select **Scatter** as your **Plot type**.
- 2 Select the first grouped test vector from the X Axis list.
- 3 Select the second grouped test vector from the Y Axis list.
- 4 Click the Plot button.

You will see a plot similar to the one shown above in which you can see how the two test vectors relate to each other.

Using Grouped Test Vectors as Distinguishing Variables in Subplots

You can also use grouped test vectors as distinguishing variables in subplots. You can select them in the **Subplot** drop-down lists next to the labels **show** and **and**.

For example, in the example shown above, if a test variable TestVariable1 were plotted against a non-grouped test vector TestVector1Ungrouped, TestVector1G could be used to distinguish the resulting scatter points using different marker colors and TestVector2G could be used to distinguish them by different subplot rows. The grouped test vectors would appear in the subplot drop-down lists to allow this configuration.

Choosing a Plot

There are six types of plots. The line plot, mesh plot, and time series plot types have additional subtypes available. Additionally, the Test Results Viewer has rules for determining which test results you can plot on the X-axis, Y-axis, and Z-axis. These rules vary by plot type. The following table explains these selections:

Plot	Description
Line	 Standard line plot of Y versus X. Represents scalar or vector data. The default is a wave line, but you can choose a square line sub type. The following data are allowed on each axis: X — Numeric test vectors
	• Y — Numeric test results
Surf	 Wireframe surf plot based on X, Y, and Z coordinates. Optional surface sub type available. The following data are allowed on each axis: X — Numeric test vectors
	• Y — Numeric test vectors
	• Z — Numeric test results
Scatter	Standard scatter plot of X and Y where either axis can have numeric test vectors or numeric test results.
Time Series	Plots time series data Y against time (X is always time). Designed to represent Simulink time series object data. The default is a wave line, but you can choose a square line sub type. See "Viewing Simulink Time Series Data" on page 9-38 for more information about this plot type.

Plot	Description
Waterfall	 Waterfall plot for vectors or time series. One vector or time series can be displayed on each waterfall plot. The meaning of the X, Y, and Z axes is as follows: X — Is automatically selected to be "*Auto*" if the Z axes
	is assigned to a vector-valued test result, or "Time" if Z axes is assigned to a time series test result.
	• Y — You can select either Test Run or Iteration. In the former case, if a test is excluded by application of constraints a gap will appear in the waterfall plot at the Y position corresponding to that test. In the latter case, lines representing the test result displayed on the Z axis are always placed in consecutive Y positions.
	• Z — You can select either a single vector-valued numeric test result or a single time series test result.
Image	Lets you look at individual frames from an image sequence saved during a test iteration. Data must be a supported MATLAB Image format, and must be numeric test results whose size is compatible with an image, namely that:
	• It has three or four dimensions.
	• The third dimension has a length of 1 or 3.

Exploring Plots

This section describes the tools the Test Results Viewer makes available to help you understand its generated plots. It contains the following topics:

- "Plotting Tools" on page 9-17 describes the tools available to help you examine and understand the contents of a generated plot.
- "Viewing Individual Iteration Values" on page 9-17 shows how to focus on specific iteration test results in a plot.
- "Highlighting Values in Your Plot" on page 9-21 shows how to distinguish test results in a plot.

• "Exposing Overlapping Plot Lines" on page 9-25 explains how you can view individual lines in a plot that shows multiple test result values as the same line.

Plotting Tools

The Test Results Viewer integrates the MATLAB Figure Toolbar, which lets you examine and distinguish the test results shown in your plots. See "Plotting Tools—Interactive Plotting" and "Data Exploration Tools" in the MATLAB Graphics documentation for more information.

In addition, the viewer also supports the desktop arrangement tools available in the MATLAB editor. See "Arranging the Desktop — Overview" in the MATLAB documentation.

The Test Results Viewer adds the following features to the MATLAB Figure Toolbar:

- Test run selection Lets you click different test runs in the plot and see the test vector and test results for that iteration in the **Current Iteration** pane. "Viewing Individual Iteration Values" on page 9-17 shows an example of how to use this.
- Lock the plot Prevents constraints from changing the test results displayed in the plot.

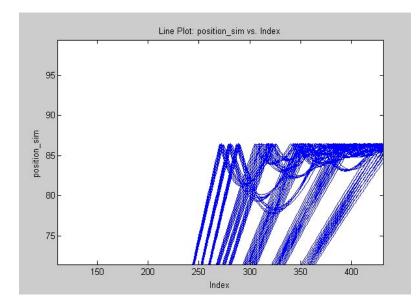
Viewing Individual Iteration Values

Every test iteration has its own representation in a plot unless you screened it out with a constraint ("Refining Your Test Results" on page 9-29 explains constraints). By clicking a line, marker, or surface in a plot with the test run selection tool, you can see the information associated with that test iteration in the **Current Iteration** pane.

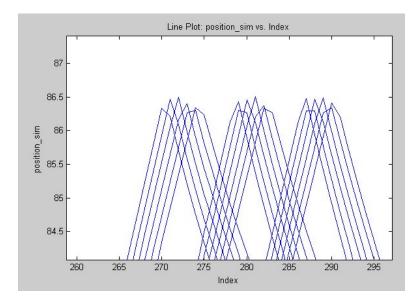
For example, "Generating Plots" on page 9-9 demonstrates how to generate a plot showing all test iteration results of the Throttle demo. You can use the Test Results Viewer plotting tools to zoom in on areas of the plot and determine which iteration was responsible for the result.

1 Click the Zoom In button.

- **2** Move the mouse pointer over an area of the plot you want to investigate further.
- **3** Left-click your mouse or click and drag over the area you want to see. The plot redraws to show this area.



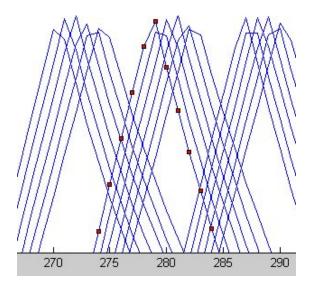
You can repeat zooming in until you have the level of detail you want.



- 4 To turn off the Zoom, click the Zoom In button again.
- **5** Click the **Select an iteration** button in the Figure Toolbar.



6 Click one of the plotted lines in the line plot. The viewer marks the line.



The viewer simultaneously populates the **Current Iteration** pane with information about the values for all test vectors and test results for your selected test iteration. This lets you easily see what test conditions generated a specific result.

Current Iteration 🔹					
Export					
Result	Value				
pass_fail	0				
position	<750x1 double>				
position_limit	25				
position_norm	97.9	-			
Test Vector	Value	\Box			
Damping	5				
Mass	0.2				
Stiffness	15				
l		•			

Highlighting Values in Your Plot

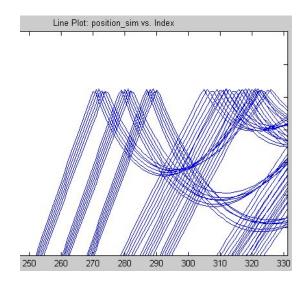
The Test Results Viewer lets you further distinguish your test results for any given plot by letting you control how a plot renders the data on each axis. This is useful in deciphering test results on a plot—especially when the initial plot has a large number of test results closely grouped together. This section explains how you use the **Define Plot** pane to modify the appearance of your plot without modifying the underlying test results. (See "Refining Your Test Results" on page 9-29 for information about modifying the test results used to render a plot.)

The **Define Plot** pane provides four ways to distinguish plotted test results:

- Color
- Markers
- Subplot rows
- Subplot columns

For example, the Throttle demo shows the effect of variations in mass, damping, and stiffness on a component of a Simulink model. The plot you generated in "Generating Plots" on page 9-9 shows test results for of all test iterations, but it is impossible to determine how changes to each test vector affected this outcome. To distinguish the test results on the plot:

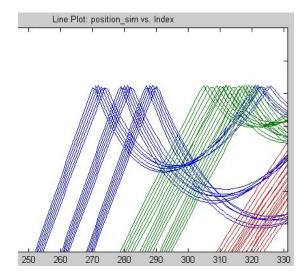
 Zoom in on an area of the line plot so that you can see individual test iterations (as explained in "Viewing Individual Iteration Values" on page 9-17).



2 In the **Define Plot** pane, click **Show > Damping**.

Define Pl	ot: Line Plot 1						ş	×
Plot type:	Line	▼ Valid plo	t of unconstrain	ied data wit	n 90 line(s)			
X Axis:	*Auto*	Show	1	▼ as	subplot rows	-	_	-
Y Axis:	position_sim	I		as				
		and	Damping	as	subplot columns	-	• +	
			Mass Stiffness					
								-
	Multiple Y Data				Copy Setting	IS Ref	resh Pl	iot

- **3** Select **color** from the **as** list.
- **4** Click the **Refresh Plot** button. The plot lines change to show a range of colors.



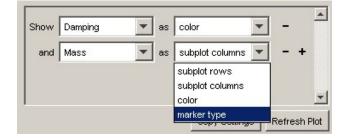
You now have some idea how damping has affected the test results. You have a cluster of blue, green, and red indicating that damping is the same value in each cluster, which you can confirm by using the test selection tool to choose lines and by viewing the value for the Damping test vector in the **Current Iteration** pane.

You can modify the appearance of another set of test vectors to further understand the test results. For example, the menu below **Damping** can be used to distinguish variations in mass with markers.

1 Click the menu next to and.

Show	Damping	•	as	color	•	-		
and		-	as	subplot columns	•] -	+	
	Damping Mass							•
	Stiffness			Copy Setting		Refre		-+

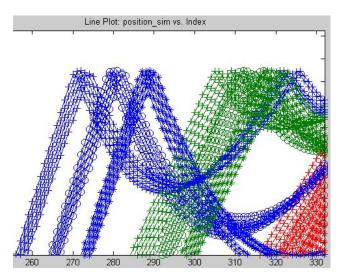
2 Select Mass from the list.



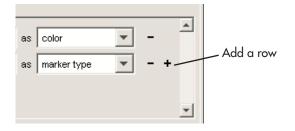
3 Click the menu next to **as** and select **marker type**.

4 Click the Refresh Plot button.

The viewer redraws the plot to show markers distinguishing variations in mass. Notice how each cluster of lines has its own unique color and marker, which shows that variations in damping and mass have a visible effect when you run the model.



You can add two more rows using the **+** button in the **Define Plot** pane to distinguish your test results further.

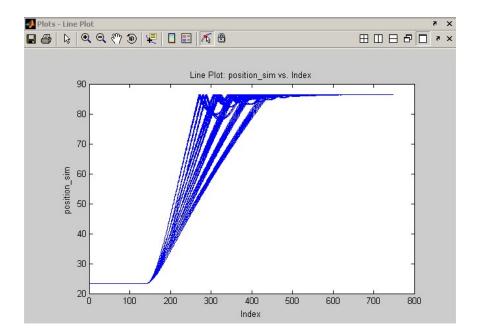


Note These colors and markers do not necessarily show the same value throughout the overall plot. The viewer cycles through all colors and markers in the palette making it possible for different test result values to have the same color or marker.

Exposing Overlapping Plot Lines

It is possible for plot lines and points to overlap and appear undistinguishable. When multiple lines overlap, you can create subplots to distinguish the data points.

For example, if you create a line plot for the Throttle demo with the X-axis set to ***Auto*** and the Y-axis set to **position_sim**, the Test Results Viewer renders a plot with plot lines in close proximity.

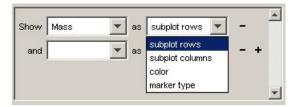


This plot has 90 lines that are too close together to be able to discern clear patterns. You can use the **Define Plot** pane to distinguish plots of test results by placing the generated lines of a test in individual subplots. Each subplot shows the test vector values associated with the test results being plotted. The number of runs per test vector value determines how many subplots you can generate. Using the Throttle demo, you can generate subplots based on changes in damping, mass, or stiffness. For example, what effect did changes in mass have on these test results? To show its effect:

1 In the **Define Plot** pane, select **Show > Mass**.

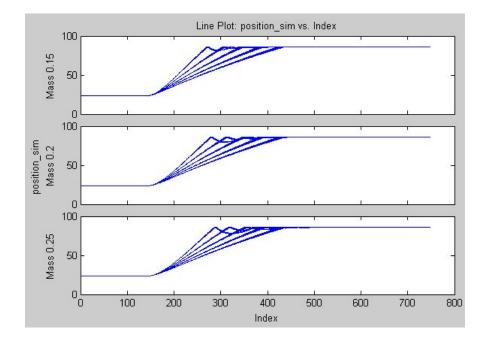
Define Plo	ot: Line Plot 1						8 X
Plot type:	<u> Line</u>	▼ ∨a	alid plot of unconstrair	ned data with !	90 line(s)		
X Axis:	*Auto*		Show	▼ as	subplot rows	<u>न</u> -	
Y Axis:	position_sim	T	show [<u> </u>	
			and Damping	as	subplot columns	<u> </u>	+
			Mass				
			Stiffness				
							-
	Multiple Y Data				Copy Settings	Refresh	n Plot

2 Select subplot rows from the as list.



3 Click the **Refresh Plot** button.

The viewer now shows three subplot diagrams, one for each value of the Mass test vector.



Refining Your Test Results

In this section ...

"Creating and Applying Constraints" on page 9-29

"Plotting Single Iterations" on page 9-36

Creating and Applying Constraints

This section explains how you create and apply constraints to restrict the test results to a subset of test iterations. You also see how to use a constraint to walk through a set of test results.

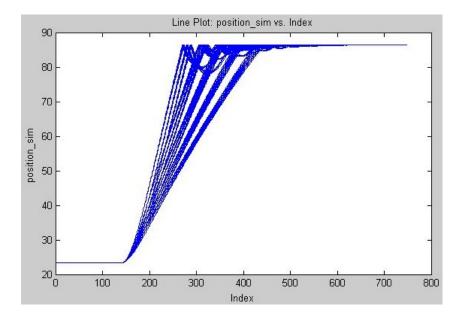
Constraints are a Test Results Viewer mechanism that screen out test result values. Constraints can be a single value, a range, or an evaluated expression. Applied constraints result in plots rendered from a subset of test iterations, and the viewer applies constraints immediately to all plots. This is useful when you want to screen out or filter test results in your attempts to find or understand the results of a test.

Using Default Constraints

The Test Results Viewer, when opened after a test run, has constraints present but not applied. The viewer creates a constraint for each test vector and defines the constraint's range as a function of the full range of values in the test vector. These default constraints let you see the immediate effect of your test's test vectors on the results of the test.

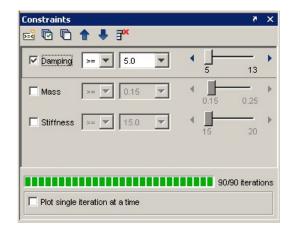
For example, the Throttle demo has three test vectors corresponding to changes in damping, mass, and stiffness to a Simulink model. If you display a line plot as explained in "Generating Plots" on page 9-9, you get a plot similar to the following:

9



This output shows that the test results group in small clusters. You can use a constraint to see which of the test vectors cause this clustering.

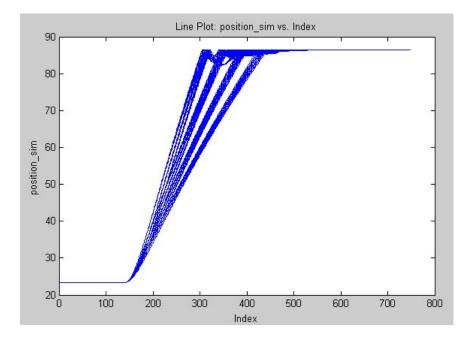
- **1** Return the plot to the previous state by clicking the menu next to **as** and clicking **color**, then click the **Refresh Plot** button.
- 2 In the **Constraints** pane, select the check box next to the **Damping** constraint. The constraint becomes active showing all tests with a Damping greater than or equal to 5.0, which is the lowest value in the range of test vectors. All test results remain in the plot.



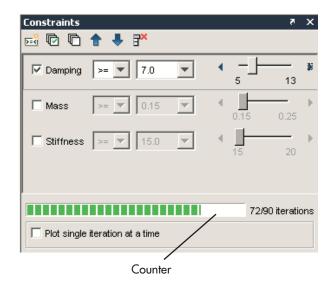
3 Click the right-pointing arrow at the end of the **Damping** constraint's slider.



This advances the constraints slider by one value of the test vector, which causes the first value of the Damping test vector to be removed from the test results used in generating the plot. The viewer immediately applies this constraint to the plot, which, in this case, removes the left-most cluster of test results from the plot. 9



The constraint counter gives another way for you to see whether the constraint affected the test results. In this case, if you set the constraint value to 7, the bar shows that there are only 72 of 90 test iterations visible because of the constraint you just created. Thus these 18 test iterations that are screened out have a Damping test vector value greater than or equal to 7 (see "Creating a Test Vector" on page 1-15 to understand test vector values).



Creating a Constraint

The Test Results Viewer lets you create a custom constraint based on the following:

- A mathematical expression
- Scalar logical test results
- Scalar numeric test results
- String test results that have a value for each test iteration
- Test vectors

You can see an example for creating a constraint based on a mathematical expression in "Viewing Test Results" on page 1-42.

A constraint you might want to create regularly would isolate test results that have passed or failed. This is useful if your test contains a Limit Check element that assigns data to a test variable that you choose to save as a test result. When this test variable is saved, the SystemTest software records the test iteration and whether the test passed or failed (represented by a 1 or 0); you can create a constraint based on these test results. For example:

- 1 If you activated the **Damping** constraint in "Using Default Constraints" on page 9-29, deactivate it now by clearing the check box next to **Damping**, or delete it.
- 2 Click the New Constraint button.



The Add a New Constraint dialog box appears.

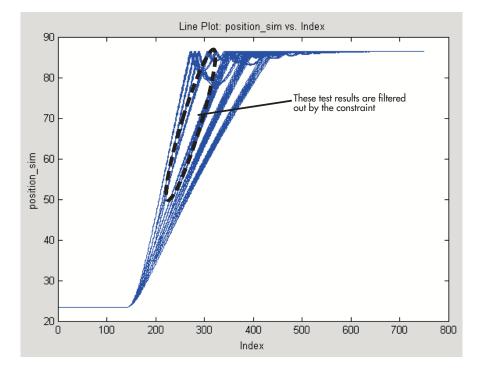
3 Click the list beneath the **Using a result or test vector** field to show the list of test vectors and test results available for basing a constraint on.

🥠 A	dd a New Constraint	×
۲	Using a result or test vector	
	Damping	
~	Damping	
0	Mass	
	Stiffness	
	position_norm	
	position_limit	
	pass_fail	1

- **4** Scroll down and select **pass_fail** in this list. This is the name of the test result that is used to save the Throttle demo's Limit Check element's output.
- **5** Click **OK**. The viewer adds the new constraint to the **Constraints** pane, but it is not active.
- 6 Select the check box next to the **pass_fail** constraint to apply it.

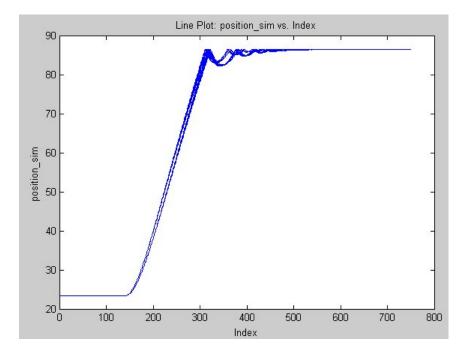


7 Change the operator to ==. The value is already set to 0, representing failed test iterations.



You now have a constraint set to show only those test iterations that failed.

If you change the value of the constraint to 1 using the slider, you will show only those test results that passed the Limit Check element in your test.



Plotting Single Iterations

The constraint option **Plot single iteration at a time** lets you step through and see individual test results within the subset defined by the active constraints. The plot shows only one test iteration until you choose to show the next or previous one. The specific values for that test iteration's test vectors and test results appear in the **Current Iteration** pane. This is useful when you want to know what combination of test vectors allow a test to pass, or what values can lead to failure.

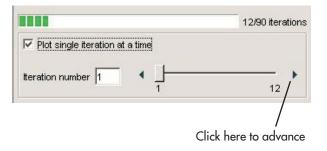
For example, if you follow "Creating a Constraint" on page 9-33, by the end you have created a constraint that shows you all test iterations that have passed. To see each iteration individually:

- 1 Move the slider for the **pass_fail** constraint back to 0.
- **2** Select the **Plot single iteration at a time** check box in the **Constraints** pane.

Mass >= ▼ 0.15 ▼ Stiffness >= ▼ 15.0 ▼	• 0.15 0.25	Þ
Stiffness - V 150 V		
	 ↓ ↓	Þ
🔽 pass_fail 🛛 💻 🔽 0.0 💌	۲ III ا	Þ
	78/90 iterati	ions

The **Constraints** pane changes to show a slider and the currently displayed test iteration.

3 Move the slider or click the advance button to see the next iteration. You see only those test results that match any defined constraints, which, in this case includes only those tests that have passed.



The **Plots** pane updates to show only the plotted line for that iteration.

Viewing Simulink Time Series Data

In this section...

"Overview" on page 9-38

"Creating a Time Series Plot" on page 9-38

Overview

The Test Results Viewer lets you plot test results over time. Simulink can generate time series data when it runs a model, and the SystemTest software can use this data to generate time series plots. Instead of knowing simply that a change in a test vector resulted in a specific test result value, you can now know when during the test that the test vector caused that test result value to be achieved.

This section shows how you plot test results containing time series data. The examples in this section use the model from the Inverted Pendulum demo; if you want to load this model and follow the examples in this section, see "Before You Begin" on page 4-2.

Creating a Time Series Plot

Time series plots require that you have time series data. Your test results will contain time series data because of any of the following:

- Time series data is generated from Simulink Logged Signals and Simulink To Workspace signals.
- The time series data was explicitly created in a MATLAB element and assigned to a test variable that was saved as a test result.
- The viewer created a derived result that represents time series data constructed from Simulink structs (with time data) or log signals. These new derived results have names derived from their original test result name and value.

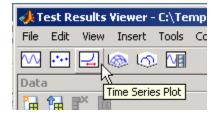
You can verify whether your test generated time series data by reviewing the test results list in the Test Results Viewer's **Data** pane. The viewer labels

time series test results as being of type Simulink.Timeseries (Simulink saves time series data within the workspace in Model Data Logs objects).

▼ Results					
Name 🛆	Value	Туре			
🗕 limit	<1×1 double>	Raw scalar			
🛨 st_time	<201×1 double>	Raw array			
🕂 values	<201×1 double>	Raw array			
🕂 maxvalue	<1×1 double>	Raw scalar			
😰 st_loggedsignal	{1007×1 Simulink.Timeseries}	Object/struct			
Est_outportsignal	{1x1 struct}	Object/struct			
Est_toworkspace	{1x1 struct}	Object/struct			
H LimitRecult	<1×1 doubles	Row coolor			

To create a time series plot:

- 1 Run the test in the SystemTest software.
- 2 Click the Time Series Plot button in the viewer.

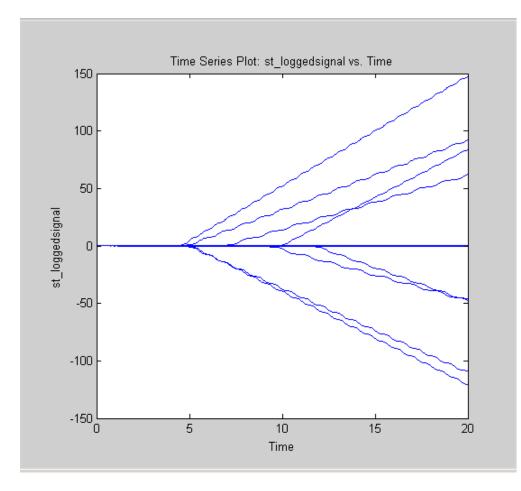


3 In the **Define Plot** pane, click the **Y Axis** menu to show a list of test results with time series data. The **Y Axis** field shows only test results with time series values. The **X Axis** field is always set to **Time** in a time series plot.

Plot type:	🚧 Line	•
X Axis:	Time	
Y Axis:		¥
	st_loggedsignal	
	st_outportsignal_signal1	
	st_toworkspace_systemtestpendulumToWorkspace	

- **4** Click the test result you want to use. For the Inverted Pendulum example, click **st_loggedsignal**.
- **5** Click the **Refresh Plot** button.

The Test Results Viewer generates a time series plot with your selected data.



At this point, you can use the data exploration and refinement tools explained in "Viewing Your Test Results" on page 9-8 and "Refining Your Test Results" on page 9-29 to make more sense of the test results in the plot.

For example, you can use a constraint to step through each individual iteration, by selecting the **Plot single iteration at a time** check box.

Data		X 5	📣 Plots	- Time Se	ries Plot 1				× *
🖬 🖬 💕 🖻			8	₿ 🔍	🔍 🖑 ५	2 🗖 🗉 🗖	5 🗄		-
▼ Results									
Name 🛆	Value	Туре			т	ïme Series P	lot: st_loggedsigna	al vs. Time	
Himit H st_time	<1x1 double> <201x1 double>	Raw scalar 🔺		0.14				1	
Η values	<201×1 double>	Raw array							
maxvalue t_loggedsignal	<1x1 double> {1007x1 Simulink.Timeseries}	Raw scalar Object/struct		0.12					1
E st_outportsignal	{1x1 struct}	Object/struct		0.1 -					
st_toworkspace	{1x1 struct}	Object/struct		0.1					
-				0.08 -	l				-
▼ Test Vectors									
Name ∠ Value → pend <4x1 do	ulden		gnal	0.06					-
Η cart <4x1 do			st_loggedsignal	0.04					_
H distance [0.7,0.7:	2]		660						
1			st l	0.02 -	1				-
▼ Data Statistics: limit		C Refresh							
Statistic	Unconstrained	Constrained		0-	- M.	Walkara			-
Max Min	1			-0.02 -	1	Martin			_
Mean	1				William	NPY .			
Median STD	0			-0.04 -	- 'YMMP'	r.			-
1910	0				auths.				
Constraints		× 5		-0.06		5	10	15	20
	₽×						Time		
🗖 pend 🛛 >= 💌	0.15	0.6	Define P	lot: Time 9	ieries Plot 1				× 5
	0.15	U.6							
🗖 cart 🛛 >= 💌	0.2	0.5	Plot type:	,			 Valid plot of cons 	strained data with 1 line(s)
			X Axis:	Time			Show	as subpl	ㅋ _ ^
T distance >= 💌	0.7	0.72	Y Axis:	st_logg	edsignal		Show		
							and	as subpl	<u>-</u> +
		32/32 iterations							
Plot single iteration	at a time								
									•
Iteration number 1	 ▲ 1 	32		Multiple Y	Data			Copy Settings	Refresh Plot

As this example shows, the time series test result for a single test iteration is composed of many values over time. There are many points with uneven spacing reflecting the actual values of the signal over the time period.

Saving and Reloading Test Results

In this section ...

"Saving Test Results" on page 9-43

"Loading Test Results" on page 9-44

Saving Test Results

You can save the plotting and analysis work done in the Test Results Viewer. Data, constraints, and plots created in the Test Results Viewer can be saved and then reloaded in order to continue working on or viewing the data, or to share it with others.

The following information will be saved:

- The data set created by the SystemTest software during your test run.
- Derived variables you create in the viewer.
- The layout state of the data tables (the order of the columns).
- Any constraints that you set up, and their order.
- Any plots you create, and their layout within the viewer.

Note Since any modifications made in the viewer could potentially be saved, you will see the "file modified" indicator as soon as you do any actions in the viewer, that is, the asterisk denoting a file as modified will be shown in the viewer title bar.

To save your test results and the state of the Test Results Viewer, use the **File > Save Test Results** or **File > Save Test Results** As commands from the Test Results Viewer desktop.

When you use these save commands, a MAT-file is created that contains all of the information listed above.

9

Loading Test Results

There are four ways you can load test results in the Test Results Viewer.

- Load a saved results file from the **File > Load Test Results** menu in the Test Results Viewer desktop.
- Load a saved results file from the MATLAB command line by typing stviewer('matfilename'), where 'matfilename' is the name of the MAT file containing your results.
- Open the Test Results Viewer automatically after a test runs in the SystemTest software. To do this, be sure that the **Visualize and plot** saved results by launching the Test Results Viewer option is selected in the Test Properties pane in the SystemTest desktop before you run the test. After the test executes, the Viewer is opened and the test results you mapped in Saved Results are displayed.
- Open the Test Results Viewer any time after a test runs in the SystemTest software by using the **Tools > Test Results Viewer** menu command or the **Test Results Viewer** toolbar button from the SystemTest desktop. The results of the last test that was executed will be opened in the viewer.

10

Accessing Test Results from the MATLAB Command Line

- "Viewing Test Results at the Command Line" on page 10-2
- "Working with Test Results" on page 10-8
- "Accessing Test Results While a Test is Running" on page 10-15

Viewing Test Results at the Command Line

In this section...

"Introduction" on page 10-2

"Accessing the Results Summary" on page 10-2

"Accessing the dataset Array" on page 10-5

Introduction

After you run a test, the SystemTest software will automatically populate the MATLAB workspace with a variable called stresults. This variable provides access to the test results object, which is useful for comparing the results of separate test runs and for postprocessing test results.

Accessing the Results Summary

You access the results using the stresults variable. To see an example, use the Fault Tolerant Fuel Control System demo.

1 To open the demo in the SystemTest software, type the following at the MATLAB command line:

systemtest demosystest_fuelctrl

- 2 Run the test by clicking the Run button on the SystemTest toolbar.
- **3** To view the results after the test runs, return to MATLAB and type:

stresults

The test results object looks like the following for the Fault Tolerant Fuel Control System demo:

The summary shows the number of iterations that ran, the names of the test vectors included in the test, the saved results you specified in **Save Results**, the dataset array, and generated artifacts.

NumberOfIterations reflects how many iterations actually executed when the test ran. This will match what is reflected in the SystemTest software in the **Main Test** node of the **Test Browser** if all iterations ran. If any iterations stopped or errored out, this will show only the number that did execute.

TestVectorNames is a 1-by-N string cell array containing the test vector names. The values are an alphabetical list of test vector names.

SavedResultNames is a 1-by-N string cell array containing the test result names. The values are an alphabetical list of test result names.

ResultsDataSet is the dataset array storing the test vector and test result values for each iteration. See "Accessing the dataset Array" on page 10-5 for information on accessing the test results data.

Artifacts provides links to SystemTest-generated documents, such as the test report. You can open the report by clicking the link. If your test includes a model coverage report, that would also be included here.

Accessing Properties of the Test Results Object

You can see a complete list of test results object properties before looking at the actual test results data. At the command line, type:

```
get(stresults)
```

In the example using the Fault Tolerant Fuel Control System demo, you see the following properties:

```
>> get(stresults)
    NumberOfIterations: 96
    DerivedResultNames: {}
        ResultsDataSet: [96x10 dataset]
      SavedResultNames: {1x5 cell}
             StartTime: [2007 11 29 10 19 31.2490]
              StopTime: [2007 11 29 10 21 44.9200]
              TestFile: [1x92 char]
       TestVectorNames: {'EGOSensor'
                                       'EngineSpeed'
                                                       'MAPSensor'
                                                                    'SpeedSensor'
                                                                                    [1x14 char] }
             Artifacts: {2x2 cell}
                   Tag: ''
              UserData: []
```

>>

In addition to information that is also included in the summary, this includes derived results names, start time, stop time, tags, and user data.

DerivedResultNames contains values if you created any derived results using the Test Results Viewer. In the previous example there are no derived results, so the value is {}. If there were derived results, this property would contain an alphabetical list of their names.

StartTime provides the time the test was started in the form of a MATLAB clock vector.

StopTime provides the time the test was stopped in the form of a MATLAB clock vector.

TestFile stores the full path and name of the test that generated the test results. If the test has been saved, the value will contain the full path and

name of the test. If the test has not yet been saved, the value will show only the test name.

Tag displays any string you specified using the set function. It is a descriptive string used for labeling purposes. By default, this property is empty.

UserData is a property for storing user data. It is used to store any arbitrary MATLAB data you would like to associate with the test results object. By default, this property is empty.

Accessing the dataset Array

The ResultsDataSet property contains the test results data in the form of a dataset array. This is what you set up using the **Saved Results** node in the **Test Browser**. See "Saving Test Results" on page 1-31 for more information on setting up saved results.

To access the test results data:

- 1 After running a test, use the stresults variable to view the test results object summary, as described in the previous section.
- 2 To access the ResultsDataSet property, type:

stresults.ResultsDataSet

or

```
get(stresults, 'ResultsDataSet')
```

This returns the test results data in the form of a dataset array.

In the Fault Tolerant Fuel Control System demo example, a portion of the test results data looks like this:

>> stresults.ResultsDataSet

ans =

	EGOSensor	EngineSpeed	MAPSensor	SpeedSensor	ThrottleSensor
I1	[1]	[300]	[1]	[1]	[1]
12	[0]	[300]	[1]	[1]	[1]
I3	[1]	[400]	[1]	[1]	[1]
14	[0]	[400]	[1]	[1]	[1]
15	[1]	[500]	[1]	[1]	[1]
I6	[0]	[500]	[1]	[1]	[1]
17	[1]	[600]	[1]	[1]	[1]
18	[0]	[600]	[1]	[1]	[1]
19	[1]	[700]	[1]	[1]	[1]
I10	[0]	[700]	[1]	[1]	[1]

In the dataset array, each row represents a test iteration, labeled using the convention of ['I' + Iteration_Number]. The previous example shows the first 10 iterations. Test vector values are listed first, in alphabetical order, as shown, followed by test results, listed in alphabetical order, as shown in the following figure.

195	[1]	[800]	[0]	[0]	[0]
196	[0]	[800]	[0]	[0]	[0]

	AvgAirFuel	AvgFuelRate	NSensorsActive	SimAFRatio
I1	[14.4466]	[1.3302]	[4]	[4098x1 Simulink.Timeseries]
12	[11.8858]	[1.6251]	[3]	[4098x1 Simulink.Timeseries]
13	[14.4283]	[1.5517]	[4]	[4084x1 Simulink.Timeseries]
14	[11.7511]	[1.9158]	[3]	[4084x1 Simulink.Timeseries]
15	[14.4281]	[1.6298]	[4]	[4067x1 Simulink.Timeseries]
I6	[11.6776]	[2.0261]	[3]	[4067x1 Simulink.Timeseries]
17	[14.4196]	[1.6302]	[4]	[4005x1 Simulink.Timeseries]
18	[11.6281]	[2.0346]	[3]	[4005x1 Simulink.Timeseries]
19	[]	[0.0020]	[4]	[4009x1 Simulink.Timeseries]
I10	[]	[0.0020]	[3]	[4009x1 Simulink.Timeseries]

Notice that this example shows the test vectors list for the last two iterations (I95 and I96), and the beginning of the display of the test result values. There are five results, shown in alphabetical order. The display wraps in MATLAB, so the fifth result is shown after all the iterations for the first four.

In this example, the value for AvgAirFuel is 14.4466 for the first iteration, 11.8858 for the second iteration, etc.

Working with Test Results

In this section ...

"Introduction" on page 10-8

"Managing Test Results Data in its Native Format" on page 10-8

"Managing Test Results as a Dataset Array" on page 10-9

"Plotting Results Data" on page 10-10

Introduction

After accessing test results data in the form of a dataset array, you can work with the data in MATLAB. This feature is useful for comparing the test results data of separate test runs and for postprocessing of test results data.

One advantage to accessing test results data at the command line is that all of the MATLAB plotting tools are available to use on the test results data. You can plot the data using any of the plot types MATLAB offers.

Another major use of the datatset array is to quickly see the results when you use a Limit Check element in your test. You can see whether each iteration passed or failed, and what the value was.

Managing Test Results Data in its Native Format

You can use indexing to extract out data of the dataset in its native format. You can index by string or value.

For example, you can assign a variable to represent the dataset, then access one column of the set using that variable. In the case of the Fault Tolerant Fuel Control System demo this example has been using, it could look like the following.

1 Create a variable to refer to the test results dataset array:

SetA = stresults.ResultsDataSet;

In this example the test results data is assigned to the variable SetA.

2 Specify the desired columns of data by referencing the name of the test result.

```
SetA.AvgFuelRate
```

This indexed into the column called AvgFuelRate.

Note When extracting data in its native format, the test results are always returned as a cell array.

MATLAB displays the contents of that column of data, as shown in this example:

```
>> SetA = stresults.ResultsDataSet;
>> SetA.AvgFuelRate
ans =
    [1.3302]
    [1.6251]
    [1.5517]
    [1.9158]
    [1.6298]
    [2.0261]
    [1.6302]
    [2.0346]
    [0.0020]
    [0.0020]
```

The first 10 iterations are shown in the example.

Managing Test Results as a Dataset Array

You can also choose to manage the test results as a dataset array, refining the data as finely as needed. Suppose you just want to get the average fuel rate for iterations 4 through 8. Use standard MATLAB indexing, as shown in the next example:

The value returned represents the average fuel rate for iterations 4 through 8, in the form of a dataset array.

Plotting Results Data

To demonstrate plotting results, you can use another demo called Simple Demo.

1 Open the demo in the SystemTest software by typing the following at the MATLAB command line:

systemtest simple_demo

- 2 Run the test by clicking the Run button on the SystemTest toolbar.
- **3** View the results summary using stresults at the command line.

```
>> systemtest simple_demo
>> stresults
stresults =
   Test Results Object Summary for 'Simple_Demo':
        NumberOfIterations: 60
        TestVectorNames: signal
        SavedResultNames: HiLimit, LowLimit, Y
        ResultsDataSet: [60x4 dataset]
   Artifacts associated with this test result object:
        <u>TEST-File (Simple_Demo.test)
        Test Report (Simple_Demo report.html)
   }
}
>> stresults
>> stresults
>> stresultsDataSet: [60x4 dataset]
</u>
```

You can see that this test has one test vector for a signal, called signal, and three saved results. The result for Y is the signal's value for a given test run.

4 Look at the test results dataset by typing the following:

stresults.ResultsDataSet

The first 10 iterations are shown here:

>> stresults.ResultsDataSet

ans =

	signal	HiLimit	LowLimit	Y
I1	[0.2094]	[1]	[-1]	[0.5226]
12	[0.4189]	[1]	[-1]	[0.8125]
I3	[0.6283]	[1]	[-1]	[0.2148]
I4	[0.8378]	[1]	[-1]	[1.1565]
15	[1.0472]	[1]	[-1]	[0.9984]
I6	[1.2566]	[1]	[-1]	[0.5486]
17	[1.4661]	[1]	[-1]	[0.7730]
18	[1.6755]	[1]	[-1]	[1.0414]
19	[1.8850]	[1]	[-1]	[1.4086]
I10	[2.0944]	[1]	[-1]	[1.3309]

You can see the test vector signal followed by the three results, including the one of interest in this example, Y.

5 Create a variable called SetB for the results dataset for ease of use in working with the data.

SetB = stresults.ResultsDataSet;

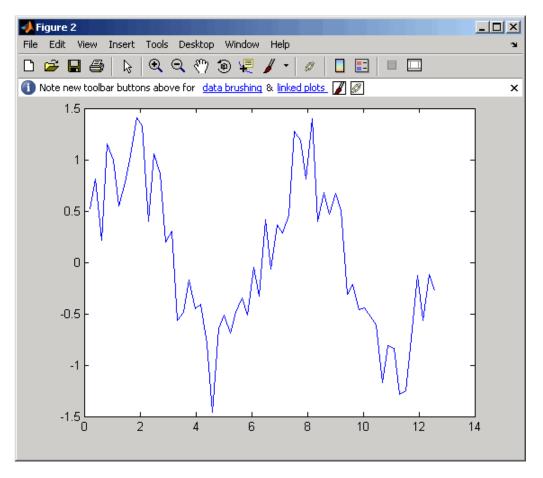
6 Create variables for the signal (the test vector) and the Y test result.

```
signalA = SetB.signal;
VarA = SetB.Y;
```

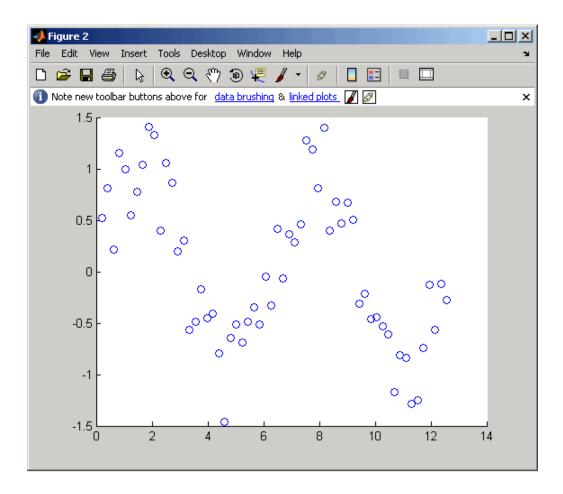
7 Plot the signal. Because Y represents the current value of the signal for each iteration of the test, plotting the signal against Y shows the values of the signal throughout the test.

```
plot([signalA{:}], [VarA{:}])
```

The plot command produces a line plot, as shown here. You can use any type of plot that MATLAB offers.



To use another plot type, such as a scatter plot, replace the plot command. scatter([signalA{:}], [VarA{:}])



Accessing Test Results While a Test is Running

While a test is executing in the SystemTest software, you can access test results using the systest.testresults.getCurrent method.

The getCurrent function is intended to be used in a MATLAB element within the Pre Test, Main Test, or Post Test sections of a TEST-File, in order to access test information or test results during test execution.

This is a function of the systest.testresults class, which is the class definition for a test results object, allowing you to access test results from MATLAB.

The following example used in a MATLAB element will allow you to access the test results object while the test is executing. The ResultsDataSet property can be queried in order to access the underlying test data that is currently available.

```
obj = systest.testresults.getCurrent;
currentResults = obj.ResultsDataSet;
```



Function Reference

addArtifact

Purpose	Add artifact to test results object
Syntax	addArtifact(obj, name, filepath)
Description	addArtifact(obj, name, filepath) adds an artifact to the test results object obj using the string name, representing a user-customizable display name, and the string filepath, representing the full file path to the artifact.
	This function is a convenience for adding additional artifacts to the Artifacts property of the test results object obj.
	Artifacts can be any document or report associated with a test results object. By associating artifacts with a test results object, hyperlinks are automatically provided to access the artifacts when the test results object is displayed at the MATLAB command line.
	This is function of the systest.testresults class, which is the class definition for a test results object, allowing you to access test results from MATLAB. For more information on the test results object, see Chapter 10, "Accessing Test Results from the MATLAB Command Line".
How To	 Chapter 10, "Accessing Test Results from the MATLAB Command Line"

Purpose	Access test results object from SystemTest TEST-File
Syntax	obj = systest.testresults.getCurrent
Description	<pre>obj = systest.testresults.getCurrent returns obj, the test results object associated with the currently running SystemTest test file.</pre>
	If no TEST-File is currently executing, obj is returned as [].
	The getCurrent function is intended to be used in a MATLAB element within the Pre Test, Main Test, or Post Test sections of a TEST-File, in order to access test information or test results during test execution.
	This is function of the systest.testresults class, which is the class definition for a test results object, allowing you to access test results from MATLAB. For more information on the test results object, see Chapter 10, "Accessing Test Results from the MATLAB Command Line".
Examples	The following code example used in a MATLAB element will allow you to access the test results object while the test is executing. The ResultsDataSet property can be queried in order to access the underlying test data that is currently available.
	obj = systest.testresults.getCurrent; currentResults = obj.ResultsDataSet;
How To	• Chapter 10, "Accessing Test Results from the MATLAB Command Line"

strun

Durness				
Purpose	Run series of SystemTest test files			
Syntax	<pre>strun(testfile)</pre>			
Description	strun (<i>testfile</i>) runs the SystemTest test file specified by the string <i>testfile</i> . You can specify <i>testfile</i> as the name of a test file, or as the full path to a test file. If a test file name is specified without a full path, the test file must reside on the MATLAB path.			
	<i>testfile</i> may also be specified as a 1-by-N or N-by-1 cell array of test files, each of which is run serially.			
	Running tests that you set up in the SystemTest software from the MATLAB command line using strun is useful for running multiple test files as a batch or calling a test file as part of an M-file.			
	strun will run in a synchronous manner, that is, the MATLAB command line will be blocked until strun finishes executing. strun will finish executing when either of the following conditions is met:			
	• All test files have finished executing.			
	• A Ctrl+C is issued.			
	When a test is run, it is executed using the settings specified in the test file. The only exception is the option to launch the Test Results Viewer. If this option is enabled, it will be ignored.			
	If only one test file is specified, and the test encounters an execution error, strun will error. If multiple test files have been specified, a warning will be issued for any test execution errors, and the remaining test files will be run.			
	Note that it is recommend that you run the test from the SystemTest desktop to verify that elements are not in an error state, and the test will run successfully, before running it via the MATLAB command line using this function.			

	Note that MATLAB will remain busy while tests are executing via the strun command. Control is returned to the MATLAB command line once all tests execute.
Examples	Run a test called mytest that is on the MATLAB path.
	<pre>strun('mytest')</pre>
	Run a test called mytest that is not on the MATLAB path, but is in a local directory called c:\work.
	<pre>strun('c:\work\mytest.test')</pre>
	Run two tests, called mytest and mytest2, that are both on the MATLAB path.
	<pre>strun({'mytest' 'mytest2'})</pre>
	Run three tests, two of which are on the MATLAB path, and one of which is not.
	<pre>strun({'mytest' 'c:\work\mytest2.test' 'mytest3'})</pre>
How To	• "Running Tests from the MATLAB Command Line" on page 1-10

stviewer

Purpose	Open Test Results Viewer
Syntax	<pre>stviewer(filename)</pre>
Description	<pre>stviewer(filename) opens the Test Results Viewer using the test results saved in the MAT-file specified by the string filename. filename must specify a MAT-file created by a SystemTest test.</pre>
	Note that this function opens the Test Results Viewer directly from MATLAB. The most common use case is to open the Test Results Viewer from the SystemTest software at any time to see the results of the last executed test, or automatically after a test runs that contains test results.
	For more information about the Test Results Viewer, see Chapter 9, "Using the Test Results Viewer".
How To	• Chapter 9, "Using the Test Results Viewer"

Purpose	Open SystemTest desktop
Syntax	systemtest systemtest(<i>testfile</i>)
Description	systemtest opens the SystemTest desktop with a new untitled test.
	<pre>systemtest(testfile) opens testfile in the SystemTest desktop, where testfile is a SystemTest test file (.test) available on the MATLAB path or specified with a full path.</pre>
Examples	Open a test called mytest that is on the MATLAB path.
	<pre>systemtest('mytest')</pre>
	Open a test called mytest that is not on the MATLAB path, but is in a local directory called c:\work.
	<pre>systemtest('c:\work\mytest.test')</pre>

systemtest

A

SystemTest Hot Keys

The following keyboard shortcuts are available in the SystemTest software.

Кеу	Description
Alt+N	Activates the New button to create a new test vector or test variable.
F1	Opens Help.
F5	Runs a test.
Ctrl+C	While a test is running, stops the test.
Ctrl+C	When a test is not running, copies selection in some parts of the user interface.
Ctrl+N	Adds a new untitled test.
Ctrl+O	Opens a test.
Ctrl+Q	Closes the SystemTest software.
Ctrl+S	Saves a test.
Ctrl+V	Pastes the copied selection.
Ctrl+W	Closes a test.
Ctrl+X	Cuts a selection in some parts of the user interface.
Ctrl+Y	Performs redo of last undo action.
Ctrl+Z	Performs undo of last action.
Ctrl+0	Gives focus to the Test Browser .
Ctrl+1	Gives focus to the Properties pane.

Кеу	Description
Ctrl+2	Gives focus to the Test Vectors pane.
Ctrl+3	Gives focus to the Test Variables pane.
Ctrl+4	Gives focus to the Resources pane.
Ctrl+5	Gives focus to the Run Status pane.
Ctrl+6	Gives focus to the Desktop Help pane.
Ctrl+7	Gives focus to the Elements pane.
Ctrl+8	Gives focus to the Getting Started pane.
Ctrl+Shift+0	Gives focus to the Plots pane.
Ctrl+Shift+U	Undocks the currently selected pane.
Ctrl+Shift+D	Docks the currently selected pane.

The dataset Array

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- "Dataset Array Operations" on page B-5

Dataset Arrays

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"Looking at Data" on page B-3

Overview

When you run a test, you can view your test results data as a dataset array in MATLAB. This appendix contains general information on the dataset array that is the format used for test results that can be accessed in MATLAB. See Chapter 10, "Accessing Test Results from the MATLAB Command Line" for information on using the command-line test results.

Dataset arrays are used to collect heterogeneous data and metadata including into a single container variable. Dataset arrays can be viewed as tables of values, with rows representing different observations and columns representing different measured variables. Dataset arrays can accommodate variables of different types, sizes, units, etc.

Note In the SystemTest software, each observation (i.e., row) is used to represent a test iteration, while each measured variable (i.e., column) represents a test vector or test result value.

Dataset arrays combine the organizational advantages of basic MATLAB data types while addressing their shortcomings with respect to storing complex heterogeneous data.

Dataset arrays have a family of functions for assembling, accessing, manipulating, and processing the collected data. Basic array operations parallel those for numerical, cell, and structure arrays.

Test Results Data

MATLAB data containers (variables) are suitable for completely homogeneous data (numeric, character, and logical arrays) and for completely heterogeneous data (cell and structure arrays). Test results data, however, are often a mixture of homogeneous variables of heterogeneous types and sizes. Dataset arrays are suitable containers for this kind of data.

Dataset arrays can be viewed as tables of values, with rows representing different test iterations or cases and columns representing different test vector and test result values. Basic methods for creating and manipulating dataset arrays parallel the syntax of corresponding methods for numerical arrays. Because of the potentially heterogeneous nature of the data, dataset arrays have indexing methods with syntax that parallels corresponding methods for cell and structure arrays.

Looking at Data

Dataset arrays in MATLAB are variables created with the dataset function, and then manipulated with associated functions. In the case of the SystemTest software, when a test is run, a dataset array is created and stored as part of a test results object. The test results object is assigned to a variable named stresults in the MATLAB workspace when the test stops running. See Chapter 10, "Accessing Test Results from the MATLAB Command Line" for information on using stresults.

The following table lists the accessible properties of dataset arrays. Properties can be configured using the set function, or accessed using the get function.

Dataset Property	Value
Description	A string describing the data set. The default is an empty string.
Units	A cell array of strings giving the units of the variables in the data set. The number of strings must equal the number of variables. Strings may be empty. The default is an empty cell array.

Dataset Property	Value
DimNames	A cell array of two strings giving the names of the rows and columns, respectively, of the data set. The default is {'Observations' 'Variables'}.
UserData	Any variable containing additional information to be associated with the data set. The default is an empty array.
ObsNames	A cell array of nonempty, distinct strings giving the names of the observations in the data set. The number of strings must equal the number of observations. The default is an empty cell array.
VarNames	A cell array of nonempty, distinct strings giving the names of the variables in the data set. The number of strings must equal the number of variables. The default is the cell array of string names for the variables used to create the data set.

Functions associated with dataset arrays are used to display, summarize, convert, concatenate, and access the collected data. Examples include disp, summary, double, horzcat, and get, respectively. Many of these functions are invoked using operations analogous to those for numerical arrays, and do not need to be called directly. (For example, horzcat is invoked by [].) Other functions access the collected data and must be called directly (for example, replacedata).

Dataset arrays are implemented as MATLAB *objects*; the associated functions are their *methods*. It isn't necessary to understand objects and methods to make use of dataset arrays—in fact, dataset arrays are designed to behave as much as possible like other, familiar MATLAB arrays.

Dataset Array Operations

This table lists available methods for dataset arrays. Many of the methods are invoked by familiar MATLAB operators and do not need to be called directly. For full descriptions of individual methods, type

help	dataset/ <i>methodname</i>
------	----------------------------

Dataset Method	Description
cat	Concatenate dataset arrays. The horzcat and vertcat methods implement special cases.
dataset	Create dataset array.
datasetfun	Apply function to each variable of dataset array.
disp	Display dataset array, without printing data set name.
display	Display dataset array, printing data set name. This method is invoked when the name of a dataset array is entered at the command prompt.
double	Convert dataset variables to double array.
end	Last index in indexing expression for dataset array.
get	Get dataset array property.
horzcat	Horizontal concatenation for dataset arrays (add variables). This method is invoked by square brackets.
isempty	True for empty dataset array.
join	Merge observations from two dataset arrays.
length	Length of dataset array.
ndims	Number of dimensions of dataset array.
numel	Number of elements in dataset array.
replacedata	Convert array to dataset variables.
set	Set dataset array property value.
single	Convert dataset variables to single array.
size	Size of dataset array.

Dataset Method	Description
sortrows	Sort rows of dataset array.
subsasgn	Subscripted assignment for dataset array. This method is invoked by the parenthesis, dot, and curly brace indexing.
subsref	Subscripted reference for dataset array. This method is invoked by the parenthesis, dot, and curly brace indexing.
summary	Print summary statistics for dataset array.
unique	Unique observations in dataset.
vertcat	Vertical concatenation for dataset arrays (add observations). This method is invoked by square brackets.

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